4D-A043256

ALEX(01)-TR-76-09

DESIGN, SIMULATED OPERATION, AND EVALUATION OF A SHORT-PERIOD SEISMIC
DISCRIMINATION PROCESSOR IN THE CONTEXT OF A WORLD-WIDE
SEISMIC SURVEILLANCE SYSTEM



TECHNICAL REPORT NO. 9

VELA NETWORK EVALUATION AND AUTOMATIC PROCESSING RESEARCH

Prepared by Robert L. Sax

TEXAS INSTRUMENTS INCORPORATED

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Dallas, Texas 75222

Prepared for

AIR FORCE TECHNICAL APPLICATIONS CENTER Alexandria, Virginia 22314

Sponsored by

ADVANCED RESEARCH PROJECTS AGENCY Nuclear Monitoring Research Office ARPA Program Code No. 6F10 ARPA Order No. 2551



29 October 1976

Acknowledgment: This research was supported by the Advanced Research Projects Agency, Nuclear Monitoring Research Office, under Project VELA-UNIFORM, and accomplished under the technical direction of the Air Force Technical Applications Center under Contract Number F08606-76-C-0011.



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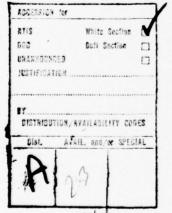
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SECURITY CLASSIFICATION OF THIS PAGE (When Date Entered)

REPORT DOCUMENTATION PAGE	READ INSTRUCTIONS BEFORE COMPLETING FORM
1. R T NUMBER 2. GOVT ACCESSION NO.	3. RECIPIENT'S CATALOG NUMBER
4. TITLE DESIGN, SIMULATED OPERATION, AND EVALUATION OF A SHORT-PERIOD SEISMIC DIS-	
CRIMINATION PROCESSOR IN THE CONTEXT OF A WORLD-WIDE SEISMIC SURVEILLANCE SYSTE	M ALEX(01)-TR-76-09
Robert L. Sax	F08606-76-C-0011
9. PERFORMING ORGANIZATION NAME AND ADDRESS Texas Instruments Incorporated	10. PROGRAM ELEMENT, PROJECT, TASK AREA & WORK UNIT NUMBERS
Equipment Group Dallas, Texas 75222	VELA T/6705/B/ETR
11. CONTROLLING OFFICE NAME AND ADDRESS Advanced Research Projects Agency	12. REPORT DATE 29 October 1976
Nuclear Monitoring Research Office Arlington, Virginia 22209	13. NUMBER OF PAGES 161
14. MONITORING AGENCY NAME & ADDRESS(II different from Controlling Office) Air Force Technical Applications Center VELA Seismological Center	UNCLASSIFIED
Alexandria, Virginia 22314	15a. DECLASSIFICATION/DOWNGRADING SCHEDULE

16. DISTRIBUTION STATEMENT (of this Report)

APPROVED FOR PUBLIC RELEASE, DISTRIBUTION UNLIMITED

17. DISTRIBUTION STATEMENT (of the abstract entered in Block 20, if different from Report)

18. SUPPLEMENTARY NOTES

ARPA Order No. 2551

19. KEY WORDS (Continue on reverse side if necessary and identify by block number)

Seismic Surveillance System Interactive Seismic Data Processing

System Design Automatic Seismic Processing

Earthquakes Seismic Data Preparation
Explosions Seismic Event Processing

Seismic Discriminants Algorithms
ABSTRACT (Continue on reverse side if necessary and identity by block number)

A brief summary of a series of system studies describes the data flow, file structures, and data processing required to operate a world-wide seismic surveillance network. One of the design problems in developing a surveillance mode of operation is to provide the seismic analyst-computer interaction needed to efficiently perform discrimination processing to effectively classify events as earthquakes or explosions. Efficiency is required to keep up with

DD 1 JAN 73 1473

EDITION OF 1 NOV 65 IS OBSOLETE

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the daily load of events which must be subjected to classification processing. Flexibility in altering operating procedures will be needed until our discrimination capability is sufficiently developed to identify explosions originating from any region which is possibly accessible to nuclear explosions.

To partially fulfill these requirements, a special purpose Interactive Seismic Processing Module was developed on a PDP-15 minicomputer for Short-Period Earthquake/Explosion Discrimination (SPEED). This processing module was imbedded in a simulated special purpose seismic operating system, Interactive Seismic Processing System (ISPS) developed by Ringdal and Shaub. All of the capabilities for waveform processing using SPEED were described and demonstrated by processing a seismic event and displaying the results of each stage of processing. Support programs were developed to use an IBM 360/44 computer to reduce all of the station component seismograms to a single representative event waveform. An option is provided for inputting into SPEED the single representative event waveform either corrected for or uncorrected for system response. The examples analyzed were corrected to broadband ground displacement between 0.25 and 5.0 Hz.

The SPEED processing module as presently configured can be programmed to perform any one of many discrimination procedures by a prescribed sequence of button pushing. To obtain baseline performance data, one very simple and reproducible discrimination processing procedure was prescribed. A data base of 35 events, including 20 earthquakes and 15 presumed explosions in the magnitude range between 4.4 and 6.1, were run through the SPEED processor. For each event, the discrimination measurements obtained from SPEED were processed by multivariate discrimination analysis of frequency dependent magnitude measurements to derive a twocomponent discriminant output. One component was optimized to discriminate central Asian presumed explosions. The other component was optimized to discriminate western United States presumed explosions. The performance results obtained by analyzing the length of the two-component discriminant vectors were to clearly separate earthquakes from presumed explosion events from the two regions. Assuming normal statistics, it is expected that 90 percent of the presumed explosions can be detected with a probability of false positive identification of 4 x 10⁻³. Two outliers were obtained; one from each presumed explosion region. This indicates the need for more discriminant components in the measured discriminant vector, and possibly more components in the resultant discriminant space needed to identify all explosions by region or medium type. Before considering use of some of the more advanced capabilities of SPEED, significant improvements over these baseline results should be firmly established.

ABSTRACT

A brief summary of a series of system studies describes the data flow, file structures, and data processing required to operate a world-wide seismic surveillance network. One of the design problems in developing a surveillance mode of operation is to provide the seismic analyst-computer interaction needed to efficiently perform discrimination processing to effectively classify events as earthquakes or explosions. Efficiency is required to keep up with the daily load of events which must be subjected to classification processing. Flexibility in altering operating procedures will be needed until our discrimination capability is sufficiently developed to identify explosions originating from any region which is possibly accessible to nuclear explosions.

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ACKNOWLEDGMENTS

I gratefully adknowledge J. S. Shaub for his association in planning the implementation of the Interactive Process Module, SPEED, and its imbedding into the higher level Interactive Seismic Processing System (ISPS) developed by F. Ringdal and J. S. Shaub. I received considerable systems programming support from D. A. Eastburn, who performed most of the implementation of SPEED on the PDP-15 computer at the Seismic Data Analysis Center. Suggestions for improvement, made by J. R. Filson (absorption correction) and R. W. Alewine (band-limited echo) and others, are currently being implemented by D. R. Lashmit. Support data preparation programs were programmed by R. L. Whitelaw. The least squares multivariate discrimination analysis described in this report was programmed by A. W. Schmidt.

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SECTION I OVERVIEW

A. INTRODUCTION

Over the past several years Texas Instruments Incorporated has performed a series of system studies. The first of these defined the surveillance problem and the functions required to perform it. From this it was possible to describe facilities, data flow, file structures, and hardware or software requirements for seismic data processing and communications processing.

A report was written to analyze the most feasible means of utilizing past measurements of seismic events and seismic noise. Past history of the seismic noise and seismic event measurements can be used to improve the front end detection of seismic events and to improve the quality of seismic event waveform estimates, given the location of a newly detected event. Another feasibility report was written to evaluate where automatic data processing can be most effectively used. Possible areas of application are for front-end seismic event detectors, detection association processors, and event waveform retrieval processors. Also considered were the seismic analyst interpretation tasks which need to be supported by interactive graphics processing. This type of information processing was used for waveform alignment, later phase picking, recursive event focal parameter estimates, reduction of many event waveforms to one or several to be used for discrimination processing, and earthquake and explosion discrimination processing.

This report and several preceding reports are part of the present phase of system design studies to develop and evaluate the computer

codes needed to perform surveillance functions. To facilitate rapid development, these are performed in a mode which simulates surveillance mode operation. Interactive graphics programs were developed to perform longperiod and short-period seismic event analysis. Automatic programs were developed and tested to perform detection association processing and waveform retrieval.

B. SYSTEMS ANALYSIS OF A WORLD-WIDE SURVEILLANCE ENVIRONMENT

This report continues the series of system studies by Texas Instruments Incorporated to develop feasible and economically viable options of implementing a seismic earthquake and explosion surveillance system. The first of the reports by Sax et al. (1974) scoped the problem of defining and parameterizing a system capable of monitoring world-wide occurrences of earthquakes and explosions. One of the parameters scoped was sensor deployment, ranging from a network of single sensor stations to a network of array stations. Another parameter was the data collection mode. At one extreme, a centralized system forwards all raw seismic data to a central facility. There, the seismic events are detected, classified and documented. At the opposite extreme, to accomplish the same mission a decentralized system forwards only selected data and information. In that case data processing for event detection and waveform retrieval is partitioned between computer processing at remote sites and computer processing at the central facility.

The 1974 system study report was written to provide systems analysis for implementing and operating a seismic surveillance system. The report specified definition of data processing functions, definition of files, allocation of storage, control of access to data and information files by automatic processors or analyst-driven function processors, communications,

and communications control functions. Given this level of function requirement definition, it was possible to specify preliminary designs of facilities, hardware and software modules needed to perform required functions, and of interfaces needed to synchronize performance of the function processes. The function processes were designed to transform on-line files of raw seismic data to event associated data and information. The function processes and file structures were defined with sufficient generality to accommodate ground motion measurements either by a single component sensor, multiple component sensor, multiple sensors distributed as array elements, or complexes of arrays. This generality of software and file structure enables the system to adapt to changes in sensor deployment. For example, single sensor stations could be converted to array stations without interruption or serious adverse effects on the performance of seismic surveillance.

If the seismic surveillance system is designed to be implemented and operated as an integrated system, the managers of the network could alter the size of arrays or could add or subtract remote stations to meet almost any future anticipated requirement for seismic event detection capability. Top down planning of the design for this kind of flexibility requires in advance detailed quantitative specification of all data processing functions; of the content and size of storage files; of the control needed for sequential access to data files by parallel operating function processes; of the communications capacity requirements; of the system reliability and recovery requirements; and the limit of time delay tolerance allowable before a final seismic event classification is obtained.

One important system design decision is to select either a centralized or decentralized mode of seismic data collection. Given the present state of the art, either type of data collection can meet any reasonable anticipated requirements for the system monitoring world-wide occurrences of earthquakes and explosions. The main impact of this decision is

on the size and capabilities of remote and central facilities to hold, process, and forward data. The decision should therefore be made before firming the design of such facilities. A decentralized data collection system utilizes station disk files and remote station processors to send reduced data and information to a central facility. A centralized system utilizes much simpler direct sensor to satellite data collection links to send all sensor data to a central facility. In both cases it is anticipated that each remote station's raw seismic data will be held for at least six to eight hours pending the data retrieval needed to analyze each seismic event. These event data retrievals are driven by automatic and independently activated station threshold detections. The detections, sent asynchronously as bulletins from the remote stations to a central facility are linked by an automatic station detection association processor to specific seismic events focal parameters, e.g., origin time, location, and depth of earthquake. The detection association processor utilizes detection bulletin information to obtain the location and origin time of the event. It must do this to predict event arrival times at all remote stations. The predicted arrival times should be accurate to within the order of ten to twenty seconds, to assure confident retrieval of two-minute signal centered short-period seismic event waveforms as well as the one-half hour long-period waveforms.

One advantage of a decentralized over centralized data collection is the estimated 15 to 20% lower cost of implementation and 10-year operation. Another advantage is the capability for more responsive computer assisted quality control of sensor operation at remote sites. The quality control, e.g., detection and repair of bad sensors, can be more readily performed by staff personnel with equipment available at the remote station processor facilities.

One advantage of centralized data collection is simultaneous world-wide access to all of the raw sensor data. Because of this access and

the lack of communication delays, higher false alarm waveform retrievals can be tolerated. These would be caused by detectors operated at lower thresholds. This could result in some increased network event detection capability. It is also possible that hardware and software economies of scale can be built into performing all of the station level detection and waveform retrieval by means of simultaneously parallel station detection processing. Recoverability from system overloading, due to abnormal event occurrences such as earthquake swarms, is faster and more certain because of simultaneous access to all of the raw seismic data files. These can be temporarily dumped onto and retrieved from backup tape or disk units. If a satellite data collection system is built, it is expected that considerable excess satellite data communications capacity would be available for use by other agencies on a when-available basis. For example, lower data rate missions, such as collecting earthquake prediction data, can utilize the excess capacity of the satellite seismic data collection system to forward measurements to a central facility. By so sharing the cost of the data collection system, there could result a considerable communications cost savings for participating agencies. A disadvantage of a centralized data collection system is the longer and more critical development path with more technological risks.

However the decision is made between centralized and decentralized data collection, design studies of algorithms required to perform surveillance system's functions can presently be performed. This can be done in a simulation mode prior to finalizing their design. By iterative design and testing, certain critical functions such as detection association processors, event classification processors, and station detection processors can be specified in minute detail. To the extent that detailed specification of function processors are realistic, the code required to perform the functions can be developed free of faults. Finally, top down design of an integrated surveillance system, i.e., facilities, hardware, and software, is feasible after achieving such a level of problem definition.

C. FEASIBILITY ANALYSIS OF PARAMETER UPDATE PROCESSING

To optimize the operation of a network of event detectors, thresholds can be controlled to obtain the highest possible detection capability in areas of surveillance interest. For a network of array stations, performance optimization also involves improving event estimation by correcting for consistent bias in beamforming parameters, i.e., for anomalous transmission time delays, and for anomalous transmission amplitude attenuation factors.

The performance of the network for acquisition of seismic event waveforms depends on the operating characteristics of the station detectors. These flag possible arrivals of events by means of bulletins. Given these bulletins, a detection association processor times and locates the seismic events. At the station level, sensor data is registered and held on disk pending the request of event waveform data. A front end detection process is performed on the newly registered data. The detector searches for indications of new events by detecting large amplitudes on single sensors or on waveform estimates derived from array sensors. The start time of large amplitude excursions provides a first estimate of the event arrival time. To estimate possible event arrivals on arrays, a set of targeted locations are scanned for events originating from the vicinity of one of the targeted locations. Thus array detections yield not only event arrival times but also associated location ellipses. In that case, any point within a large elliptical area centered about the targeted location is a possible location of the detected event. Since large amplitude excursions can occasionally result from ambient seismic noise, thresholds are set high enough to eliminate most large amplitude excursions due to noise. But this is done at the cost of missing smaller events. Each level that a threshold can be set can be characterized by a rate of false alarms due to noise as well as by the probability of missing an event of some specified magnitude and distance. Each threshold level of

a station detector implies a point on the curve of false alarm rate versus probability of missing the targeted signal. This curve is the operating characteristic of the front end detector. It is important to use thresholds to limit the expected number of false alarm bulletins. At the network level, arrival times at four or more stations are needed to time and locate events. This focal estimate is used to drive requests for event waveforms. This sampled event data is obtained from the raw seismic data held at each station. The false alarm bulletins can interfere with this process. By controlling the average rate of false alarms from all of the stations, the network level timing and location of events by detection association processing can be optimized.

Unger (1974) analyzed the methodology of optimizing threshold settings to improve the detectability of events by a network of sensors. This was done by setting up a cost function to assess the cost in network performance of detecting false alarms and of missing signals. The optimum threshold setting at a station is that setting which minimizes the total cost of both types of detection errors. In general, the false alarm rate of these minimum cost threshold settings will not be the same at every station. For example, one means of implementing the minimum cost threshold strategy is to set up target locations in areas of surveillance interest. In that case, the false alarm rate of the optimum threshold settings will depend on the following parameters: the location of targeted regions, the minimum desired magnitude event to be detected from each region, and the maximum number of false alarms that can be tolerated to avoid missing events from the region. Simulation of network operations should allow these network level threshold control parameters to be set at values which optimize the performance of the detection association processor in detecting seismic events from each region. The detection bulletins would be coded to indicate each conditional region location implied by the threshold. An obvious result of the strategy of making thresholds conditional to event location is that thresholds will be set high enough to prevent needlessly high false alarm rates due to local events. This follows from the extremely

high likelihood of detecting the targeted event. Thresholds will also be set very high on far out noisy stations due to their very low likelihood of detection. Preliminary analysis of a minimum cost threshold strategy compared to operating thresholds at a constant false alarm rate indicated that the minimum cost mode operating at the same average false alarm rate can gain 0.3 units of magnitude detection capability.

The operating characteristics of station level array detectors depend not only on threshold control but also on the signal-to-noise (S/N) ratio of events estimated by beamforming. The S/N ratio of beams depends on accurate time alignment, the relative effect of transmission attenuation on each sensor, and the relative noise level of each sensor. The same noise information used to control thresholds could be used to estimate sensor noise. The information needed to estimate the amplitude attenuation and time delays depends strongly on the location and depth of the event within the targeted region. By analyzing past events from each targeted region, systematic corrections of plane wave models for the transmission effects (e.g., amplitudes, velocity, direction, curvature, random delays, etc.) can be derived for each targeted region. Such corrections have been shown to be very effective at the Large Aperture Seismic Array (LASA) and the Norwegian Seismic Array (NOR-SAR) for estimating events of known location. It is not as yet known whether such corrections can significantly improve the waveform estimations of known events on small arrays or significantly improve the performance of front end small array detectors.

D. FEASIBILITY ANALYSIS OF AUTOMATIC AND SEISMIC ANALYST INTERACTIVE DATA PROCESSING

A study was performed by Sax (1974) to evaluate how automatic and analyst interactive processing is most effectively employed for surveillance operations. At the present state of the art, the detection association process severely limits the event detection capability of a network. The process is driven by front end detection bulletins sent to a central facility.

There, false alarm bulletins, large timing errors, and interfering transmissions must be eliminated effectively from the bulletins. The remaining detection bulletins can then be used to reliably detect and update event focal parameters. These updated estimates of the location, depth, and origin time are used to estimate expected arrival times of an event at each station. The arrival times must be estimated to within about one quarter minute to confidently retrieve the event's waveform from a station. To attain a low missed signal probability, front end detectors must be operated at the lowest possible thresholds. To achieve this, the detection association processor must efficiently eliminate a large number of false alarms. It is anticipated that, to attain the most efficient elimination of false alarms, the detection association processor will need to be operated in the automatic mode with a sufficiently well designed algorithm.

To analyze event data after retrieving the waveforms, it is anticipated that, due to the interpretive nature of discrimination processing, seismic analysts will be needed. These analysts will need to turn over programs efficiently with results displayed at each step. Interactive graphics programs are needed to keep up with the work required to parameterize, document and classify events. At the post detection association processing stage, event waveforms sent in from different stations are deposited on a central storage unit. The waveforms from each station are then displayed for edit by an analyst. The analyst selects waveforms with visible signals and time aligns them by cursor manipulation. This is done interactively by the analyst so that the updated event location and error ellipse can be observed after timing each waveform. Large timing errors can be detected by large changes in the size of the error ellipse. Such problem waveforms can be re-timed or deleted if large apparent timing errors are unresolved. Another user option is to pick possible later phases, especially, nearly time coincident pP phases. As each depth-phase (pP) is picked, the old and new value of the depth of

focus, origin time estimate, and standard deviations are displayed. Convergence of the error ellipses can be used for much more accurate determination of the focal parameters, especially depth of focus.

After accurately determining the focal parameters of the event, the large S/N waveforms can be selected and corrected for the ground displacement system response, and for absorption. Each waveform can be classified as positive or negative first motion, with the results stereo plotted to estimate the source mechanism.

The final step of the post detection association process is for the seismic analyst to reduce the waveforms to one or several to be analyzed by the event classification analyst. The event classification analyst interactively performs extensive discrimination analysis to classify the event as an earthquake, as a possible explosion, as a multiple explosion, or as a possible explosion hidden by the coda of an earthquake. For routine event classification analysis, statistical discriminants such as $M_{_{\mathrm{S}}}$ versus $m_{_{\mathrm{h}}}$ and variable frequency magnitude are measured in order to detect possible explosions. These statistical discriminants are supplemented with complex cepstrum analysis to detect explosion echo delays, the reflection coefficient of the echo, the displacement waveform with the echo removed, and the log-log spectrum on which the analyst picks the long-period amplitude and corner frequency. Also, provision is needed to analyze multiple explosions. It is expected that the routine event classification analysis will be performed in considerably less than one-half hour per event. Since there is so much of this analysis which is also highly interpretive, it is anticipated that it must be done in the analyst-computer interactive mode given our present state of the art.

Inevitably, there will be priority events from areas of high surveillance interest which will require extended event classification processing. This will take considerably more interpretation time and more data analysis than routine event classification processing. For such cases a regional file will be opened to document possible treaty violations, and to analyze and evaluate strategically located earthquakes which may present possible opportunities for hiding explosion sources. It is anticipated that a need exists for the capability of handling data collection for such cases at a rate of approximately one per day. This task would require that a research seismologist interactively retrieve the interesting event waveforms and other associated nearby events for comparative analysis. An important support task for analyzing interesting events is to collect raw sensor data of considerable time duration from backup tapes. These extended waveform files should be available for deposition in the data bank as interesting event files within something like twenty-four to forty-eight hours after the event occurrence. It is reasonable that data supporting interesting events will be held for a specified period of time on special event tapes. These would be batch processed until a final classification is obtained. It is anticipated that backup tapes holding the raw sensor data will be held at the station levels for at least several months before recycling.

E. SYSTEM DESIGN ANALYSIS BY SIMULATION

To be able to perform functions in the surveillance mode, it is necessary to develop fault free codes for all of the automatic and interactive processes involved in detecting events. The capability to perform a function, in the surveillance mode, can be evaluated by realistically simulating the workload handled by each process. When feasible, this is done by analyzing seismic event data and seismic noise data. If such data is not available as in the case of hypothetical future network configurations, it is necessary to realistically simulate earth seismicity and noise as well as the system function to be evaluated. This is done by means of computer generated Monte Carlo realizations from representative statistical distributions.

Statistical distributions functions and, in some cases, simulation models were used to generate the effects of event occurrences, transmission, and the operation of automatic system functions such as station detectors and detection association processors. Shoup and Sax (1974) constructed simulators to model the earthquake seismicity and transmission of P waves, pP, and several other dominant compressional wave phases. Also an algorithm was used to generate the statistical fluctuations due to the coda of earthquakes. The model used to generate coda was based on observations of the decay characteristics of earthquakes. Station detectors were simulated by controlling the average false alarm rate of each detector level, e.g., of one false alarm per hour. The required threshold to attain the prescribed false alarm rate is an output of the station detector simulator. The event timing errors were simulated by modeling a special type of event complexity factor: the time delay from first motion to the maximum signal peak. Timing errors were generated by automatically simulating noise detection by backing up from the signal peak to what was detected as noise preceding the signal. From all of the world-wide stations the detection bulletins due to false alarms, P phases, later phases and coda were printed and copied on tape. From this information, the estimated performance and precision of the simulated power detectors could be assessed.

In order to develop suitable codes for automatic detection association processing, the above tape containing world-wide station detection bulletins was used to drive a baseline model detection association processor. The baseline procedure used was to detect overlapping location error ellipses, update the location, and perform logical tests to eliminate false and redundant information. The results indicated that, although the bulletin information could be used to locate events and retrieve data, serious problems were encountered by overloading buffers and occasionally committing logical errors in the association process. Performance was thereby degraded by 0.3 magnitude units of detection capability and by the high rate of about twenty-

five erroneous waveform retrievals per day. Snell and Sax (1976) developed a more advanced model of the same automatic detection association processor. This was accomplished through repeated simulations and diagnoses of results. Performance evaluation of detection association was done by comparing detection association process locations to the known location of simulated events. for all events which exceeded threshold at four or more remote stations. The new model detection association processor demonstrated almost no loss of magnitude detection capability. This result was obtained at an error rate of about three erroneous waveform retrievals per day and at constant front end detector false alarm bulletin rate of twelve per day per remote station. The original baseline detection association processor was shown to perform optimally with remote stations operating at the twelve per day bulletin false alarm rate. Since the new model performs so well, the false alarm rate of front end detectors can obviously be raised substantially. This will improve the overall system detection capability. The optimum value of this rate has not as yet been determined by simulation.

After retrieving event waveforms, the rate at which the event data must be routinely interpreted is expected to range from one to five events per hour. To keep up with this flow of event data, seismic interpreters must process between two and four events per hour. To keep the maximum event processing delays reasonably low, event processors should be designed to achieve rates close to the upper limit but with options for more thorough processing if the workload will permit it. It is also anticipated that for recovery purposes, at least one backup graphics processor will be available to work off any occasional large backlog of event data. During normal periods, this extra graphics processor would be available to create special data files and to perform extended event classification analysis of the interesting events.

To normally maintain small backlogs and to otherwise maintain recoverability from system overloading, it is necessary to provide the seismic

analysts with computer graphics capability to interpret the seismic data. It must be possible for the seismic data analyst to create required graphics supported interactive procedures by means of a convenient special seismic command language. If the graphics processes are properly designed, the analyst can efficiently select data and processing tasks, input parameters, perform time series measurements, and recover conveniently from his own interpretation errors. The proper design of the seismic graphics processor needed to perform any analyst-driven surveillance function requires thorough understanding of the surveillance problem, the associated seismology, and the efficient numerical algorithms needed for the time series analysis. These must be integrated into a top down design by the principal scientist familiar with the above requirements working in close conjunction with one or more persons who perform the system analysis, the computer science, and the software programming. From planning through to final implementation and demonstration, it is usually necessary that these skills remain integrated and coordinated as a team effort.

In operating a surveillance system it is anticipated that at least three seismic analysts are needed in the loop required to carry through data acquisition, interpretation, and deposition of a documented event report into the seismic data bank. Initially, event waveforms are held on a central storage element after automatic retrieval by the detection association processor, the station processors, and the communication processors. The post-detection association seismic analyst selects usable waveform data, aligns the waveforms, picks later phases such as pP, and accurately determines focal information. As a final step, the analyst reduces the aligned waveforms to one or several waveforms to represent source ground motion. At this point the routine event classification seismic analyst identifies the event as an earthquake, a possible explosion, or an interesting event requiring further research investigation. A research support seismic analyst performs quality control on the resultant event waveforms and information and

deposits the classified events into a seismic data bank. This analyst supports events of special interest by retrieving additional sensor data and associated event data. Separate files are set up for events of special interest, and these are possibly also deposited in the seismic data bank.

To establish some of the interactive graphics capability needed to support the surveillance functions of seismic data analysts, Ringdal and Shaub (1974) developed and demonstrated an interactive long-period seismic processing system. They developed a high level special purpose seismic command language for fetching seismic data and performing any desired sequence of interactive computer programs on the data. Their system can be used to create data processing procedures by performing serial or branched sequences of commands. Each command allows the seismic analyst to reference video displays of data and information and interact through a keyboard to guide the next processing step. By selecting appropriate processing steps, the seismic data is manipulated to perform filtering, magnitude measurement, and group velocity analysis. These are some of the useful tools which can be used by the seismic analyst to perform routine event classification processing. In particular, filtering improves detection of the long-period event waveforms. By measuring the long-period magnitude of Rayleigh waves and Love waves, most explosions can be separated from earthquakes. The two random populations are separated by about 0.7 to 1.0 magnitude units with standard deviations of from 0.3 to 0.45 magnitude units. The detectability is approximately 1.0/0.33 ≈ 3.0. Given the detectability of about 3, at the 90% level of explosion detection, it is expected that approximately 5% of the earthquake population will be erroneously classified as explosions based on M versus m criteria alone. At the 50% level of explosion detection, the error rate will be about one per thousand. Clearly, better operating characteristics than these are needed to effectively monitor a test ban treaty. The dependence on M versus m, criteria alone is further complicated by repeated observations of explosion-like earthquakes from certain regions. Not only is this criteria

region dependent but at teleseismic distances it is only reliable for large events of the order of 5.0 and greater due to the severe limitations imposed by long-period seismic noise on the detectability of explosion surface waves. The above cited operating characteristics are conditional on detecting both the surface waves and the bodywaves of both classes of events.

Our present research is motivated by the need to effectively extend analyst interactive discrimination capability to lower magnitude events, e.g., on the order of 4.0 magnitude at teleseismic distance, and the need to more reliably discriminate explosion events from earthquakes. Bache et al. (1975) thoroughly evaluated a short-period variable frequency magnitude discriminant described by Savino and Archambeau (1974), Bache et al. (1974), and Archambeau et al. (1974). The results of the evaluation of the short-period variable frequency magnitude discrimination techniques indicated that approximately the same operating characteristics as M versus m discrimination could be extended to lower magnitude events.

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Any statistical method of discriminating earthquakes and explosions such as M_s versus m_b measurements or short-period variable frequency magnitude measurements will generate out of the earthquake population occasional and possibly, from some locations, consistent false indications that an explosion has occurred. Another even more serious type of error is discriminants generated out of the presumed explosion population which are consistently misidentified as earthquakes. In order for the surveillance system to be credible, the rate of such alarms must be adequately controlled as part of the discrimination process.

In order to improve the operating characteristics of statistical discriminants, the statistical methods should be backed up by a capability to separate the direct transmission and free surface echo. This provides the means of directly verifying that an event, statistically indicated as an

explosion, satisfies the necessary conditions of an explosion, i.e., an echo reflection coefficient close to minus one, a reasonable time delay for a shallow focus contained explosion, and a reasonable direct transmission waveform shape and spectrum.

SECTION II

DESIGN SPECIFICATIONS OF THE SHORT-PERIOD EARTHQUAKE/ EXPLOSION DISCRIMINATOR (SPEED) AS AN INTERACTIVE GRAPHICS EVENT CLASSIFICATION MODULE ON THE PDP-15

A. INTRODUCTION

The Short-Period Earthquake/Explosion Discriminator (SPEED) processing module has been integrated into the Interactive Seismic Processing System (ISPS) graphics capability on the PDP-15 computer. This section provides background information, data preparation procedures, and a description of the SPEED module.

In Subsection B, the ISPS is briefly discussed in terms of a world-wide surveillance system. The data preparation procedures - the reduction to one or at most several event waveform representations to be used in the discrimination processing - are described in Subsection C. A thorough description of the operation of the SPEED module, with its real cepstrum and Variable Frequency Magnitude (VFM) and corner frequency analysis procedures is given in Subsection D. A general summary of the algorithms used by SPEED are shown in Subsection E. Finally, hardcopy examples of the SPEED graphics displays are shown in Subsection F.

B. CONTEXT OF IMPLEMENTING A WORLD-WIDE SEISMIC SURVEILLANCE SYSTEM

The overall objective of a seismic surveillance network is the detection, location, and identification of seismic events on a world-wide basis. To achieve this objective, there are six broad functional categories that need to be considered. In Table II-1, each of the broad functional areas

TABLE II-1
SURVEILLANCE NETWORK FUNCTIONS
(PAGE 1 OF 2)

Functional Category	Information Generation and Processing
Data Collection	 Deploy remote sensors. Data collection processing. Hold sensor data for retrieval. Edit event waveforms from the sensor data which are held for retrieval.
Station Event Detection	Generate station detection bulletins.
Communications and Data Lines	 Retrieve raw data from sensors to disk or station collection platforms. Detection bulletin from data collection platform to central storage element. Event waveforms from station storage element to central storage element. Event parameters and representative waveform from central storage element to data bank. Backup data tapes. Messages for command and control of central and station operations.

TABLE II-1
SURVEILLANCE NETWORK FUNCTIONS
(PAGE 2 OF 2)

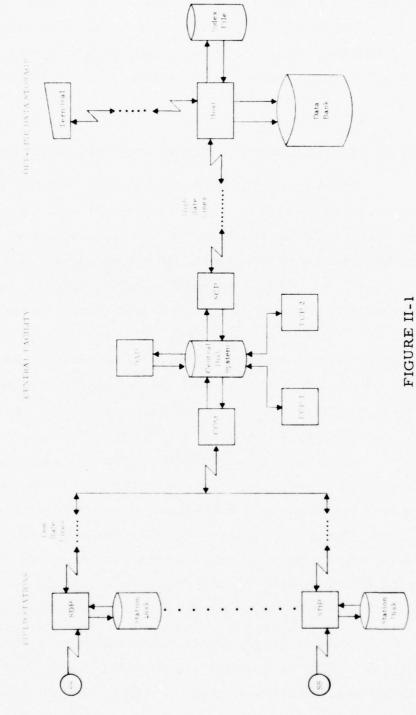
Functional Category	Information Generation and Processing
Retrieval of Event Waveforms	 Control retrieval of event data from station storage elements by generating event locations and origin times from detection bulletin information. Generate accurate focal parameters from event data sent in from stations. Classify events by discrimination analysis of representative event waveforms.
Storage and Retrieval of Event Parameters and Data	 File event bulletins and representative waveforms. File hourly noise parameter measurements. Update regional reference event file. Update and consolidate index and files for long-term storage of events.
System Control and Upgrade	 Stations and network performance evaluation. Prediction and control of system overloading. Fault detection, maintenance and repair control. Start up and updating of new model function processors. Updating reference event files. Research support by data base generation.

are defined. They are broken down into specific function processes which generate the files of information needed to control the operation of a seismic surveillance network.

The hardware configuration of a seismic surveillance network is shown in Figure II-1. Arrays or regional deployments of short-period and long-period sensors are linked by communications to a data collection platform. At the data collection platform, the data are formatted, multiplexed, and held temporarily on a station disk and permanently on a backup tape. Station detection functions are immediately performed upon this sensor data held on the station disk. Independently of other stations in the network, each station detection processor detects the possible arrival of seismic events. These detections are described on detection bulletins which are immediately sent by a communication link or data line from the data collection platform to a central facility. At the central facility the detection bulletin is decoded by the COM processor and queued on the central disk system in a detection bulletin file. On a first in/first out basis, the detection bulletins fill the work space of an automatic detection association processor. This processor uses information obtained from the incoming detection bulletins to generate output which includes locations and origin times of events. The event focal parameter estimates are used at this point to automatically request time windows of data containing the event waveforms. These requests to retrieve a seismic event waveform data are sent by communication links or data lines to the station data collection platforms. At each station data collection platform, the desired event waveforms are automatically retrieved from a disk storage element which is holding the seismic data for up to six hours. The retrieved event waveform data are sent back as data packets during periods of time that the communication link or data line is available (e.g., between transmissions of detection bulletins). The waveform data are received at the central facility by a central communications processor which files the waveforms on the central storage element under supervision of a central disk system.

Detection Association Processor DAP Station Detection Processor Communication Processor Seismic Sensors SS SDP COM

Event Classification Processor (Discrimination) Event Classification Processor (Special Events) System Control Processor ECP1 ECP2 SCP



SEISMIC NETWORK HARDWARE CONFIGURATION

The event data stored on the central disk system consists of many channels. To be practical, discrimination processing must be fast enough to keep up with the data flow generated by the surveillance network. The reduction of the multi-sensor representations of an event to one or several representations for discrimination processing is described in the next section.

C. DATA PREPARATION FOR DISCRIMINATION PROCESSING

The event waveform file stored on the central disk system consists of one or more sensors or signal estimates from each station receiving the event. These must be reduced to one or at most several event waveform representations to be used for discrimination processing. In order to rapidly classify the event as a possible explosion or earthquake, the discrimination processing must be rapid enough to keep up with data flow on the order of 50 events per day. Allowing a utilization of 50% of computer capacity, the processing time per event for all routine event classification processing should be on the order of 15 minutes. Specific algorithms should therefore consume no more than several minutes of the event processing time. In order to reliably classify the events, there should be considerable diversity of discrimination processing readily accessible to the analyst. In particular, short echo time determinations by cepstrum analysis should be mandatory in order to reduce false identification of earthquakes to an acceptably low false alarm rate for events of magnitude greater than the minimum targetted for surveillance. Also, some form of the variable frequency magnitude method should be used, provided that discrimination capability comparable with M versus m, can be obtained with better detectability of lower magnitude events.

At the station platform level, multi-sensors such as arrays are reduced to a single station waveform representation. Since very accurate arrival time measurements are not required at this level, the reduction

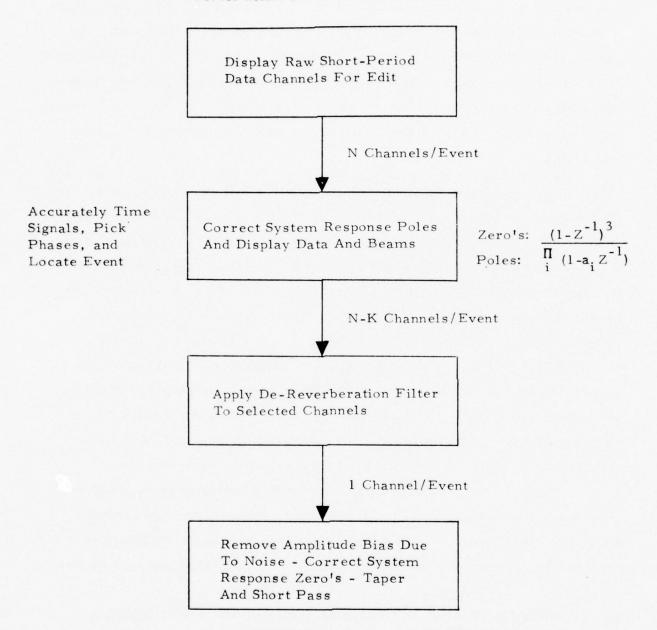
process can be carried out automatically. The need for reduction also occurs at the post DAP level, where station waveforms are accurately timed by an analyst and precise focal parameter estimates are made. A post DAP analyst edits stations with seismic information, signal centers the event, and invokes processing to reduce the station waveforms to a single event waveform representation to be queued for discrimination processing by the event classification analyst.

A requirement for designing data reduction algorithms for the above applications is to produce event estimates with an undistorted spectrum of the event. Beamforming is in many cases inadequate, as deviations from the assumption of plane waves in an infinite homogeneous medium (the model for beamforming) produces severe attenuation of high frequencies which degrades the data for short-period discrimination processing. A method of event estimation based on multi-channel complex cepstrum estimation is shown in Figure II-2. The critical technical points in the development are to prevent aliasing of the phase between channels, and to develop the optimum method of automatically weighting channels in computing the average log amplitude and phase of the representative waveform. In Figure II-2, it is also shown that the waveforms are corrected for spectral bias due to additive noise, and are corrected for system response to produce an estimate of broadband ground motion such as acceleration, velocity, or displacement. As a final step, single channel complex cepstral techniques such as shortpass filtering are used to reduce the extensive coda of large complex events.

D. APPLICATION OF THE INTERACTIVE SEISMIC PROCESSING SYSTEM TO DISCRIMINATION PROCESSING

The Interactive Seismic Processing System (ISPS) provides an interactive graphics capability on the PDP-15 computer located at the Seismic Data Analysis Center for the purpose of detecting and analyzing seismic waveforms. It currently consists of a system supervisor and five stand-alone

DATA BASE INPUT PREPARATION



J EVENTS ON TAPE WITH 1 WAVEFORM PER EVENT

FIGURE II-2

REDUCTION OF WAVEFORMS TO PARAMETERS AND A SINGLE WAVEFORM REPRESENTATION OF THE EVENT

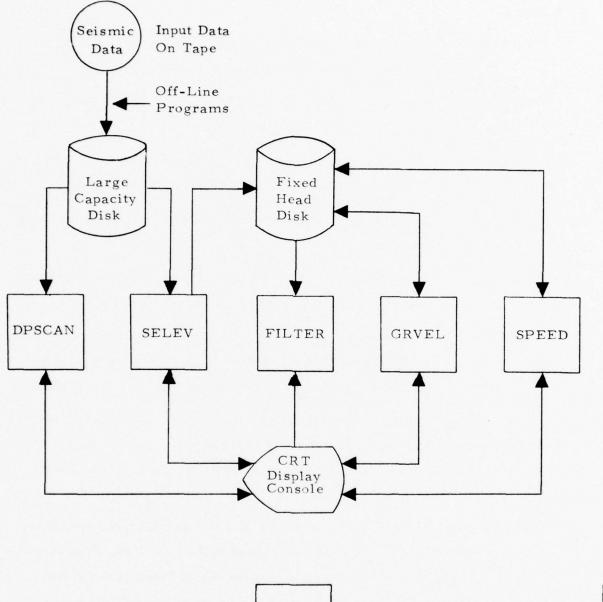
processing modules as shown in Figure II-3. In particular, they are defined as follows:

- SUPVSR The system supervisor to control processing module execution within the CRT console environment.
- DPSCAN A processing module to catalog and display waveforms from the large capacity disk.
- SELEV A processing module to select any event, station, component, or time window for analysis.
- FILTER A processing module to perform general signal analysis functions.
- GRVEL A processing module to generate long-period dispersion curves and fundamental mode source spectrum.
- SPEED A processing module to perform short-period earthquake/ explosion discrimination utilizing cepstrum, variable frequency magnitude, and corner frequency techniques.

The continuing methodology associated with ISPS is the simulation of analysis functions to be performed by processors comprising a world-wide seismic surveillance system. A description of how this simulation is achieved is given as follows:

- Research and development of analysis software for detection, association, and classification of seismic events. The components of this software are computational subroutines coded in FORTRAN IV, having minimal or non-existent I/O requirements. This insures that these routines are machine independent and are easily maintained.
- Imbedding this analysis software in an environment simulating that of a surveillance system when each processor is driven

RESEARCH ON ROUTINE EVENT CLASSIFICATION PROCESSING (DISCRIMINATION)



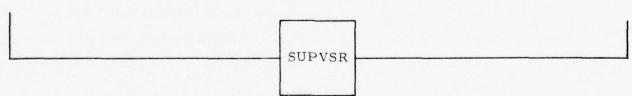


FIGURE II-3

INTERACTIVE SEISMIC PROCESSING SYSTEM (ISPS) INFORMATION FLOW

by a special purpose operating system which supports the following:

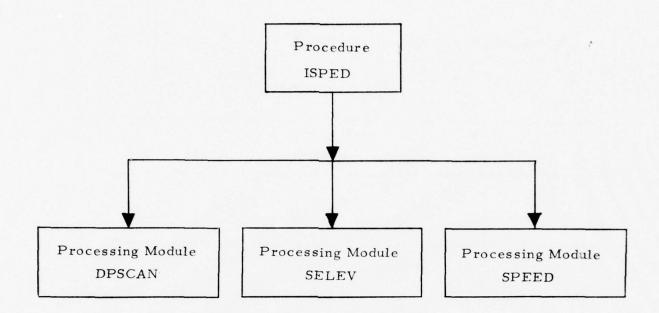
- A console device to serve as the physical interface between computer system and analyst, capable of communicating and displaying symbol strings and graphic images
- A command language to control execution of analysis functions assigned to the processor
- An interpretive high level seismic programming language permitting the analyst to design and execute special functions on-line. The language will have the capability to access, perform computation upon, and display data for evaluation and analysis purposes
- Automatic processing modes providing for execution of analysis functions with minimal intervention required by the analyst once processing procedures have been standardized.
- Insuring that the ISPS environment accurately simulates that
 of an actual processor by incorporating a top-down design
 stressing the following:
 - Operational flexibility
 - System reliability and recoverability
 - System maintainability and extendability.

This effort was given high priority for two main reasons. First, interactive processing systems must be capable of accepting erroneous input without requiring a restart of the entire analysis procedure in question. Secondly, the system should be extendible so as to maintain its applicability as advancements in seismic processing are realized.

A new analysis function designated SPEED has been developed to simulate discrimination processing by utilizing CEPSTRUM and Variable Frequency Magnitude (VFM) techniques and corner frequency. SPEED will be demonstrated as a processing module which has been incorporated into ISPS. Figure II-4 illustrates the utilization of a procedure named ISPED to perform discrimination processing within the ISPS environment. ISPED defines a processing module execution sequence which includes the modules DPSCAN, SELEV, and SPEED.

The function SPEED consists of three discriminant calculations. In Figure II-5, the first one of the discriminant functions performs cepstrum analysis; the second, variable frequency magnitude (VFM) analysis, and the last, corner frequency analysis (CF). The three functions of SPEED - cepstrum, VFM, and CF - are described as follows:

- The cepstrum analysis is subdivided into three interactive subroutines. SUB1 adjusts start time or exponentially tapers the data as desired by the analyst. SUB2 separates the signal and echo by trial-and-error deconvolution. SUB3 generates a residual seismogram and sets up CEPSTRUM to pick later phases (e.g., multiple explosions), if desired by the analyst. The statistics generated for discrimination are the time delay of the echo, reflection coefficient, correlation coefficient between the echo and the first arrival, and the residual noise when the estimate of the echo and first arrival are removed from the original data.
- The VFM analysis in SUB4 removes the exponential taper from the first arrival signal estimate derived from CEPSTRUM. In SUB5 it computes the high and low frequency dependent magnitudes from the corresponding semi-log-signal spectrum display corrected for absorption.

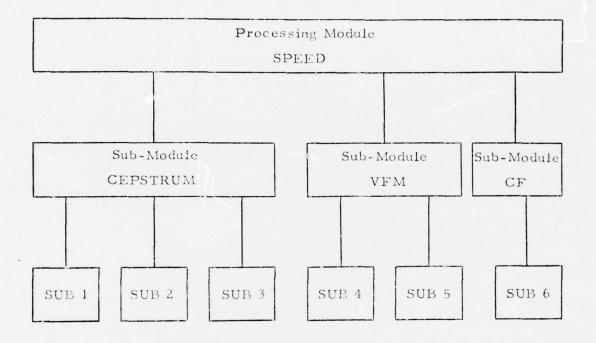


The procedure ISPED may be created and executed at the Interactive Console by the following commands:

. CREATE ISPED PERFORM DPSCAN 1.0 . PERFORM INTERUP 2.0 . PERFORM SELEV 3.0 4.0 . PERFORM INTERUP . PERFORM SPEED 5.0 6.0 . PERFORM INTERUP 7.0 . #S . PERFORM ISPED.

FIGURE II-4:
IMBEDDING SPEED WITHIN ISPS ENVIRONMENT

SHORT-PERIOD EARTHQUAKE/EXPLOSION DISCRIMINATOR



- SUB 1 Conditions Data For Cepstrum Analysis
- SUB 2 Separates Signal And Echo
- SUB 3 Computes Residual Seismogram
- SUB 4 Conditions Data For Spectral Analysis
- SUB 5 Computes Variable Frequency Magnitudes
- SUB 6 Computes Corner Frequency And Amplitude From Log-Log Spectrum Plot

FIGURE II-5

SHORT-PERIOD EARTHQUAKE/EXPLOSION DISCRIMINATOR

The CF analysis in SUB6 can measure up to four corner frequencies, amplitudes, and roll-offs from the log amplitude versus log frequency spectrum of the signal transmission corrected for absorption.

The software configuration of the interactive CEPSTRUM processor is shown in Figure II-6. A signal is input to SUBl, and the data and real cepstrum are displayed. The complex log spectrum is calculated and held in workspace along with the data. If the analyst is not satisfied with the start time of the data selected with the SELEV module, he may input other trial time shifts until he is satisfied. The analyst then presses the taper button until he is satisfied with the appearance of the data and the real cepstrum. If he tapers too much, he recovers by pressing the replace taper button. After data conditioning is finished, the analyst presses the hardcopy-exit button and a Calcomp plot tape of the results is prepared. Should the analyst desire, the data may be plotted while he is performing other analysis. Following preparation of the plot tape, control is passed to SUB2. In SUB2, the cepstrum and conditioned data display are refreshed. The analyst presses the deconvolve button. He then inputs trial values of the reflection coefficient and time delay, examining the effect of deconvolution on the data and cepstrum. When satisfied with the resultant deconvolution, he presses the load button which computes and saves the echo and allows him to short pass the signal. Smoothing of the log spectrum of the signal estimate with a Bartlett window provides a short pass filter. This is used to separate the earthquake pulse from the echo. If the analyst presses the smooth button one too many times, he can recover the preceding state by pressing the replace smooth button. By pressing the load button again, the smoothed signal is saved and the echo is retrieved to be similarly short passed. The load button is pressed a third time to form the reconstructed signal with its echo. Whenever the load button is pressed, a display of the conditional data, the signal, the echo, and the reconstructed signal are shown from top to bottom as they become available

- Separates signal from coda and noise
- Separates the direct path and free surface reflection
- Estimates first pulse direct path and echo
- Sets up SPEED to compute multiple events
- Computes discriminant statistics

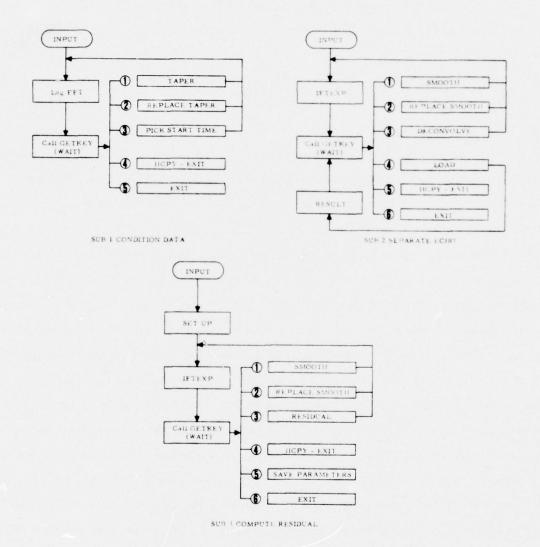


FIGURE II-6

INTERACTIVE PROCESSOR SPEED MODULES CEPSTRUM

by the above analyst processing. After finishing SUB2 processing, the analyst presses the hardcopy-exit button to plot the results, and passes control to SUB3. In SUB3, the reconstructed seismogram is subtracted from the conditioned data to produce a residual seismogram with the first phase signal and echo removed. A later phase is picked by means of trial shifts of the waveform similar to that done in SUB1. By pressing the SAVE PARAMETER button, the residual signal, which was shifted to the front of the seismogram, is replaced as input to CEPSTRUM. In this way, up to four phases (e.g., multiple explosions) can be successively analyzed by the analyst. In the preceding operations, discriminants such as echo time, reflection coefficient, correlation coefficient, and residual signal-to-noise ratio are calculated and included in the hardcopy as annotations.

The software configuration for variable frequency magnitude (VFM) calculation is shown in Figure II-7. Initially in SUB4, the smoothed and tapered signal estimate from CEPSTRUM is displayed along with the real cepstrum. The data are conditioned by inverting the exponential tapers put in by the analyst to condition the data for the cepstrum analysis. Roundoff errors which may occur at the end of the record are zeroed out by pressing the zero button. The signal may be short pass filtered by pressing the smooth button. Control is then passed to SUB5 and the real log spectrum of the signal estimate is displayed. This spectrum may be smoothed incrementally by a Bartlett window and may be corrected for absorption. Magnitude measurements are initiated by pressing the measure magnitude button. The average log amplitude is computed in a central window of the log spectrum. The change in log amplitude between a marked low frequency and the average and a marked high frequency and the average are computed as VFM discriminants. If the signal is obviously noisy at the specified low or high frequency, a cursor is used to pick points on the spectrum near the desired frequency outside the frequency range of the noise. By linear extrapolation, the magnitude difference

- Operates on signal estimate output of cepstrum program
- Inverts the taper which was applied to the signal
- Add zero's to end of signal model, if needed
- Picks two low and high frequencies to read magnitude
- Linearly extrapolates to obtain low and high frequency magnitude at desired frequencies

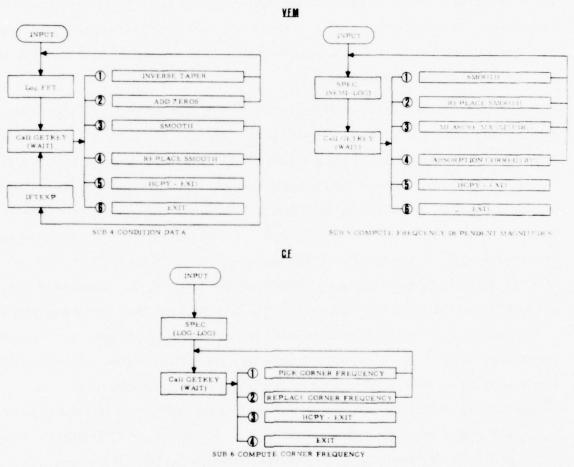


FIGURE II-7

INTERACTIVE PROCESSOR SPEED MODULES
VARIABLE FREQUENCY MAGNITUDE AND CORNER FREQUENCY

at the desired high or low frequency is computed. Our experience indicates that this option is usually not needed.

The software configuration of the corner frequency (CF) calculation is also shown in Figure II-7. The real log spectrum versus frequency computed in SUB5 is transformed into a log spectrum versus log frequency display. Corner frequencies, magnitudes, and roll-offs are measured by pressing the corner frequency button. A cursor is used to pick two points of the spectrum on each side of the desired corner frequency. The corner frequency is then automatically picked as the intersection of the two straight lines through the left and right pair of points. This process may be repeated up to four times. The resultant corner frequency, amplitude at the corner frequency, and roll-offs on the left and right side of the corner are displayed for each corner picked. If the analyst is not satisfied with a picked corner frequency, it may be erased by pressing the replace corner frequency button. After the analyst finishes picking corner frequencies, the hardcopy-exit button can be used to produce a Calcomp plot tape.

An exit button is present in all of the subroutine modules described above. This is a recovery procedure which re-starts the subroutine module in case of irrecoverable errors or failures. It is unlikely that this option will be needed because of other internal provisions for error recovery.

E. ALGORITHMS

- 1. Data Preparation
 - a. Align and Display Data

A partial list of symbols used in the following derivation of algorithms is given here.

T	-	represents uniform time between sampled data points.		
N	-	number of time sampled points.		
n	-	sequence number of real time domain data points.		
k	-	sequence number of complex frequency domain data points.		
Δf	-	uniform frequency interval between spectrum samples,		
		1/NT.		
FFT()		fast Fourier Transform operator; FFT (), inverse.		
d(t)	-	data; d(nT), sampled data.		
$Z(k\Delta f)$	-	spectrum computed from sampled data.		
$X(k\Delta f)$	-	real part of $Z(k\Delta f)$.		
$Y(k\Delta f)$	-	imaginary part of $Z(k\Delta f)$.		
$A(k\Delta f)$	-	amplitude spectrum		
$\phi(k\Delta f)$	-	phase spectrum		
$\Delta \phi (k \Delta f)$	-	the finite difference of phase as an approximation to the		
		differential of the phase.		
$\Delta X(k\Delta f)$	-	difference of the real part of the spectrum.		
$\Delta Y(k \Delta f)$	-	difference of the imaginary part of the spectrum.		
w	-	exponential taper used to derive channel Wiener weights,		
		et al.		
$j^{d}_{N}(nT)$	-	sampled noise data on j th channel.		
j ^d S (nT)	-	sampled signal data on j th channel.		
u	-	parameter to weight ambient noise in deriving channel		
		Wiener weights.		
v	-	parameter to weight coda noise in deriving channel		
2		Wiener weights.		
s_j^2	-	signal power; N _j ² , noise power; C _j ² , coda power used in		
		channel Wiener weight estimates.		
C _j (f)	-	the spectrum of a linear coda operator for the j th channel.		
S(f)		the spectrum of signal common to all channels.		

the spectra of independent noise added to the jth channel. $N_{i}(f)$ $\text{Log } Z_{S}(k\Delta f)$ log-spectrum of signal corrected for noise bias. $\text{Log } A_S(k\Delta f)$ real part of log-spectrum of signal. $\phi_{S}(k\Delta f)$ imaginary part of log-spectrum of signal. $\text{Log } A_S^*(k\Delta f)$ corrected for absorption. $\phi_S^*(k\Delta f)$ corrected for absorption. $S(k\Delta f)$ exponentiated spectrum corrected for absorption. d*(nT) estimate of signal pulse corrected for absorption. R(Z)system response $R_1(Z)$ part of system response due to poles. $R_2(Z)$ part of system response due to zeros. roots of poles of system response. α_{i} scale factors of system response associated with poles. γ_i d'(nT), d(nT) corrected for poles of system response. $\text{Log } A_S^{\text{\tiny{II}}}(k\Delta f)$ binomial smoothing of Log $A_{S}(K\Delta f)$. $\phi_S''(k\Delta f)$ binomial smoothing of $\phi_S(k\Delta f)$. Re() real part of complex elements of an array. Log { } logarithm of complex elements of an array. the elements generated by operators on the left side re- $() \rightarrow ()$ place the elements of the array on the right side. display of arrays designated in parenthesis. DISPLAY() travel time divided by absorption Q when used in Strick's T/Q absorption formula.

Given the ray parameter $\,\mathrm{d}t/\mathrm{d}r$ (seconds/kilometer) and direction $\,\theta\,$ of the incident wave,

$$dt/dx = dt/dr \cos \theta$$

$$dt/dy = dt/dr \sin \theta$$
(II-1)

and the travel time delay from the center of the array (x_0, y_0) to a sensor position (x_i, y_i) is:

$$\Delta t_{i} = (dt/dx) (x_{i} - x_{o}) + (dt/dy) (y_{i} - y_{o}). \qquad (II-2)$$

A matrix plot of all of the plane wave aligned sensors, either filtered or unfiltered and with the signal centered, is inspected by the analyst to remove inoperative channels, noisy channels, and clipped channels.

b. Selected Channels Are Complex Cepstrum Beamformed

Acceptable data channels are timed to allow about one-half second of noise preceding the earliest apparent arrival of signal energy. From that start time, the following 512 points (20 points/second) of data are read into a signal buffer; the preceding 512 points are read into a noise buffer. An exponential taper, a - where n is the number of points delay from the start point - is applied to the data in the signal and noise buffer. The parameter, a, weights the cepstrum analysis more heavily toward the start time of the signal. A recommended value is 0.98 which is down to 0.13 after 100 points. If desired, smaller values can be applied to the noise buffer for more conservative estimates of the interfering noise power. We used 0.98 for both buffers. The signal buffer and noise buffer were filled out with 1536 zeros so that each buffer contained 2048 points.

An N = 2048 point fast Fourier Transform (FFT) was applied to the signal and noise buffer producing a signal and noise spectrum, each of 1023 complex points plus 2 real points at zero frequency and the Nyquist frequency (10 Hz). The log-spectrum is computed of the spectral data in the signal and noise buffer. Given the data, d(t), as uniformly sampled signal or noise at period T, the spectrum sampled at frequency interval $\Delta f = 1/NT$ follows:

$$Z(k\Delta f) = FFT(d(nT))$$
 $n = 1, ..., N.$

$$= X(k\Delta f) + i Y(k\Delta f) \qquad k = 0, ..., N/2$$

$$Log (Z(k\Delta f)) = Log A(k\Delta f) + i\phi(k\Delta f)$$
 (II-3)

where

$$A(k\Delta f) = \left(X(k\Delta f)^{2} + Y(k\Delta f)^{2}\right)^{1/2}$$

$$\phi(k\Delta f) = \tan^{-1} \left(Y(k\Delta f)/X(k\Delta f)\right)$$

and

FFT() = functional Fourier transform operation.

The phase $\phi(k\Delta f)$ is complicated by rapid changes in phase from one frequency point to another due to unknown start time delays and influence of coda. This can cause errors in detecting the position and size of 2n jumps in the phase angle, which must be corrected to produce a continuous phase curve. To avoid this problem, the phase information is passed through as, i.e., $\Delta \phi(k\Delta f)$, a first difference operator running from k=1, to k=N/2, where $k\Delta f$ are the corresponding frequencies running from zero to Nyquist $(N/2) \bullet (1/NT) = 1/2T$.

$$\Delta\phi(k\Delta f) = \frac{Y(k\Delta f) \Delta X(k\Delta f) - X(k\Delta f) \Delta Y(k\Delta f)}{\left(X(k\Delta f)^2 + Y(k\Delta f)^2\right)}$$
(II-4)

where

$$\Delta X(k\Delta f) = X(k\Delta f) - X((k-1)\Delta f)$$

and

$$\Delta Y(k\Delta f) = Y(k\Delta f) - Y((k-1)\Delta f).$$

The data on each channel d(nT) are converted to a log-spectrum, where the first part is $A(k\Delta f)$ and the second part is $\Delta\phi(k\Delta f)$; and both parts are even symmetric at zero and the Nyquist frequency (k=0, N/2).

Each channel $\left(A(k\Delta f),\ \Delta\phi(k\Delta f)\right)$ is weighted and summed by a Wiener weight for the j^{th} channel:

$$W_{j} = S_{j}^{2}/(S_{j}^{2} + uN_{j}^{2} + vC_{j}^{2})$$
 (II-5)

where

$$s_j^2 = \sum_{n=0}^{N} \left[j d_S(nT) \cdot w^n \right]^2$$

$$N_j^2 = \sum_{n=0}^{N} \left[i d_N(nT) \cdot w^n \right]^2$$

$$C_j^2 = \sum_{n=0}^{N} \left[j^d S \left((N* - n + 1) T \right) w^n \right]^2$$

u = parameter between zero and one to weight ambient noise

v = parameter to weight coda measure

w = exponential taper, zero to less than one.

For the channel Wiener weights to be realistic signal and noise, it is recommended that w be set to 0.94 to 0.98. A value of w = 0.95 was used for this study, which effectively gives a signal window length of about two seconds. Note that setting u = v = 0 provides a unity weighted beamform process. Setting u = 1, v = 0 provides a full Wiener weighting using ambient noise. It is recommended that, since S_j^2 , N_j^2 and C_j^2 are subject to statistical errors as well as bias due to timing problems, less than full Wiener weights be used. In this study, u = v = 0 in order to baseline our results using unity weighted complex cepstrum beamforming. It is also noted that the $\Delta\phi(k\Delta f)$ of the noise buffer contains no information of value. It, therefore, was not computed and passed through the next stage of data processing.

c. The Complex Cepstrum Beamform is Smoothed and Corrected for System Response, Absorption, and Reverberation Noise

The complex cepstrum beamform is designed to minimize the variance of log normally distributed random fluctuations of the signal due to random propagation effects and to some extent due to the additive log-normal noise factor. If $C_i(f)$ is a random propagation effect of the jth channel and

 $N_{j}(f)$ is an additive zero mean random variate with a log normally modulated envelope, then the jth channel with common signal spectrum S(f) is:

$$X_{j}(f) = C_{j}(f) S(f) + N_{j}(f)$$

$$= S(f) C_{j}(f) L_{j}(f)$$
(II-6)

where

$$L_{j}(f) = 1 + C_{j}(f)^{-1} N_{j}(f).$$

For visible signals it is expected that $|C_j(f)| \gg |N_j(f)|$. To the extent that $L_j(f)$ can be approximated as a log normal variate, beamforming over the spatial distribution of channels minimizes transmission effects of C_j and pseudotransmission effects of L_j . The variance of the expected log amplitude of the signal and the expected phase of the signal due to such independently random transmission effects is reduced by 1/J where J channels compose the complex cepstrum beamform of the signal. It is noted that this type of beamforming does not directly reduce the expected means of the ambient noise as does time domain beamforming. But indirectly as the variance of the log normal distribution is lowered, the arithmetic mean amplitude of the noise will also be somewhat reduced, especially the occasional large amplitude fluctuations.

Before beamforming the log amplitude of data in the noise buffer, the power spectrum of noise was compared to that of the signal. Based on stationarity, it was expected that the power in the signal buffer should exceed the power in the noise buffer at all frequencies. In some cases due to statistical estimation errors, this was not the case. In those cases, the log amplitude of the signal buffer replaced that of the noise buffer. Thus, the average log amplitude of the data in the noise buffer was guaranteed to be equal or less than that in the signal buffer.

To correct for positive bias of the measured mean amplitude of signal, the power of the average signal was reduced by the power of the average noise as follows, where the subscripts S+N and N refer to the

signal and noise buffers, respectively; the bar refers to numerical averaging over channels; and the E operator refers to the expected value, in this case, of the signal amplitude spectrum Log A_S^t

$$E(\text{Log } A_S) = \text{Log} \left(\text{Exp}(\overline{\text{Log } A_{S+N}}) - \text{Exp}(\overline{\text{Log } A_N}) \right). \quad (\text{II-7})$$

This expected value of Log A_S , obtained by applying a noise bias correction, must be positive definite. This resulted from limiting the noise power estimate of each data channel to power less than or equal to the power of data in the signal buffer. The real part of the signal log spectrum was replaced by $E(\text{Log }A_S)$. The imaginary part of the signal log spectrum remained unchanged because no phase bias correction can be derived from noise power information.

At a seismic station, the observation of past events from most regions could be characterized by a nominal value for absorption, T/Q. Events from most regions observed at NORSAR were observed to be approximately T/Q = 0.25, as shown for a number of events by flat displacement spectrum near the corner frequency and roll-offs of k^{-2} or k^{-3} above the corner frequency. It is expected that events from certain localized regions associated with high heat flow could be observed to have much higher absorption factors, T/Q. Regional absorption corrections were applied to the events following the method of Strick (1970). The absorption-dispersion operator used to correct the log spectrum is as follows:

Uncorrected for absorption:

$$Log Z_{S}(k\Delta f) = Log A_{S}(k\Delta f) + i \phi_{S}(k\Delta f) . \qquad (II-8)$$

Corrected for absorption:

$$\log A_{S}^{*}(k\Delta f) = \log A_{S}(k\Delta f) + \pi k\Delta f (T/Q)$$

$$\phi_{S}^{*}(k\Delta f) = \phi_{S}(k\Delta f) + 2k\Delta f (T/Q) \log \left(\frac{1000 \pi}{k\Delta f}\right). \quad (II-9)$$

Before applying the absorption correction, the beamformed first difference of the phase, $\Delta\phi_S(k\Delta f)$, must be numerically integrated to compute the phase. The initial phase at k=0 was taken as zero. The $\Delta\phi_S(k\Delta f)$ was exponentially tapered by w^n to statistically weight the influence of low frequency phase information and to minimize roundoff errors due to the integration. The taper of 0.96 used was determined experimentally by inspection of time traces. No significant distortion of the time trace was noted for the phase angle taper greater than 0.96. The integration process used to compute $\phi_S(k\Delta f)$ follows as:

$$\phi_{S}(k\Delta f) = w \phi_{S}((k-1)\Delta f) + \Delta \phi_{S}(k\Delta f)$$

$$k = 1 \cdots K \qquad \phi_{S}(0) = 0. \tag{II-10}$$

At this point the preceding absorption corrections are applied to the real and imaginary part of the log spectrum. The absorption-dispersion corrected log spectrum of the signal is exponentiated.

$$S(k\Delta f) = \exp\left(\text{Log } A_S^*(k\Delta f) + i \phi_S(k\Delta f)\right)$$

$$= A_S^*(k\Delta f) \left[\cos \phi_S(k\Delta f) + i \sin \phi_S(k\Delta f)\right]. \quad (II-11)$$

This exponentiated spectrum is transformed to the time domain:

$$d*(nT) = FFT^{-1}(S(k\Delta f))$$
,

to produce the complex cepstrum beamformed seismogram.

As a result of the system response correction applied to each channel fed into the above complex beamforming process, d*($n\Delta T$) represents the first derivative of the acceleration of earth ground motion.

The method for correcting time domain data for system response was to experimentally fit a physically realizable and invertible spectral operator such that the power of the operator matched the power of the system response to an impulsive ground displacement input. The spectrum of the seismic system response, R(Z), is given as follows, where $Z^{-1} = \exp(-i \ 2\pi k\Delta f \ T)$ represents the spectrum of a time delay of one point sampled every T seconds:

$$R(Z) = R_{1}(Z) * R_{2}(Z)$$
(poles) (zero's)

 $R(Z) = \left\{ \prod_{j=1}^{3} \frac{\gamma_{j}}{(1 - \alpha_{j} Z^{-1})} \right\} \left\{ \prod_{j=1}^{3} (1 - Z^{-1}) \right\}. \quad (II-12)$

The values of γ_j and α_j were determined by visual curve fitting where |R(Z)| fitted the measured system response to within about 10 percent in the range from 0.0 Hz to 5.0 Hz. Above 5.0 Hz an analogue Butterworth filter was cascaded into the system response. Since we could not obtain consistent specifications of the roll-off between 5.0 and 10.0 Hz, no attempt was made to correct the response in that frequency range. Note that R(Z) is split into two parts: the first part, $R_1(Z)$, is the weighted cascade of 3 poles with roots $Z = \alpha_j$ and weights on the input γ_j . The second part, $R_2(Z)$, is the cube of a numerator zero factor with root Z = 1. The inverse of $R_1(Z)$ is stable and generally increases the S/N ratio of the seismic event. This operator was applied to each input channel was follows, where d(nT) is the input with seismic response $R_2(Z)$, and d'(nT) is the output with the response $R_2(Z)$:

$$d'(nT) = \left[d(nT) - \alpha_{j} d(n-1)T\right]/\gamma_{j}. \qquad (II-13)$$

For j = 1, γ_1 = 1.08, and α_1 = 0.7778. The output of this first stage corresponding to j = 1 replaces the input d(nT) to form a digital cascaded filter. The two following operations are j = 2: γ_2 = 1.39, α_2 = 0.6243; and j = 3: γ_3 = 3.20, α_3 = 0. After inverting the poles, the remainder system response γ_3 = 3.20, γ_3 is a first difference operator cascaded three times or a

third difference operator. Thus, $R_2(Z)$ approximates digitally the third derivative of ground motion displacement or first derivative of ground motion acceleration. Since $Z^{-1} = \exp(-i \ 2 \ \pi \ k \Delta f \ T)$, when k=0 (zero frequency), the magnification of $(1-Z^{-1})^{-1}$ is infinite. For this reason, the inverse is taken approximately to avoid blowing up low frequency noise as:

For acceleration:
$$A(Z) = \frac{1 - aZ^{-1}}{1 - u_1Z^{-1}}$$

For velocity: $V(Z) = \frac{1 - aZ^{-1}}{1 - v_1Z^{-1}} \cdot \frac{1 - aZ^{-1}}{1 - v_2Z^{-1}}$
For displacement: $D(Z) = \frac{1 - aZ^{-1}}{1 - w_1Z^{-1}} \cdot \frac{1 - aZ^{-1}}{1 - w_2Z^{-1}} \cdot \frac{1 - aZ^{-1}}{1 - w_3Z^{-1}}$. (II-14)

The numbers used in the above spectral operators were a = 0.98, $u_1 = 0.9$, $v_1 = 0.91$, $v_2 = 0.90$, $w_1 = 0.92$, $w_2 = 0.91$, and $w_3 = 0.90$.

The time domain inverse operators are applied to compute the acceleration, velocity, and displacement time traces. The time domain inverse of the zeros of the system response are cascaded by the denominator of the above expressions to produce acceleration, velocity, and displacement wavelets, valid between 0.25 and 5.0 Hz. Inbetween each stage, a shortpass cepstrum filter is applied to improve the statistical estimation of the seismic ground motion and to remove time terms longer than 3.2 seconds.

The smoothing operator, which is also a short pass cepstrum operator, was performed by forming a running average of the log spectrum. The method used to average was to use staged smoothing with binomial coefficients. The smoothed log amplitude follows as:

$$\operatorname{Log} A_{S}^{"}(k\Delta f) = 0.25 \left[2 \operatorname{Log} A_{S} (k\Delta f) + \operatorname{Log} A_{S} ((k-j) \Delta f) \right]$$

$$+ \operatorname{Log} A_{S} ((k+j) \Delta f) \right]$$

$$\phi_{S}^{"}(k\Delta f) = 0.25 \left[2 \phi_{S} (k\Delta f) + \phi_{S} ((k-j) \Delta f) + \phi_{S} ((k-j) \Delta f) \right]$$

$$+ \phi_{S} ((k+j) \Delta f) \right]. \qquad (II-15)$$

where the prime indicates the state of the data before smoothing; unprimed indicates the state after one stage of smoothing. By cascading the above operator and skipping [0,1,2...] points after each stage of smoothing, a Bartlett window is generated to smooth the log-spectrum. For example, after 1 stage the window weights are (1,2,1)/4; after 2 stages (1,2,3,2,1)/9; etc. The taper of the complex cepstrum (short pass operator) for the Bartlett window produced by I stages of smoothing is:

$$\prod_{i=1}^{I} \cos^2 i \frac{\pi}{2} \frac{n}{N}$$
 (II-16)

where n is the number of point delay of the complex cepstrum and N is the number of data points. It is desirable that the cepstrum taper be relatively flat up to at least 32 points delay (sampled at 0.05 seconds). To insure this condition, the output data was exponentially tapered; the velocity ground motion, $\exp(n/0.99)$; displacement ground motion, $\exp(n/0.98)$. The resultant attenuation of an M point delay operator (Z^{-M}) by smoothing and compensating with the exponential taper is shown in the following Table II-2.

The wavelets at delays less than the 32-point delay shown in the table are progressively closer to one as zero point delay is approached. It appears from these values that the displacement wavelet echoes can be

TABLE II-2
DISTORTION FIGURES DUE TO SMOOTHING THE LOG-SPECTRUM
WITH A BARTLETT WINDOW

Ü

Exponential Taper	:	Exp(0.99 n)	Exp(0.98 n)
Exp	1,1,	Exp(Exp
Number of Smoothing Stages	4	∞	12
128	0.72	0.42	0.19
80	0,88	1.00	1.09
64	0.98 0.92 0.88	1.22 1.14 1.00	1.51 1.41 1.09
32	0.98	1.22	1.51
M =	Acceleration	Velocity	Displacement

sized with reasonable accuracy up to about 4.0 seconds. This should be adequate for interpreting pP delays of explosions. For much longer delays, for example, due to multiple explosions, it may be necessary to use the acceleration or the velocity ground motion wavelet instead of the displacement wavelet. The Bartlett window used to smooth the above wavelets was determined experimentally as a requirement for containing the dominance of long-period peaks in the data, possibly due to noise. The effect of the smoothing is to statistically average out such long-period peaks over a broader band of frequencies.

2. Interactive Data Processing

a. Data Conditioning

In this phase of data processing (see Figure II-8), a seismic analyst scans a list of events and selects one for discrimination analysis. The wavelet is automatically corrected for absorption based on the parameter T/Q. The start time of the wavelet is picked. Offset of the initial point is automatically corrected. A taper is applied to avoid hard truncation of the data. The analyst is guided by displays of the wavelet and the real cepstrum of the wavelet.

The ABSORB algorithm corrects for values of T/Q using the prior described Strick model. The LOGFFT algorithm is as follows:

X₁ contains 128 points of data,

X₂ contains 128 points of log spectrum in multiplexed FFT format with imaginary part set equal to zero,

Log
$$\{FFT(X_1)\} \rightarrow X_2$$
, $R_e()$: real part of,
 $FFT^{-1}\{R_e(X_2)\} \rightarrow Y_1$, DISPLAY (X_1, Y_1) .

After examining the display for the desired start point of the signal, the analyst pushes the start time button and enters the number of points delay to start the wavelet. Any initial offset due to noise is automatically removed.

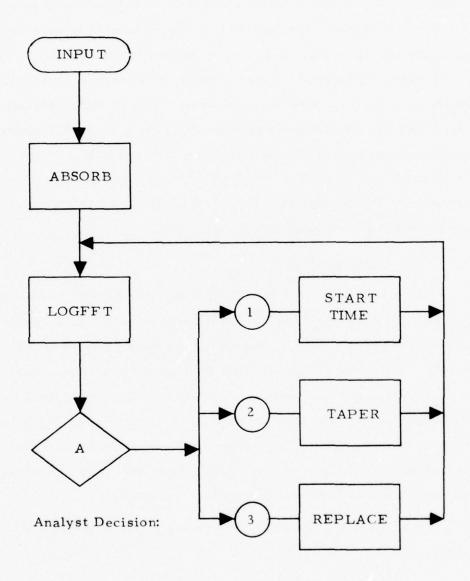


FIGURE II-8
DATA CONDITIONING

$$X(I) = X(I) - X(1) * (N - I + 1)/(N - 1).$$
 (II-17)

N is automatically taken as 64 with all subsequent operations being performed on 64 data points. If desired, the analyst may taper the data to remove abrupt truncations of the signal's coda. A record is kept of the number of times that the data is exponentially tapered. Later, provision is made to invert the taper and use cepstrum short pass filtering to remove unwanted later arrivals of energy. Upon exiting, the data are extended with zero's out to 128 points; and the real and imaginary part of the log-spectrum is saved in X_2 . From this point on, X_2 will be stored on disc and used in passing the wavelet through to the next subroutine. The replace button is used to recover an erroneous start time or taper within the data conditioning subroutine.

b. Separate Echo

In this phase (see Figure II-9), the selected data is deconvolved to remove the apparent echo which the analyst detects by inspection of the real cepstrum display. This is done by trial-and-error input of a reflection coefficient, scattering coefficient, and the time delay in data points. By pressing a load button, the echo is held while the first arriving signal log-spectrum is smoothed to short pass the signal. A second press of the load button passes through the echo which can be similarly smoothed. A third pass of the load button reconstructs the signal by adding the first arriving signal to the echo for visual comparison with the original data.

The algorithm IFTEXP displays the wavelet and the real cepstrum.

FFT⁻¹
$$\{ \text{Exp}(X_2) \} \longrightarrow X_1$$

FFT⁻¹ $\{ R_e(X_2) \} \longrightarrow Y_4$
DISPLAY (X_1, Y_4) .

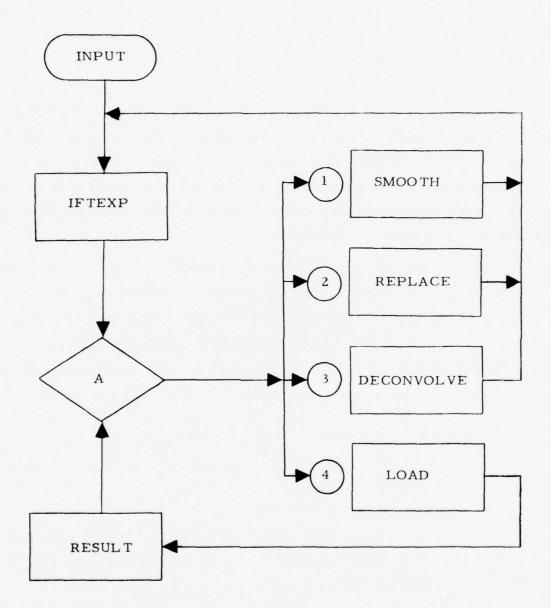


FIGURE II-9 SEPARATE ECHO

The first button pushed is DECONVOLVE which follows: Let y_i be the first arrival signal and x_i the input data:

where

$$y_i = a_1 y_{i-M-1} + a_2 y_{i-M} + a_1 y_{i-M+1} + x_i$$
 (II-18)
 $a_1 = RC * SC; a_2 = RC * (1 - 2*SC).$

SC is between 0.0 and 0.5. Given 0.0 an impulsive echo is removed by the algorithm. Given other values, a symmetrical multiple echo is removed. Such an effect would shape the cepstrum trough, e.g., a double echo or smoothed echo. The analyst can try any desired combination of delay time, M; reflection coefficient, RC; and scattering coefficient, SC, until the cepstrum trough is apparently removed.

The load algorithm stacks the data and echo while the analyst smoothes the first arrival signal; and similarly smoothes the echo. After leaving the deconvolution algorithm, the flag IK is set at -1. If IK >-1, the deconvolve algorithm is an automatic return to avoid analyst error. After exiting DECONVOLVE the data are stored on Z4, and the deconvolved signal is stored on X_1 , and its log-spectrum on X_2 . Then LOAD is entered:

LOAD: If IK>2, return

IL = 0

IK = IK + 1

If IK
$$\neq$$
 2 branch to (4)

 $Z_4 + X_1 \longrightarrow Z_1$ (Reconstruct data by adding the branch to (2). shortpassed signal and echo.)

(4) If IK = 1 branch to (1)

 $Z_4 - X_1 \longrightarrow Z_1$ (echo is data minus signal)

Log {FFT (Z_1) } $\longrightarrow Z_2$ (return)

 $z_2 \rightarrow z_1$

(3)

(2)
$$Z_3 \longrightarrow Z_2$$
 (Data in Z_2)

IL = IL + 1

(1)
$$Z_2 \longrightarrow X_2$$
 $Z_4 \longrightarrow Z_3$
 $X_1 \longrightarrow Z_4$
 $Z_1 \longrightarrow X_1$
IF (IL. EQ. 1) Go to 3 (return).

This LOAD algorithm automatically saves the data, deconvolved signal, and echo as they are generated and orders the data as follows: After first press of the LOAD button:

 $\begin{array}{rcl} {\rm IK} &=& 0 & Z_1; & {\rm original~data~minus~deconvolved~signal~(raw~echo)} \\ & & Z_2; & {\rm log~spectrum~of~}Z_1 \\ & & Z_4; & {\rm original~data} \\ & & X_1; & {\rm deconvolved~signal} \\ \end{array}$

X₂: log-spectrum of deconvolved signal

DISPLAY (Z_4, X_1, Z_1)

 $\begin{array}{rcl} {\rm IK} &=& 1 & {\rm X_2:} & {\rm log\text{-}spectrum\ of\ raw\ echo} \\ && {\rm Z_3:} & {\rm original\ data} \\ && {\rm Z_4:} & {\rm smoothed\ deconvolved\ signal} \\ \end{array}$

X₁: echo

DISPLAY (Z_3, Z_4, X_1)

IK = 2 Z₁: original data

Z₂: deconvolved signal

 Z_3 : echo

 Z_4 : deconvolved signal and echo

X1: original data

DISPLAY (Z_1, Z_2, Z_3, Z_4) .

When IK = 0, the deconvolved signal is smoothed to reduce reverberation errors and short pass the signal estimate. When IK = 1, the echo estimate is similarly smoothed. When IK = 2, the smoothed signal and echo are added to reconstruct the first phase and its echo. Also, the original data are stored on X_1 to prepare input to the next subroutine which computes the residual.

 Computation of the Residual Seismogram to Detect Multiple Events

The signal and echo of the first phase are combined to model the first arrival. This is subtracted from the original data. Any residual later phase left on the record can be picked by the analyst for possible subsequent analysis. The ratio of the removed first arrival signal to the residual is calculated from zero up to the start time picked for the possible later phase. This S/N ratio is displayed along with the possible later phase and its cepstrum. Also, here, the correlation between the signal and echo of the first phase is computed. If desired, the later phase can be stored on the disc for the next entry into SPEED and thus be analyzed as a later phase of the same event.

d. Invert Exponential Taper from the Signal Estimate

The deconvolved signal estimate is corrected for the exponential taper applied to the data in the data conditioning described in subsection a. This involves pressing the inverse exponential taper button until the number of tapers applied to the data are worked off. If roundoff errors blow up the data at long time delays, the analyst presses the zero button, inputting the number of points delay, after which the data are zeroed out to eliminate the largest roundoff errors. During the sequential inversion of the exponential taper, apparent coda noise may emerge in the tail of the signal. This can be removed by pressing the smooth button. A replace button is also available to recover from any single excessive push of any of the preceding buttons. After each

press of a button, the current state of the deconvolved signal and its cepstrum are displayed to control the next button push.

e. Absorption and Variable Frequency Magnitude Measurement

The variable frequency magnitude method of discriminating earthquakes and explosions is based on magnitude measurement at low frequency and high frequency. Explosions should be characterized by significantly lower magnitude at low frequency and higher magnitude at high frequency. First, the analyst is asked to select a low frequency, mid-band of frequencies, and high frequencies. After selecting or approving the pre-selected values, the log-amplitude versus frequency spectrum is displayed. An option is provided for picking any two frequency points and linearly extrapolating the spectrum either to the selected high or low frequency. This option is used on events only if the selected high or low frequency magnitude appears to be dominated by noise. A compute magnitude button returns a table showing the average mid-band log-amplitude, the difference between the low frequency magnitude and mid-band magnitude, and the difference between the high frequency magnitude and mid-band magnitude. Since the mid-band frequencies were selected to cover the expected peak frequency of seismometer records, the low and high frequency magnitude measurements can be approximated as the network averaged magnitude of the event as seen through the system response plus the difference magnitude at the high and low frequency, respectively.

Another processing option can be performed on the semi-log spectrum display by pressing a button for determining an absorption correction, T/Q. The amplitude spectrum of a signal with absorption is as follows:

 $Y(k\Delta f) = X(k\Delta f) Exp(-1/2(T/Q)k\Delta f)$ (II-19)

where T is the travel time, Q is the absorption coefficient, and T/Q is approximately constant for most events. The parameter T/Q is expected to be higher than normal for certain high absorption paths. Solving the above equation for the semi-log spectrum, $\text{Log } X(k\Delta f)$,

$$Log X(k\Delta f) = Log Y(k\Delta f) + 1/2(T/Q)k\Delta f.$$
 (II-20)

Rather than inputting T/Q, which is unknown, the analyst specifies whether T/Q is positive or negative. He then automatically receives a correction for T/Q = S, which produces a small rotation of the spectrum which is displayed for the analyst. After K pushes of the T/Q button, the analyst may observe that part of the spectrum is nearly flat and therefore the absorption correction is completed. At this point, the analyst exits or selects another option such as measure magnitudes, and the value of the T/Q correction is held as annotation. Entry back into condition data automatically corrects the data for absorption, and reduces the annotated T/Q back to zero. Multiple entries into condition data are taken into account in this way. In addition, the cumulative T/Q correction of the basic data is also accounted for in the annotation.

f. Corner Frequency Measurement

The semi-log spectrum display of the preceding module, corrected for absorption, is converted to a log-amplitude versus log-frequency display in this module. By picking by means of a cursor two frequencies to the left of a corner frequency and two frequencies to the right of a corner frequency, the intersection of the straight lines corresponding with each pair of points yields the corner frequency, log-amplitude of the corner frequency, and roll-off to the left and right of the corner frequencies. Up to four corner frequencies per phase can be computed in this way. Upon exiting this module, a table of corner frequencies, log-amplitudes, and roll-offs are displayed.

F. EXAMPLES OF HARDCOPY FROM SPEED

The Interactive Seismic Processing System (ISPS) provides an option to hardcopy intermediate results of processing. For the case of the SPEED module, some selected hardcopy is described and shown in Figure II-10, pages 1 through 11.

On page 1 of Figure II-10, the first time trace is a presumed explosion from Kazakh corrected for instrument response to approximate ground displacement from 0.3 to 5.0 Hz. The second time trace is the positive half real cepstrum obtained by transforming the log-amplitude spectrum into the time domain. Each hashmark on the cepstrum trace represents a delay of four points. A possible echo appears to be indicated on the seventh point. The top annotation indicates the event number, source location and origin time, magnitude, depth, station, channel and component number, station coordinates, arrival time, event azimuth and distance, and sample period. The second annotation line indicates that the event was exponentially tapered twice, started on the first point of input data, and the event amplitude. The last line 6 annotation labels the real cepstrum of the first phase picked and indicates the maximum amplitude of the trace.

On page 2 of Figure II-10, the first trace shows the displacement wavelet, the second trace shows the displacement wavelet with the pP echo apparently removed, and the third trace shows the echo. The peak amplitude of the deconvolved displacement wavelet is increased as expected, and one-sided as expected.

On page 3 of Figure II-10, the deconvolved wavelet and its cepstrum are shown. The second line of annotation shows the reflection coefficients of the pP echo, the scattering coefficient used to shape the echo, number of points delay, and amplitude.

On page 4, the deconvolved displacement wavelet was smoothed in the log-spectrum domain with a Bartlett window of five points (triangular half-width). This short passes the displacement wavelet as shown on trace 1. The cepstrum of the short passed displacement wavelet is shown on trace 2.

On page 5, the first time trace shows the displacement wavelet. The second time trace, the short passed deconvolved displacement wavelet. The third trace, the short passed echo. The fourth, the displacement data reconstructed by adding the short passed deconvolved wavelet to the short passed echo. Comparison of the reconstructed data and original data shows close correspondence. The amplitude of the reconstructed wavelet is down 50 nm or about 1% from the original data.

On page 6 of Figure II-10, the difference between the original data and reconstructed data is shown on trace 1. The maximum difference is 658 nm or about 12% of the maximum signal amplitude. The largest errors occur before the start of the signal, under the echo, and at the end of the data trace. Under the first arrival pulse, the error is much less, several percent. The second trace shows the cepstrum of the residual trace. The last line of annotation shows the correlation coefficient between the signal and echo as -0.988.

On page 7, the result of using a cursor to pick a possible later phase is shown. The first trace shows the later phase, the second, its cepstrum. The second line of annotation indicates that the later phase was time delayed 41 points and its maximum amplitude is 514 nm. The bottom line of annotation indicates a signal to noise ratio of 12.4 db based on power of the data compared to the power of the residual trace obtained by removal of the reconstructed data, computed up to the presumed arrival of the later phase. The so-called later phase was picked for demonstration purpose and is not considered a valid later phase.

On page 8 of Figure II-10, the short passed deconvolved wavelet is shown with the applied exponential taper inverted. The amplitude of the signal was increased from 4,560 nm to 6,420 nm. This is the best measurement of signal amplitude. The cepstrum is shown on the second trace. Small positive secondary delays are indicated with 4-point and 7-point delays. These can be seen on trace 1, the displacement first arrival wavelet, as possible small secondary arrivals as peaks with 4-point and 7-point delays, consistent with the cepstrum.

On page 9, the log-amplitude spectrum is plotted as a function of frequency. The vertical lines show on the left the low frequency used to compute low frequency magnitude. The two middle lines show the two frequencies for averaging mid-band magnitude. The right vertical line shows the frequency used to compute high frequency magnitude. The T/Q factor of zero indicates no absorption correction was applied to the input data. The bottom line shows smoothes equal to zero, indicating that the log-amplitude was not smoothed. The log-amplitude of 2.92 - 4.47 shows the range of log-amplitude in the plot, with base 10 logarithms.

On page 10, the semi-logarithm spectrum of the first arriving signal pulse is shown corrected for absorption using a T/Q equal to 0.225. The log-amplitude range has, of course, been narrowed by the absorption correction from 4.00 to 4.50. The absorption correction will, as expected, significantly increase the magnitude of the event. The average log-amplitude between 1.00 and 1.75 Hz is 4.37. The difference log-amplitude at 0.3 Hz is 0.13 magnitude units. The difference log-amplitude at 2.50 Hz is -0.03 magnitude units.

On page 11, the log-amplitude spectrum of the deconvolved displacement wavelet is plotted against the log-frequency from 0.45 Hz to 3.5 Hz. This plot includes the previous correction for absorption. The integers 1 and 2 next to the plot indicate where corner frequencies were picked. The

log-frequency from -0.35 to 0.55 indicates the log-frequency range of the horizontal axis, and the specification amplitude from 3.98 to 4.48 indicates the range of log-amplitudes on the vertical axis. The last four lines of annotation provides a table of corner frequency information. The corner frequencies for pick 1 and pick 2 are given under column 1 and column 2, respectively, in log base ten units. The magnitude at the corner frequencies is also given in log base ten units. The left slope indicates the power fa roll-off to the left of the corner frequency pick. The right slope, to the right of the corresponding corner frequency peak. The results for this event indicated a corner frequency at 2.4 Hz nearly flat to the left of the corner with roll-off of 1.8 power to the right of the corner. Another corner was picked at 2.9 Hz with roll-off of 3.0 power to the right of that corner. Sax (1975) indicated that measurements of log-amplitude and corner frequencies could be used to discriminate between earthquakes and explosions. In that study, maximum entropy spectral estimates were used. In this study, conventional discrete Fourier transforms were linearly interpolated at uniformly coupled log-frequencies after correcting for absorption, based on the assumption that at least part of the displacement wavelet spectrum is flat.

FIGURE II-10
PROCESS SPEED HARDCOPY
(PAGE 1 OF 11)

73 EXT

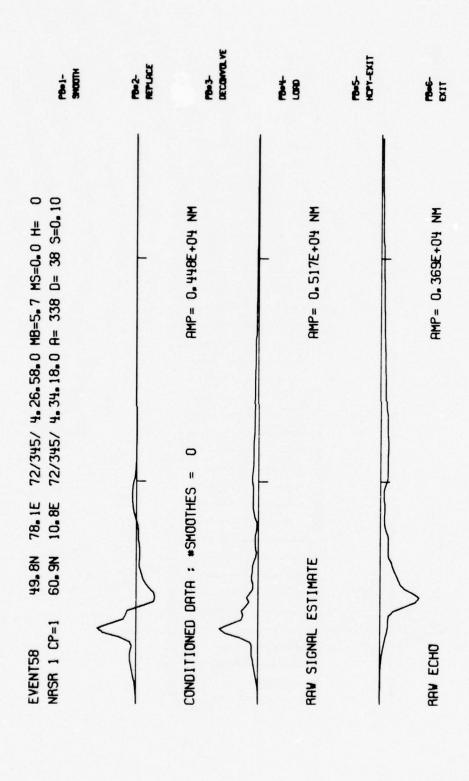


FIGURE II-10
PROCESS SPEED HARDCOPY
(PAGE 2 OF 11)

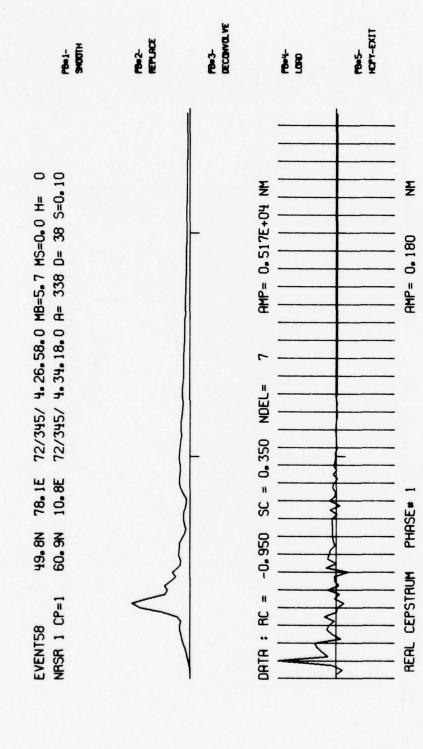


FIGURE II-10
PROCESS SPEED HARDCOPY
(PAGE 3 OF 11)

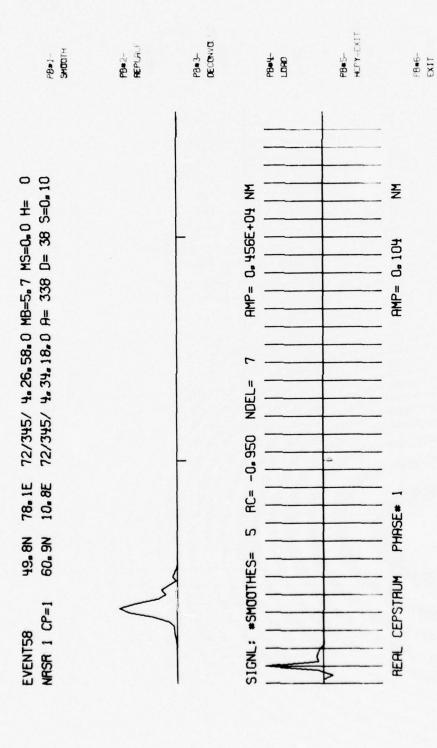
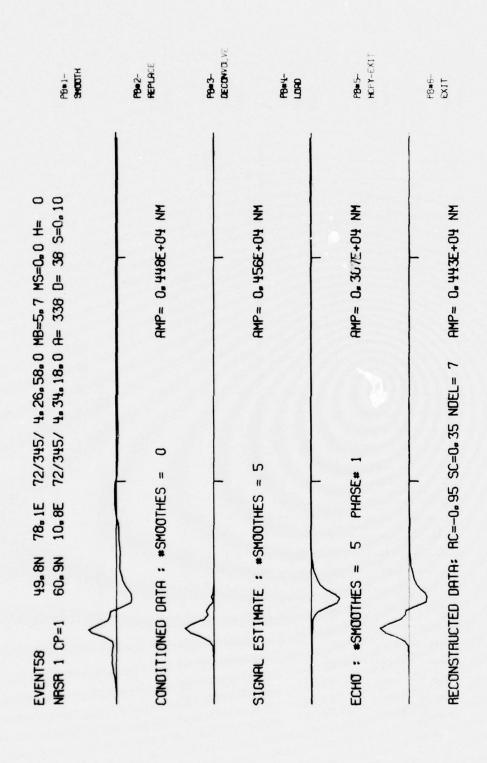
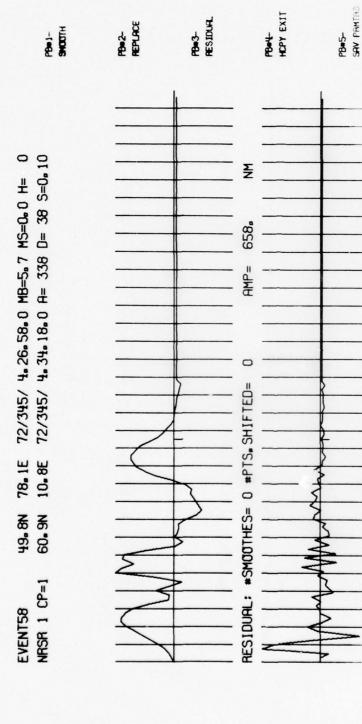


FIGURE II-10
PROCESS SPEED HARDCOPY
(PAGE 4 OF 11)



PROCESS SPEED HARDCOPY (PAGE 5 OF 11)

FIGURE II-10



(SIGNAL, ECHO) CORRELATION COEF = -0, 988E+00

FIGURE II-10

PROCESS SPEED HARDCOPY
(PAGE 6 OF 11)

P8#6-EXIT

Σ

AMP= 0,244

PHRSE# 2

REAL CEPSTRUM

(SIGNAL, ECHO) CORRELATION COEF=-0, 988E+00 SNR = 0, 124E+02 OB
FIGURE II-10
PROCESS SPEED HARDCOPY
(PAGE 7 OF 11)

8 8 F

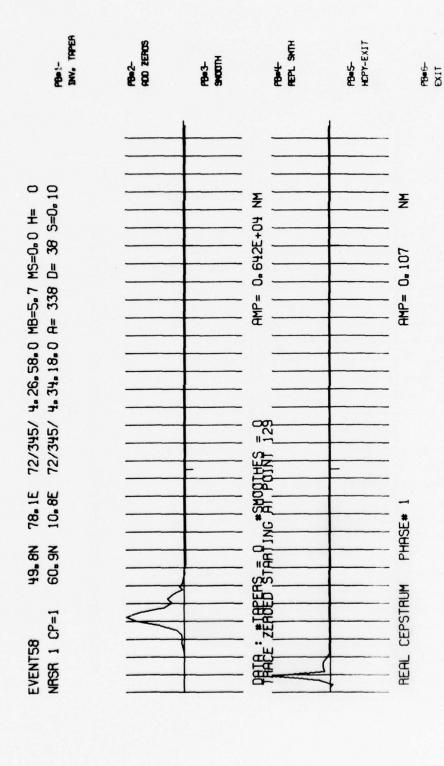
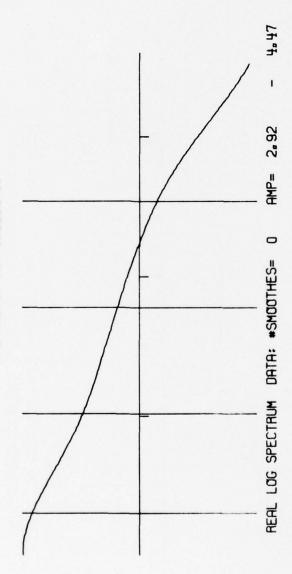


FIGURE II-10
PROCESS SPEED HARDCOPY
(PAGE 8 OF 11)

7

PHASE# 1 REAL SPECTRUM BETWEEN 0.00HZ AND 3.50HZ T/Q FACTOR IS 0.000E+00



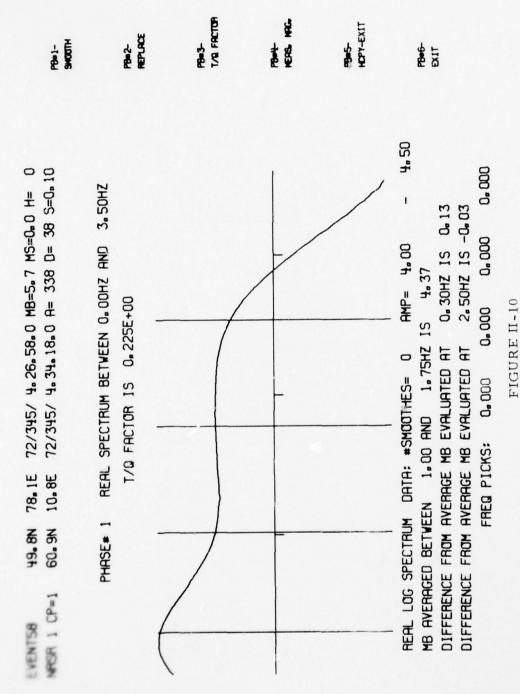
PB#3-T/G FACTUR

PB#2-REPLACE

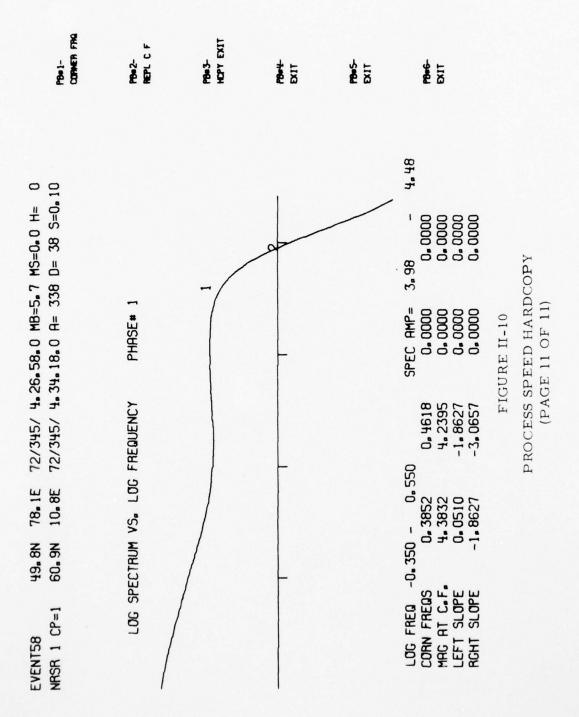
-1-9-1-3-000TH PORT MIC.

PD=5-HCPY-EXIT

FIGURE II-10
PROCESS SPEED HARDCOPY
(PAGE 9 OF 11)



PROCESS SPEED HARDCOPY (PAGE 10 OF 11)



SECTION III

EVALUATION OF ROUTINE DISCRIMINATION PROCESSING PROCEDURES

A. INTRODUCTION

In the context of a real time surveillance system environment, it is estimated that an average of fifty events per day will be collected. After each event is located, the retrieved station waveforms are time-aligned to measure accurate focal parameters and to measure accurate station parameters such as station magnitude and arrival time deviations, first motion sense, and other station parameters. The station waveforms are further reduced to one or several event waveform representations for routine discrimination processing. One of the possible reduction methods used is cepstrum beamforming, which reduces ambient and coda noise subject to the constraint that log-amplitude spectrum of the estimates source signal is the average of all the input channels fed into the cepstrum beamforming process. The algorithm used to compute the cepstrum beamforming data is described in the preceding section.

The discrimination processing performed on data collected in a real time surveillance mode must all be done with sufficient speed to keep up on an average with the event load collected by the system. This means that all routine discrimination processing must be done in less than one-half hour. This provides sufficient event processing capacity to work off backlogs due to occasional swarms of events in a reasonable span of time.

For the purpose of quickly evaluating proposed standards of short-period discrimination processing, a data base of thirty-five events was prepared. The data base consisted of twenty earthquakes and fifteen presumed explosions. All events were selected in the teleseismic range from 25 degrees to 85 degrees epicentral distance. Two classes of earthquakes were selected. In one class labelled as simple earthquakes, the events were impulsive with the maximum peak occurring in the first several seconds. In the other, labelled as complex earthquakes, the maximum peak occurs later than the first several seconds. Earthquake events were assigned to these groupings to equally weight earthquake results for simple and complex events and, if possible, differentiate results obtained for these two groupings. The magnitudes of events selected for the data base nearly uniformly cover the range from 4.5 to 6.0 for all classes of events: simple earthquakes, complex earthquakes, and presumed explosions. All earthquakes selected were shallow focus where determined or otherwise of indicated normal depth (33 km). The presumed explosion data included twelve events from the eastern Kazakh region, including two presumed PNE's; two events from NTS; and one from Colorado. All the data used were recorded at NORSAR on twenty-two subarrays. All the data preparation and interactive processing were performed starting at the level of 132 individual sensor records and working down to the level of the several event waveform representations used for discrimination processing. The processing procedures developed, when perfected, could be adapted to processing a sizeable network of sensors within the time constraints imposed by the requirement for real time rate event classification processing.

The purpose of the data base is to provide preliminary screening of the effectiveness of discrimination methodologies which are possible candidates for routine on-line discrimination processing. Although the screening procedure should quickly eliminate discrimination procedures which perform poorly, any positive results should be further tested with a much larger data base before acceptance of the procedure is finalized. A description of the earthquake event information is shown in Table III-1; of the presumed explosion data, in Table III-2.

TABLE III-1 EARTHQUAKE DATA BASE (PAGE 1 OF 2)

-	Distance	0	Azimuth Latitud	Latitude	Latitude Longitude	Date	Origin
(km)	\rightarrow	(degrees)		(N ₂)	(~E)		Time
10	27	25.1	155.4	37.1	24.0	02/13/72	02/13/72 13:07:10.5
_	z	32.7	116.6	38.1	49.1	05/15/71	05/15/71 04:53:05.5
Z	-	59.4	77.1	32.6	95.8	07/16/72	03:40:00.0
Z		56.2	162.9	56.2	162.9	07/31/72	07/31/72 06:40:28.0
Z		49.5	87.3	35.8	9.08	07/24/72	07/24/72 15:06:19.8
17		44.5	83.3	41.3	79.3	07/03/71	07/03/71 04:33:49.1
16		55.4	87.7	30.8	84.5	05/03/71	05/03/71 00:42:13.3
20		65.3	23.3	50.4	156.8	08/01/71	08/01/71 02:16:04.1
28		0.92	40.0	35.0	141.2	01/20/75	01/20/75 17:31:10.6
59		65.3	35.0	46.7	141.4	12/90/60	09/06/71 13:37:11.0

N - Not Given.

TABLE III-1 EARTHQUAKE DATA BASE (PAGE 2 OF 2)

			Col	Complex Earthquakes	thquakes			
Event Number	Magnitude	Depth (km)	Distance (degrees)	Azimuth	Latitude (^o N)	Longitude (^O E)	Date	Origin Time
26	4.5	6	24.8	143.0	39.0	29.8	10/05/71	10/05/71 18:53:06.0
17	4.8	Z	61.6	16.9	55.6	163.9	01/12/72	01/12/72 20:20:15.0
20	5.0	Z	48.1	88.2	36.5	78.5	08/29/71	08/29/71 15:16:56.0
0.1	5.1	55	63.9	19.7	52.8	160.8	06/15/71	06/15/71 14:04:08.0
02	5.2	Z	44.1	84.0	41.5	78.3	06/19/71	06/19/71 17:23:02.0
55	5.4	31	40.4	121.0	30.1	50.8	07/02/72	07/02/72 12:56:07.0
38	5.5	23	44.9	86.2	31.4	91.5	02/11/72	02/11/72 05:55:46.0
68	5.7	7	74.3	48.5	33.2	131.3	04/20/75	04/20/75 17:35:50.4
06	5.8	24	74.3	38.5	37.1	142.1	05/04/75	05/04/75 09:31:59.5
22	0.9	7	6.69	29.5	44.4	150.9	09/09/71	09/09/71 23:01:06.0

N - Not Given.

TABLE III-2 PRESUMED EXPLOSION DATA BASE

	THE RESERVE AND ADDRESS.														
Origin Time	01:02:58.0	03:56:57.6	05:59:56.9	08: 56: 58.0	03:16:57.2	02:59:57.2	01:59:58.0	16:00:00.0	03:56:57.2	04:02:57.1	14:00:00.0	15:05:00.2	04:26:57.7	15:00:00.0	04:27:08.4
Date	07/06/72	06/25/74	12/07/74	09/02/72	08/16/72	09/13/73	08/15/73	05/17/73	06/30/71	06/06/71	07/08/71	07/26/74	12/10/72	08/30/74	12/10/72
Longitude (°E)	78.0	78.1	77.6	77.7	78.1	6.79	67.4	-108.4	79.1	77.7	-116.0	-116.0	78.1	-116.0	78.8
Latitude (ON)	49.7	49.9	49.9	50.0	49.8	45.6	42.7	39.8	50.1	50.0	37.1	37.2	49.8	37.2	50.1
Azimuth	76.0	75.7	0.97	75.9	75.8	88.8	95.6	313.9	74.7	75.9	318,4	318,4	75.8	318.4	74.9
Distance (degrees)	37.8	37.2	37.5	37.4	37.8	35.8	37.7	68.0	38.0	37.4	73.0	72.9	37.8	72.9	37.9
Depth (km)	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
Magnitude	4.4	4.7	4.7	5.1	5, 2	5.2	5.3	5.4	5.4	5.5	5.5	5.6	5.7	5.8	6.0
Event	99	77	16	46	51	32 *	* 09	65	7	13	15	81	58	111	53

* Presumed PNE.

On Figure III-1, plots are shown of the representative event waveforms obtained by cepstrum beamforming. The waveforms are shown as seen through the system response and as corrected for ground motion (acceleration, velocity, displacement as specified by the user) in the band of frequencies between 0.25 and 5.0 Hz.

B. BASELINE FOR SHORT-PERIOD DISCRIMINATION PROCESSING

In Section II, an example of the application of short-period interactive processing was shown. In the example, it was possible with very little ambiguity to use the cepstrum to deconvolve an apparent echo to derive the expected one-sided displacement wavelet and echo with correlation coefficients close to unity. However, in attempting to repeat the performance on all the events in the screening data base, it was no longer found to be possible to consistently and unambiguously use the cepstrum to deconvolve an apparent highly correlated echo as in the example. To develop a satisfactory procedure for routine discrimination processing, a baseline procedure will be defined. The procedure will be run through the screening data base to establish performance figures for the baseline procedure. By systematically evolving procedures which can be shown to perform more effectively than the baseline procedure, a satisfactory procedure for discrimination processing can eventually be developed. The interactive SPEED program is a useful research tool for this purpose. By specifying a processing procedure, the entire screening data base can be run in two or three hours to provide basic data for preliminary evaluation of the procedure.

The procedure followed to establiah a baseline for discrimination was to measure variable frequency magnitude data on seismic data corrected for system response to ground displacement and ground acceleration.

All the event data were processed as follows:

DISPLACEMENT (C = Complex Earthquakes, S = Simple Earthquakes, X = Presumed Explosions) VELOCITY FIGURE III-1 ACCELERATION EVENT SEISMIC RESPONSE 13 X ڡ

PLOTS OF WAVEFORMS OBTAINED BY CEPSTRUM BEAMFORMING

(PAGE 1 OF 5)

III-7

FIGURE III-1 20 C 16 X 21 S 15 X

PLOTS OF WAVEFORMS OBTAINED BY CEPSTRUM BEAMFORMING (PAGE 2 OF 5)

DISPLACEMENT (C = Complex Earthquakes, S = Simple Earthquakes, X = Presumed Explosions) VELOCITY **ACCELERATION** EVENT SEISMIC RESPONSE 38 C 30 S 31 S 32 X 44 5 26 C

PLOTS OF WAVEFORMS OBTAINED BY CEPSTRUM BEAMFORMING (PAGE 3 OF 5)

FIGURE III-1

PLOTS OF WAVEFORMS OBTAINED BY CEPSTRUM BEAMFORMING (PAGE 4 OF 5)

DISPLACEMENT VELOCITY **ACCELERATION** EVENT SEISMIC RESPONSE

(C = Complex Earthquakes, S = Simple Earthquakes, X = Presumed Explosions)

FIGURE III-1 ວ 88 87 S X 09 81 × 59 X

PLOTS OF WAVEFORMS OBTAINED BY CEPSTRUM BEAMFORMING (PAGE 5 OF 5)

The displacement data of each event were contained in a 6.4 second time window. The data were tapered by exp(-0.01 t) to increasingly weight the data at the start of the signal and to reduce discontinuities at the end of the data sample. The log spectrum of the data was smoothed with a Bartlett window (0.11, 0.22, 0.33, 0.22, 0.11). After transforming back to the time domain, the applied taper was inverted by applying the inverse exponential taper exp (+0.01 t) to the data. The low frequency magnitudes were measured at 0.3, 0.4, and 0.5 Hz. The high frequency magnitudes were measured at 2.5, 3.0, and 4.0 Hz. The center band magnitudes were averaged from 0.75 Hz to 1.75 Hz. The acceleration wavelet of each event was contained in a 3.2 second time window. The data were tapered by exp(-0.02 t). The same Bartlett window was applied. The same frequencies were measured with additional high frequencies measured at 5.0, 6.0, and 8.0 Hz. No subjective measurements of echo delays, deconvolution, or absorption corrections have been applied to the data for this baseline procedure. In future developments, such procedures could be applied, but only if significant gains over the baseline results can be expected.

C. RESULTS OF BASELINE DISCRIMINATION PROCESSING

1. Magnitude from Spectrum Measurement

The average log amplitude measurements between 1.0 and 1.75 Hz are related to network magnitude estimates, $m_{\rm hs}$, as follows:

For displacement log amplitudes:

$$m_{bs} = \log D + 1.353 \log \sin \Delta + 1.993$$
 (III-1)

For acceleration log amplitudes:

$$m_{bs} = \log A + 1.353 \log \sin \Delta + 2.77$$
 (III-2)

where

- D = logarithm of the displacement spectral amplitude averaged between 1.00 and 1.75 Hz
- Δ = epicentral distance in degrees
- A = logarithm of the acceleration spectral amplitude averaged between 1.00 and 1.75 Hz.

The constants 1.353, 1.993, and 2.77 were obtained from the data by least squares regression of the data. The results are shown on Figure III-2. For all events, the standard deviation between computed and world-wide network magnitudes was 0.27 for magnitudes computed from average log displacement amplitude and 0.21 for magnitudes computed from average log acceleration amplitude. In the latter case, three anomalously low magnitudes (about one magnitude unit) were computed using acceleration data. This occurred with three earthquakes: events 38, 55, and 89. The result was probably due to nodes in the radiation pattern causing an observed hole in the spectrum at less than 1.75 Hz. The computation of magnitude from displacement amplitude data for these events was also low but by less than 0.5 magnitude units due to heavier weighting of amplitudes at the 1.0 Hz end of the range, which are frequencies lower than the observed hole in the spectrum.

The lower standard deviation of magnitude measurements from log acceleration amplitude measurements is probably due to the fact that the maximum peak-to-peak amplitude through the system response corresponds more closely to ground acceleration than to ground displacement. Based on source theory, the sealing of magnitude as the square root of energy requires that both the log-displacement amplitude and corner frequency be used to estimate magnitude from spectrum. It is possible that the standard deviation of magnitudes computed from ground displacement can be further reduced by such scaling.

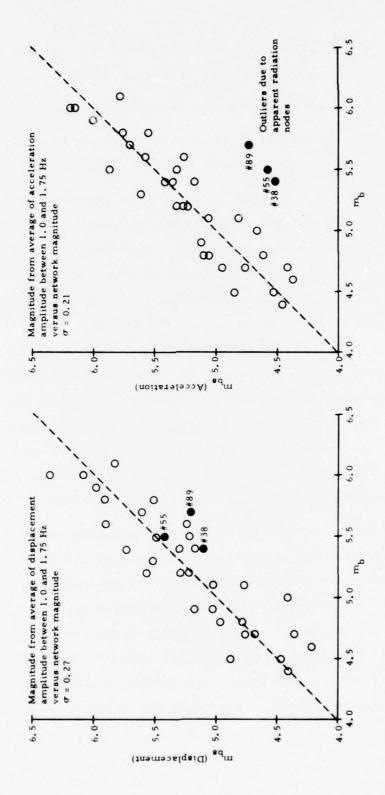


FIGURE III-2 MAGNITUDES COMPUTED FROM SPECTRA

2. Low Frequency and High Frequency Magnitude Measurements

the preceding section, it was shown that network magnitude of the events could be reasonably well estimated by averaging log spectrum measurements between 1.0 Hz and 1.75 Hz. In order to statistically compare low frequency and high frequency magnitude measurements of events of different magnitude, the average magnitude between 1.0 and 1.75 Hz was subtracted from the low frequency magnitude and high frequency magnitude measurements. These variable frequency magnitude differences are shown in Table III-3.

The following are definitions of column headings used in Table III-3 and other tables:

- Log D_{M} average log displacement amplitude between 1.0 and 1.75 Hz.
- M(0.3) log displacement amplitude at 0.3 Hz minus Log D_M.
- M(0.4) log displacement amplitude at 0.4 Hz minus Log D_M.
- M(0.5) log displacement amplitude at 0.5 Hz minus Log D_M.
- M(2.5) log displacement amplitude at 2.5 Hz minus Log D_M.
- M(3.0) log displacement amplitude at 3.0 Hz minus Log D_M.
- M(4.0) log displacement amplitude at 4.0 Hz minus Log D_M.
- γ (0.3) log log spectrum rolloff between 0.3 and 0.4 Hz.
- γ (0.4) log log spectrum rolloff between 0.4 and 0.5 Hz.
- γ (2.5) log log spectrum rolloff between 2.5 and 3.0 Hz.
- $\gamma(3.0)$ log log spectrum rolloff between 3.0 and 4.0 Hz.
- \bullet Log A_{M} average log acceleration given for reference only.

TABLE III-3
VARIABLE FREQUENCY MAGNITUDE
(PAGE 1 OF 2)

Log A _M		2.36		2.81						3.07			2.59	2.57	28.2	2.01	2.08
γ (3.0)		-9.68 -3.84		-1.12		-				-0.56					-8.48		
γ (2.5)	-6.69	-3.79	-2.65	-3.91	-1.26	-0.76	-4.80			-8.97					-0.88		
γ (0.4)	41	2.06	03	1.86						0.62					-0.93		
γ (0.3)	0.16	2.24	1.28	3.20 0.16				0.48	00.00	1.20	1.28	0.24	1.28	2.00	0.72	2.32	0.88
M (4.0)		-2.38 -1.48		-1.13						-2.58			-1.95	-2.47	-1.68	-2.68	-1.97
M (3.0)		-1.17		-0.99				-1.64	-1.10	-2.51	-1.50	-1.87	-1.65	-1.41	-0.62	-1.24	-1.00
M (2.5)		-0.87		-0.92						-1.80			-1.41	-1.13	-0.55	-0.94	-0.60
M (0.5)		0.34		1.42						0.95					0.70		
M (0.4)	0.88	0.14	0.66	0.19						0.89					0.79		
M (0.3)	0.86	-0. 14 1. 15	0.50	0.84	99.0	1.06	0.93	1.51	1.53	0.74	0.56	1.01	0.72	0.37	0.70	0.36	0.86
$\frac{\rm Log}{\rm D_{\rm M}}$	3.09	3.96	3.58	3.84				2.86					3.39				
Event Number	01	04	20	113	14	15	16	17	20	2.1	22	97	30	31	32	38	44

M = spectral magnitude levels

 $\gamma = \log \log \operatorname{spectral slope}$

TABLE III-3
VARIABLE FREQUENCY MAGNITUDE
(PAGE 2 OF 2)

Log A _M	2. 40 2. 34 2. 84 3. 67		3. 22 2. 45 3. 14	1. 99 2. 53 3. 26 1. 99 3. 01	1 1 1
γ (3.0)	-1.36 1.20 -3.52 -6.24		-5.44 -1.84 -11.04	-8.96 2.88 -0.12 -0.44	
γ (2.5)	-4.42 -10.22 -2.65 -1.76	.4. 04 -6. 44 1. 11	5.30 -6.69 -4.67	-4.67 -4.04 -1.51 -5.56	4. 1. 4. 1.
γ (0.4)	-0.41 -1.54 0.21 1.85	65 21 51	0.72	-0.83 1.75 -0.21 0.41	-0.10 1.02 -0.10
y (0.3)	1.36 0.00 0.80 2.80		1.68 1.52 1.44	0.64 2.40 1.44 1.20	
M (4.0)	-1.77 -1.01 -1.22 -1.56		-1.28 -1.68 -2.51	-1.39 -1.43 1.65 -2.20	
M (3.0)	-1.60 -1.16 -0.78	1.04	0.60 -1.45 -1.13	-0.27 -1.79 -1.56 -2.14	
M (2.5)	-1.25 -0.35 -0.57		-0.18 -0.92 -0.76	0.10 -1.47 -1.44 -1.70	-1, 12 0, 37 -0, 36 -1, 27
M (0.5)	0.78 0.99 0.45 0.73		0.81 0.86 0.67	1. 19 1. 37 1. 23 1. 08 1. 13	0.92 0.27 0.77 1.37
M (0, 4)	0.82 1.14 0.43 0.55		0.91	1.27 1.20 1.25 1.12	
M (0.3)	0.65 1.14 0.33 0.20	1.18	0.53	1.19 0.90 1.07 0.97 0.83	
Log D _M	3.08 3.07 3.59 4.38		3.90 3.21 3.81	2.66 3.27 3.99 3.23 3.23	
Event Number	48 49 51 53	55 56 57	58 59 60	77 81 87 89	MEAN (Q) SD (Q) MEAN (X) MEAN (N)

Q = earthquakes; X = central Asia presumed explosions; N = western U.S.A. presumed explosions γ = log log spectral slope M = spectral magnitude levels

Positive values of the γ 's indicate increasing amplitude with frequency; negative, decreasing. Multiplication of the γ 's by 6.0 would indicate measured dB/octaves on a log amplitude versus log frequency plot of the spectrum. Thus the statistics in Table III-3 characterize the high and low frequency spectrum by levels and slopes of the log log spectral plot of the event. The procedure used to generate Table III-3 was standardized. Several of the events were run several times; the results were reproducible. At the end of Table III-3, the MEAN (Q) represents the average earthquake spectrum statistics; MEAN (X), average of central Asia presumed explosions (excluding event 60 as an outlier); and MEAN (N), average western United States presumed explosions (excluding event 59 as an outlier). SD(Q) is the estimate of the standard deviation of the representative earthquake population. In the western United States presumed explosion population, event 59 was cast out from the mean as an outlier, as was event 60, from the central Asian population.

A special case for application of the event spectral discrimination measurements is to plot the low frequency magnitude, m_L , versus the high frequency magnitude, m_H , where

$$m_L = m_B + M(0.3)$$

and

$$m_{H} = m_{B} + M(4.0).$$
 (III-3)

The results are shown on Figure III-3.

3. Multivariate Spectral Discrimination

The variable frequency magnitude data (see Table III-3) are transformed into detectability data. The measurement vector:

$$\underline{X}$$
; [M(0.3), M(0.4), M(0.5), M(2.5), M(3.0), M(4.0), $\gamma(0.3)$, $\gamma(0.4)$, $\gamma(2.5)$, $\gamma(3.0)$] (III-4)

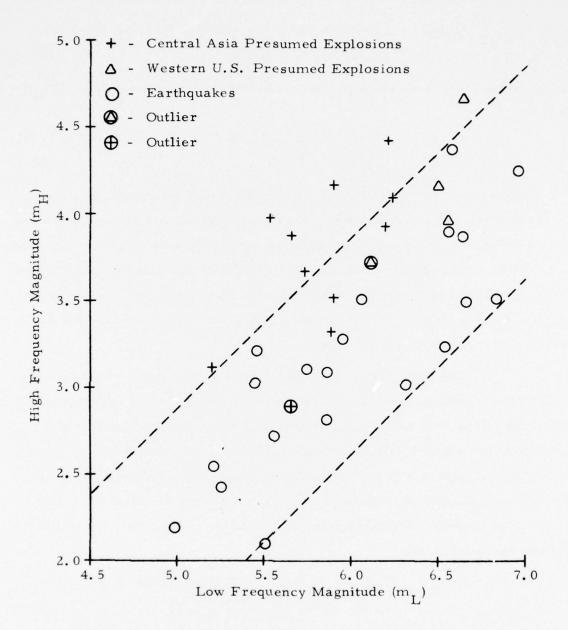


FIGURE III-3
VARIABLE FREQUENCY MAGNITUDE DISCRIMINATION PLOT

has subtracted from it the mean of the earthquake population $E_{Q}(\underline{X})$, where:

$$E_{Q}(\underline{X})$$
 ; [0.79, 0.93, 0.92, -1.12, -1.54, -2.02, 1.20, -0.10, -4.50, -3.12] , (III-5)

and is divided by the standard deviation of the earthquake population, $SD_{\overline{Q}}(\underline{X})$, where:

$$SD_{\mathbb{Q}}(\underline{X})$$
; [0.41, 0.35, 0.27, 0.37, 0.41, 0.41, 0.61, 1.02, 1.82, 2.31]. (III-6)

For earthquakes, the detectability is a unit normal Z-statistic. The mean $\gamma(2.5)$ and $\gamma(3.0)$ were taken at the 50 percent levels, and the standard deviations were computed by weighting positive deviations only which are most relevant for discrimination. Obtaining \underline{X} from Table III-3 and using the above values for $\underline{E}_Q(\underline{X})$ and $\underline{SD}_Q(\underline{X})$, detectabilities were computed for all 35 events as $(X - \underline{E}_Q(\underline{X}))/\underline{SD}_Q(\underline{X})$ with the results shown on Table III-4, for the earthquake and presumed explosion data.

The information contained in Table III-4 is the basic data for designing an optimum least squares multivariate discrimination process using measures of spectral levels and spectral rolloffs. Each component of the earthquake detectability, \underline{D}_Q , in Table III-4 is theoretically a unit variance, zero mean, Gaussian statistic. Each component of one or more presumed explosion populations is possibly detectable as a large variation from the mean. For example, the mean detectability of the central Asian presumed explosion population is:

$$E(\underline{D}_{X})$$
; [-0.34, -0.42, -0.57, 2.05, 2.04, 1.66, -0.25, -0.08, 0.10, -0.84]. (III-7)

The dominant statistics are significantly elevated high frequency spectral levels. Low frequency levels tend to be consistently lower than earthquakes, and the rolloff between 3.0 and 4.0 Hz is steeper than earthquakes. The mean detectability for western United States presumed explosions is:

TABLE III-4
DETECTABILITY DATA
(PAGE 1 OF 2)

r (0.3) (0.4) (0.5) (2.5) (3.0) (4.0) (0.3) 0.17 -0.14 -0.30 1.46 1.05 0.51 -1.70 -0.32 -0.29 -0.33 0.41 -0.88 -0.22 0.25 -2.27 -2.26 -2.15 0.68 0.90 -3.07 1.70 0.88 1.06 1.19 0.86 1.32 1.32 1.30 0.00 -0.71 -0.77 -0.59 2.32 2.61 1.95 0.03 -0.71 -0.77 -0.59 2.32 2.61 1.95 0.13 -1.51 -2.11 -2.81 1.89 1.98 1.00 1.70 -0.32 -0.14 -0.07 -1.59 -0.66 0.32 0.92 0.66 1.00 1.52 -0.78 0.17 1.17 0.92 0.54 0.26 -0.06 1.65 1.59 2.17 -0.79 1.80 1.71 <td< th=""><th>Event</th><th>Σ</th><th>×</th><th>Z</th><th>Z</th><th>×</th><th>M</th><th>^</th><th>٨</th><th></th><th>~</th></td<>	Event	Σ	×	Z	Z	×	M	^	٨		~
0.17 -0.14 -0.30 1.46 1.05 0.51 -1.70 -0.32 -0.29 -0.33 0.41 -0.88 -0.22 0.25 -2.27 -2.26 -2.15 0.68 0.90 -3.07 1.70 0.88 1.06 1.19 0.86 1.32 1.32 0.00 -0.71 -0.77 -0.59 2.32 2.61 1.95 0.03 0.12 0.89 1.85 0.54 1.34 2.17 3.28 -1.51 -2.11 -2.81 1.89 1.00 -1.70 -0.32 -0.14 -0.07 -1.59 -0.66 0.32 0.92 0.66 1.00 1.52 -0.78 0.17 1.17 0.92 0.33 0.26 -0.26 1.65 1.65 1.59 2.17 -0.79 1.76 1.49 1.26 0.38 -0.24 0.59 -2.75 1.80 1.71 1.70 1.05 1.07 0.66 -1.97 -0.12 -0.11 0.11 -1.84	Number	(0.3)	(0.4)	(0.5)	(2.5)	(3.0)	(4.0)	(0.3)	(0.4)	(2.5)	(3.0)
-0.32 -0.29 -0.33 0.41 -0.88 -0.22 0.25 -2.27 -2.26 -2.15 0.68 0.90 -3.07 1.70 0.88 1.06 1.19 0.86 1.32 1.32 1.70 -0.71 -0.77 -0.59 2.32 2.61 1.95 0.03 0.12 0.89 1.85 0.54 1.34 2.17 3.28 -1.51 -2.11 -2.81 1.89 1.98 1.00 -1.70 -0.32 -0.14 -0.07 -1.59 -0.66 0.32 0.92 0.66 1.00 1.52 -0.78 0.17 1.17 0.92 0.33 0.26 -0.26 1.65 1.59 2.17 -0.79 1.76 1.49 1.26 0.38 -0.24 0.59 -2.75 1.80 1.71 1.70 1.05 1.07 0.66 -1.97 -0.12 -0.11 0.11 -1.84 -2.37 -1.37 0.00 -0.56 -0.60 -0.52 -0.51	[0		-0.14	-0.30	1.46		0.51	-1.70	-0.30	-1.20	-1.11
-2.27 -2.26 -2.15 0.68 0.90 -3.07 1.70 0.88 1.06 1.19 0.86 1.32 1.32 0.00 -0.71 -0.59 2.32 2.61 1.95 0.013 -0.71 -0.59 2.32 2.61 1.95 0.013 -1.51 -2.11 -2.81 1.89 1.98 1.00 -1.70 -0.32 -0.14 -0.07 -1.59 -0.66 0.32 0.92 0.66 1.00 1.52 -0.78 0.17 1.17 0.92 0.33 0.26 -0.26 1.65 1.59 2.17 -0.79 1.76 1.49 1.26 0.38 -0.24 0.59 -2.75 1.80 1.71 1.70 1.05 1.07 0.66 -1.97 -0.12 -0.11 0.11 -1.84 -2.37 -1.37 0.00 -0.56 -0.60 -0.52 -0.51 0.06 -0.93 -1.57 -0.17 -0.14 -0.30 -0.65 -0.93 -0.93<	2 0		-0.29	-0.33	0.41		-0.22	0.25	0.10	-3.98	0.62
0.88 1.06 1.19 0.86 1.32 1.32 0.00 -0.71 -0.77 -0.59 2.32 2.61 1.95 0.13 -0.12 0.89 1.85 0.54 1.34 2.17 3.28 -1.51 -2.11 -2.81 1.89 1.98 1.00 -1.70 -0.32 -0.14 -0.07 -1.59 -0.66 0.32 0.92 0.66 1.00 1.52 -0.78 0.17 1.17 0.92 0.33 0.26 -0.26 1.65 1.59 2.17 -0.79 1.76 1.49 1.26 0.38 -0.24 0.59 -2.75 1.80 1.71 1.70 1.05 1.07 0.66 -1.97 -0.12 -0.11 0.11 -1.84 -2.37 -1.37 0.00 -0.56 -0.60 -0.52 -0.51 0.01 -0.13 0.05 -0.74 -0.94 -0.65 -0.08 <td< td=""><td>3 6</td><td></td><td>-2. 26</td><td>-2.15</td><td>0.68</td><td></td><td>-3.07</td><td>1.70</td><td>2.12</td><td>0.39</td><td>-2.83</td></td<>	3 6		-2. 26	-2.15	0.68		-3.07	1.70	2.12	0.39	-2.83
-0.71 -0.59 2.32 2.61 1.95 0.13 -0.12 0.89 1.85 0.54 1.34 2.17 3.28 -1.51 -2.11 -2.81 1.89 1.98 1.00 -1.70 -0.32 -0.14 -0.07 -1.59 -0.66 0.32 0.92 0.66 1.00 1.52 -0.78 0.17 1.17 0.92 0.33 0.26 -0.26 1.65 1.59 2.17 -0.79 1.76 1.49 1.26 0.38 -0.24 0.59 -2.75 1.80 1.71 1.70 1.05 1.07 0.66 -1.97 -0.12 -0.11 0.11 -1.84 -2.37 -1.37 0.07 -0.56 -0.60 -0.52 -0.51 0.10 -0.13 0.13 -0.56 -0.60 -0.52 -0.51 0.09 -0.93 -1.57 -0.17 -0.14 -0.30 -0.78 -0.27 0.17 0.13 -1.02 -0.40 -0.81 1.54 2.24<	* 90		1.06	1.19	0.86		1.32	00.0	-0.51	1.09	-0.31
0.12 0.89 1.85 0.54 1.34 2.17 3.28 -1.51 -2.11 -2.81 1.89 1.98 1.00 -1.70 -0.32 -0.14 -0.07 -1.59 -0.66 0.32 0.92 0.66 1.00 1.52 -0.78 0.17 1.17 0.92 1.76 1.49 1.26 0.38 -0.24 0.59 -2.75 1.80 1.71 1.70 1.05 1.07 0.66 -1.97 -0.12 -0.11 0.11 -1.84 -2.37 -1.37 0.00 -0.56 -0.60 -0.52 -0.51 0.10 -0.17 0.13 0.54 0.31 -0.04 -0.65 -0.80 -0.93 -1.57 -0.10 -0.17 -0.14 -0.30 -0.78 -0.27 0.17 0.13 -0.22 -0.40 -0.81 1.54 2.24 0.83 -0.79 -1.05 -0.80 -0.81 0.49 0.73 -1.61 1.84 -1.05 -0.80 -0.	07		-0.77	-0.59	2.32		1.95	0.13	1.11	1.02	-1.25
-1.51 -2.11 -2.81 1.89 1.98 1.00 -1.70 -0.32 -0.14 -0.07 -1.59 -0.66 0.32 0.92 0.66 1.00 1.52 -0.78 0.17 1.17 0.92 0.33 0.26 -0.26 1.65 1.59 2.17 -0.79 1.76 1.49 1.26 0.38 -0.24 0.59 -2.75 1.80 1.71 1.70 1.05 1.07 0.66 -1.97 -0.12 -0.11 0.11 -1.84 -2.37 -1.37 0.00 -0.56 -0.60 -0.52 -0.51 0.10 -0.13 0.54 0.31 -0.04 -0.65 -0.80 -0.93 -1.57 -0.17 -0.14 -0.30 -0.78 -0.27 0.17 0.13 -1.02 -0.89 -0.56 -0.03 0.32 -1.10 1.31 -0.22 -0.40 -0.81 1.54 2.24 0.83 -0.79 -1.05 -0.80 -0.81 0.49	=						2, 17		1.92	1.99	0.87
-0.32 -0.14 -0.07 -1.59 -0.66 0.32 0.92 0.66 1.00 1.52 -0.78 0.17 1.17 0.92 0.33 0.26 -0.26 1.65 1.59 2.17 -0.79 1.76 1.49 1.26 0.38 -0.24 0.59 -2.75 1.80 1.71 1.70 1.05 1.07 0.66 -1.97 -0.12 -0.11 0.11 -1.84 -2.37 -1.37 0.00 -0.56 -0.60 -0.52 -0.51 0.10 -0.17 0.13 0.54 0.31 -0.04 -0.65 -0.80 -0.93 -1.57 -0.17 -0.14 -0.30 -0.78 -0.27 0.17 0.13 -1.02 -0.89 -0.56 -0.03 0.32 -1.10 1.31 -0.22 -0.40 -0.81 1.54 2.24 0.83 -0.79 -1.05 -0.80 -0.81 0.49 0.73 -1.61 1.84 -1.05 -0.80	13						1.00		-0.21	0.32	-1.70
0. 66 1. 00 1. 52 -0.78 0. 17 1. 17 0. 92 0. 33 0. 26 -0. 26 1. 65 1. 59 2. 17 -0. 79 1. 76 1. 49 1. 26 0. 38 -0. 24 0. 59 -2. 75 1. 80 1. 71 1. 70 1. 05 1. 07 0. 66 -1. 97 -0. 12 -0. 11 0. 11 -1. 84 -2. 37 -1. 37 0. 00 0. 54 0. 31 -0. 04 -0. 65 -0. 80 -0. 93 -1. 57 -0. 17 -0. 14 -0. 30 -0. 78 -0. 27 0. 17 0. 13 -1. 02 -0. 89 -0. 56 -0. 03 0. 32 -1. 10 1. 31 -0. 22 -0. 40 -0. 81 1. 54 2. 24 0. 83 -0. 79 -1. 05 -0. 80 -0. 81 0. 49 0. 73 -1. 61 1. 84	77						0.32		0.30	1.78	1.07
0.33 0.26 -0.26 1.65 1.59 2.17 -0.79 1.76 1.49 1.26 0.38 -0.24 0.59 -2.75 1.80 1.71 1.70 1.05 1.07 0.66 -1.97 -0.12 -0.11 0.11 -1.84 -2.37 -1.37 0.00 -0.56 -0.60 -0.52 -0.51 0.10 -0.17 0.13 0.54 0.31 -0.04 -0.65 -0.80 -0.93 -1.57 -0.17 -0.14 -0.30 -0.78 -0.27 0.17 0.13 -1.02 -0.89 -0.56 -0.03 0.32 -1.10 1.31 -0.22 -0.40 -0.81 1.54 2.24 0.83 -0.79 -1.05 -0.80 -0.81 0.49 0.73 -1.61 1.84	, r						1.17		0.61	2.05	1.11
1. 76 1. 49 1. 26 0. 38 -0. 24 0. 59 -2. 75 1. 80 1. 71 1. 70 1. 05 1. 07 0. 66 -1. 97 -0. 12 -0. 11 0. 11 -1. 84 -2. 37 -1. 37 0. 00 -0. 56 -0. 60 -0. 52 -0. 51 0. 10 -0. 17 0. 13 0. 54 0. 31 -0. 04 -0. 65 -0. 80 -0. 93 -1. 57 -0. 17 -0. 14 -0. 30 -0. 78 -0. 27 0. 17 0. 13 -1. 02 -0. 89 -0. 56 -0. 03 0. 32 -1. 10 1. 31 -0. 22 -0. 40 -0. 81 1. 54 2. 24 0. 83 -0. 79 -1. 05 -0. 80 -0. 81 0. 49 0. 73 -1. 61 1. 84	16						2.17		-1.62	-0.16	0.52
1.80 1.71 1.70 1.05 1.07 0.66 -1.97 -0.12 -0.11 0.11 -1.84 -2.37 -1.37 0.00 -0.56 -0.60 -0.52 -0.51 0.10 -0.17 0.13 0.54 0.31 -0.04 -0.65 -0.80 -0.93 -1.57 -1.02 -0.89 -0.56 -0.03 0.32 -1.10 1.31 -0.22 -0.40 -0.81 1.54 2.24 0.83 -0.79 -1.05 -0.80 -0.81 0.49 0.73 -1.61 1.84	1.2	1 76	1 49	1. 26	0.38	-0.24			-1.82	-2.10	
-0.12 -0.11 0.11 -1.84 -2.37 -1.37 0.00 -0.56 -0.60 -0.52 -0.51 0.10 -0.17 0.13 0.54 0.31 -0.04 -0.65 -0.80 -0.93 -1.57 -0.17 -0.14 -0.30 -0.78 -0.27 0.17 0.13 -1.02 -0.89 -0.56 -0.03 0.32 -1.10 1.31 -0.22 -0.40 -0.81 1.54 2.24 0.83 -0.79 -1.05 -0.80 -0.81 0.49 0.73 -1.61 1.84		1.80	1.71	1.70	1.05	1.07			-1.42	-0.09	-0.90
-0.56 -0.60 -0.52 -0.51 0.10 -0.17 0.13 0.54 0.31 -0.04 -0.65 -0.80 -0.93 -1.57 -0.17 -0.14 -0.30 -0.78 -0.27 0.17 0.13 -1.02 -0.89 -0.56 -0.03 0.32 -1.10 1.31 -0.22 -0.40 -0.81 1.54 2.24 0.83 -0.79 -1.05 -0.80 -0.81 0.49 0.73 -1.61 1.84	2 2	-0.12	-0.11	0,11	-1.84	-2.37			0.71	-2.46	
0.54 0.31 -0.04 -0.65 -0.80 -0.93 -1.57 -0.17 -0.14 -0.30 -0.78 -0.27 0.17 0.13 -1.02 -0.89 -0.56 -0.03 0.32 -1.10 1.31 -0.22 -0.40 -0.81 1.54 2.24 0.83 -0.79 -1.05 -0.80 -0.81 0.49 0.73 -1.61 1.84	2.2	-0.56	-0.60	-0.52	-0.51	0.10				1.15	
-0.17 -0.14 -0.30 -0.78 -0.27 0.17 0.13 -1.02 -0.89 -0.56 -0.03 0.32 -1.10 1.31 -0.22 -0.40 -0.81 1.54 2.24 0.83 -0.79 -1.05 -0.80 -0.81 0.49 0.73 -1.61 1.84	5 5 7	0.54	0.31	-0.04	-0.65	-0.80				-1.07	
-1.02 -0.89 -0.56 -0.03 0.32 -1.10 1.31 -0.22 -0.40 -0.81 1.54 2.24 0.83 -0.79 -1.05 -0.80 -0.81 0.49 0.73 -1.61 1.84	30	-0.17	-0.14		-0.78	-0.27	0.17		0.30	0.81	0.31
-0.22 -0.40 -0.81 1.54 2.24 0.83 -0.79 -1.05 -0.80 -0.81 0.49 0.73 -1.61 1.84	31	-1.02	-0.89		-0.03	0.32	-1.10		1.62	0.53	-2.32
-1.05 -0.80 -0.81 0.49 0.73 -1.61 1.84	32	-0.22	-0.40		1.54	2, 24	0.83		-0.81	1.99	-2.32
C 2 0 C	38	-1.05	-0.80		0.49	0.73	-1.61		09.0	0.67	-3.64
0.17 0.11 0.15 1.40 1.32 0.12 -0.32	44	0.17	0.11		1.40	1.32	0.12		00.00	-0.30	-2.01

M = spectral magnitude levels $\gamma = log log spectral slope$

TABLE III-4
DETECTABILITY DATA
(PAGE 2 OF 2)

Event Number	M (0.3)	M (0.4)	M (0.5)	M (2.5)	M (3.0)	M (4.0)	γ (0.3)	γ (0.4)	γ (2.5)	(3.0)
48	-0.34	-0.31	-0.52	-0.35	-0.15	0.61	0.26	-0.30	0.04	0.76
49	0.85	09.0	0.26	2.08	0.93	2.46	-1.97	-1.41	-3.14	1.87
51 53	-1.12	-1.43	-1.74	1. 49	1.85	1.95	2.62	0.30	1.01	-0.17
55	0.95	0.83	0.52	1.08	1.22	2.46	-1.44	-1.52	0.25	1,45
99	0.07	0.29	0.33	2.35	1.90	1.80	0.79	-0.11	-1.07	-0.45
57	-1.46	-1.74	-2.03	0.35	-0.80	-1.41	-0.26	09.0	-3.63	-1.17
58	-0.63	-0.54	-0.40	2,54	2.29	1.80	0.79	0.80	-0.44	-1.00
69	-0.17	-0.06	-0.03	0.54	0.22	0.83	0.52	-0.41	-1.20	0.55
09	-1.05	-1.11	-0.93	0.97	1.00	-1.20	0.39	1.41	-0.09	-3.42
77	0.98	0.97	1.00	3,30	3, 10	1.54	-0.92	-0.72	-0.09	-2.53
81	0.27	0.77	1.67	-0.95	-0.61	1.44	1.97	1.81	0.25	2.60
87	0.68	0.91	1.15	-0,86	-0.05	06.0	0.39	-0.11	1.64	1,30
68	0.44	0.54	0.59	-1.57	-1.46	0.44	00.00	-0.30	-0.58	1.16
06	0.10	0.37	0.78	-0.08	-0.56	0.24	1.05	08.0	-1.83	0.83

M = spectral magnitude levels $\gamma = log log spectral slope$

$$E(\underline{D}_{N})$$
; [0.34, 0.89, 1.68, -0.40, 0.30, 1.59, 2.06, 1.45, 1.43, 1.53]. (III-8)

The dominant statistics are progressively increasing spectral levels at low frequencies, significantly elevated spectra at 4.0 Hz, significantly more steeply increasing spectral slopes at low frequencies, and less rolloff at high frequencies. The coherence between $E(\underline{D}_X)$ and $E(\underline{D}_N)$ is 0.05 indicating that the events represented by the average detectability $E(\underline{D}_X)$ are detectable to an almost completely independent basis from those events detectable by $E(\underline{D}_N)$. Thus at least two distinct sets of weights must be derived to optimally detect presumed explosions from western United States and from central Asia.

The performance of an optimum multivariate detector depends not only on the mean of the signal classes being detected, but also on their variation from the mean signal model. The difference from mean signal models $E(\underline{D}_X)$ and $E(\underline{D}_N)$ are shown on Table III-5. The covariance matrices for earthquake errors and presumed explosion errors are shown on Table III-6. The large variances for $\gamma(2.5)$ and $\gamma(3.0)$ (the last two diagonal values of earthquake area variances on Table III-6) are due to using positive deviations to compute the last two elements of $SD_O(\underline{X})$.

The least squares equation for optimizing the detection of presumed explosions from central Asia is as follows. Elements of the symmetric earthquake correlation matrix, [R], are R:

$$R_{ij} = \frac{1}{K-1} \sum_{k=1}^{K} X_{i}(k) X_{j}(k)$$
 (III-9)

where

K = the number of earthquakes used, and

 X_{i} = the ith element of X, which is the vector of measured discriminants.

TABLE III-5
PRESUMED EXPLOSIONS ERROR DATA

<u> </u>	38 83 39 47 74 74 70 70 70 66 65 65 65
γ (3.0)	0001112000011
γ (2.5)	0.90 0.20 -0.28 1.87 -3.26 0.89 -1.19 -0.56 0.56 0.62
y (0.4)	1.11 -0.21 -1.62 -0.81 -1.41 0.30 1.91 -0.11 0.80 -0.72 0.88
, (0°3)	0. 39 -1. 44 -0. 53 -0. 53 -1. 71 -0. 40 2. 88 1. 05 1. 05 -0. 66 -0. 66
M (4.0)	0.29 -0.66 0.51 -0.83 0.80 0.29 -0.54 0.14 0.14 0.14 0.14 -0.15
M (3.0)	0.56 -0.07 -0.46 0.19 -0.19 -0.15 0.24 1.05 -0.12 -0.12
M (2.5)	0.27 -0.16 -0.40 -0.51 0.03 0.30 0.49 1.28 0.94 -0.37
M (0.5)	-0.03 -2.25 0.30 -0.25 0.82 -1.18 -0.14 0.89 0.16 1.56
M (0.4)	-0.34 -1.68 0.69 0.03 1.03 -1.00 -0.66 0.72 -0.11 1.40
M (0.3)	-0.37 -1.17 0.67 0.12 1.19 -0.78 -1.10 0.41 1.32 -0.22 0.32
Event Number	07 13 16 32 49 51 53 56 58 77 11
	Western Central Asia

M = spectral magnitude levels $\gamma = log log spectral slope$

TABLE III-6 COVARIANCE MATRICES (PAGE 1 OF 2)

Earthquakes Error Data

1.00	0.97	0.94	0.09	0.10	0.93	-0.94	-0.89	0.03	0.81
	0.97	0.96	0.03	0.09	0.92	-0.77	-0.81	0.17	0.82
		1.00	-0.02	0.07	0.87	-0.60	-0.68	0.25	0.80
			0.99	0.83	0.23	-0.37	-0.17	-0.18	-0.74
				1.02	0.37	-0.13	-0.12	0.79	-0.77
					1.50	-0.75	-0.87	0.50	1.14
						1.55	1.06	0.66	-0.56
							1.02	0.11	-0.71
								2.94	-0.19
									2.36

TABLE III-6

COVARIANCE MATRICES (PAGE 2 OF 2)

Presumed Explosions Error Data

Central Asia Events

				Central	nsia L	vents			
0.80	0.83	0.80	0.30	-0.01	0.23	0.50	-0.73	-0.80	0.35
	0.93	0.99	0.33	0.01	0.24	-0.18	-0.59	-0.77	0.30
		1.17	0.39	0.09	0.24	0.22	-0.30	-0.71	0.21
			0.37	0.21	0.07	-0.13	-0.09	-0.35	-0.20
				0.34	-0.13	0.14	0.20	0.44	-0.67
					0.28	-0.16	-0.18	-0.54	0.58
						1.87	1.22	0.75	-0.43
							1.27	0.81	-0.54
								2.17	-1.41
									1.78
				Western	U. S. 1	Events			
0.08	0.02	-0.04	-0.14	-0.10	-0.13	-0.31	-0.20	0.08	-0.03
	0.01	0.01	0.01	0.05	-0.01	-0.06	-0.07	0.10	-0.09
		0.03	0.11	0.10	0.08	0.20	0.11	0.00	-0.03
			0.66	0.76	0.39	0.81	0.28	0.47	-0.53
				0.96	0.41	0.75	0.14	0.79	-0.80
					0.27	0.60	0.29	0.12	-0.18
						1.40	0.75	0.04	-0.21
							0.53	-0.34	0.21
								1.05	-0.95

1.08

The summation K is over the earthquake population. The optimization is furthered by casting out large negative deviations of the dot product $\left(E\left(\underline{D}_{X}\right) \cdot \underline{X} \right) < -SQRT \left(E\left(\underline{D}_{X}\right) \cdot E\left(\underline{D}_{X}\right) \right)$. Thus the least squares process makes no attempt to reduce the variance contributions of large negative earthquake deviations as these are easy to discriminate. If a much larger data base were used to design the optimum multivariate discriminant, then $\left(E\left(\underline{D}_{X}\right) \cdot \underline{X} \right) < 0$ would be cast out as only positive earthquake errors result in false positive earthquake identification. As a result of this condition, the large negative detectabilities, which obviously indicate earthquakes, are unconstrained.

A covariance matrix [R'] is constructed for a combined population of earthquakes and presumed explosions from central Asia, \underline{D}_X . Let $\underline{\underline{U}}$ (m) be the vector of average detectabilities of presumed explosions from the mth region or explosions medium type. For example, from the central Asian set, m=1, and $\overline{\underline{U}}_{\underline{i}}(1)$ is the ith element of $\underline{\underline{U}}(1)$, elsewhere referred to as \underline{E} (\underline{D}_X):

$$[S]_{m} = S_{ij}(m) = \frac{1}{K-1} \sum_{k=1}^{K} [U_{i}(k, m) - \overline{U_{i}(m)}]$$

$$* [U_{i}(k, m) - \overline{U_{i}(m)}]. \qquad (III-10)$$

 $[S]_{m}$ is the covariance matrix of signal errors from the mth region or explosion medium type. $[S]_{m}$ is shown on the bottom of Table III-6 for m=1, central Asian presumed explosion types, and for m=2, western United States presumed explosion types. The covariance [R'] which combines the variance due to earthquake errors and presumed explosion errors is:

$$R'_{ij}(m) = a \cdot [\overline{U_i(m)} \overline{U_j(m)} + S_{ij}(m)] + (1-a) R_{ij}.$$
 (III-11)

The scalar factors, a, where $(0 \le a \le 1)$ and (1-a), provide the designer the option to relatively weight the minimization of errors due to presumed explosion deviations and the errors due to earthquakes in the assumed mixed population. For example, if a=1, the multivariate discriminant minimizes the variance of the explosion population and ignores the variance due to earthquakes. If a=0, presumed explosion errors are neglected and positive deviations of earthquakes are minimized. Several trials have indicated that the multivariate discriminants are more effective if a is close to zero.

The least squares solution for the optimum multivariate discriminant W(m) for presumed explosion events from the mth region is:

$$\underline{\mathbf{W}}(\mathbf{m}) = [\mathbf{R'}]^{-1} \underline{\underline{\mathbf{U}}(\mathbf{m})}$$
 (III-12)

where the elements of the vector $\overline{\underline{U(m)}}$, the expected value of detectabilities of the mth signal region or medium type, is $\overline{U_i(m)}$.

In obtaining stable solutions for $\underline{W}(1)$ for the central Asian events and $\underline{W}(2)$ for the western United States events, the off-diagonal elements of the matrix [R'] must be multiplied by a positive factor, b, equal to or less than one. The solution is considered stable if the maximum absolute change in the solution (given an iteration of the off-diagonal weighting factor b) is less than $\tau \cdot (1-b) \cdot SQRT\left(\underline{W}(n) \cdot W(n)\right)$. In our case, b was taken as 0.99 and τ as 3.0. The solution vectors $\underline{W}(n)$ were normalized so that the expected value of a presumed explosion was 1.0 and of an earthquake was 0.0. For the central Asian presumed explosions, the off-diagonal elements of [R'] were multiplied by 0.94 and for the western United States, 0.93. This satisfied the above conditions for a stable solution. The solution for the central Asian presumed explosions is:

$$\underline{\mathbf{W}}(1) = [-0.07, -0.07, -0.07, 0.20, 0.10, 0.20, 0.05, 0.04, 0.00, 0.04]$$
(III-13)

and for the western United States presumed explosions,

$$\underline{\mathbf{W}}(2) = [0.02, 0.03, 0.13, 0.05, 0.02, 0.08, 0.05, 0.26, 0.03, 0.08].$$
 (III-14)

The coherence between $\underline{W}(1)$ and $\underline{W}(2)$ is 0.31. Thus, $\underline{W}(1)$ and $\underline{W}(2)$ provide a nearly independent basis for detecting events from the two regions. Figure III-4 shows the results obtained by plotting $\underline{W}(1) \cdot \underline{X}$, the component directed toward the central Asian set of presumed explosions versus $\underline{W}(2) \cdot \underline{X}$, the component directed toward the western United States presumed explosion component.

The set of vectors $\underline{W}(n)$, which are used to weight discriminants of events from N regions or medium types, are in general correlated. To obtain an independent and orthogonal basis for detecting events of N types, the set $\underline{W}(n)$ is replaced by a set of unit normalized orthogonal vectors, $\underline{W}'(n)$. Let:

$$\underline{\underline{Y}}(n) = \underline{\underline{W}}(n) / |\underline{\underline{W}}(n)|$$
 $n = 1, 2, ... N$. (III-15)

The correlation matrix of the set of vectors $\underline{Y}(n)$ is an N x N matrix [A], where:

$$A_{kn} = \underline{Y}(k) \cdot \underline{Y}(n) . \qquad (III-16)$$

From the above normalization, the diagonal elements of [A] (i=j) are 1.0; the off-diagonal element magnitudes, the coherence between the vectors $\underline{Y}(k)$ and $\underline{Y}(n)$; and the sign of the off-diagonal elements, the sense of the correlation between $\underline{Y}(k)$ and $\underline{Y}(n)$. The solution for the matrix of independent orthogonal unit vectors $\underline{W}'(n)$ are as follows:

$$[\underline{w}'(n)] = [A]^{-1} [\underline{w}(n)],$$
 (III-17)

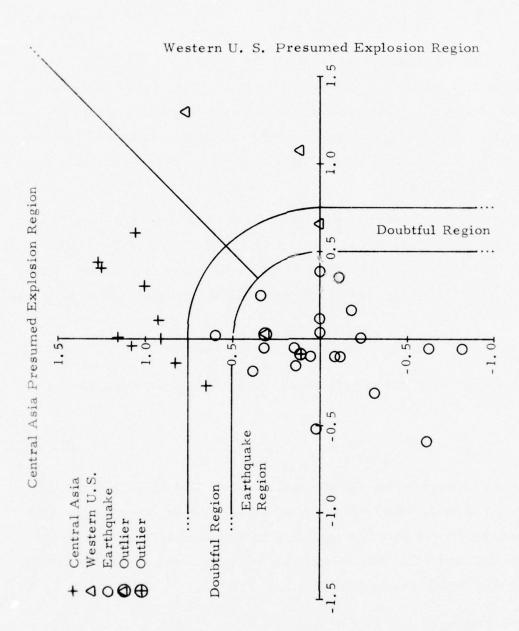


FIGURE III-4
MULTIVARIATE DISCRIMINANTS NOT ORTHOGONALIZED

where $[\underline{W}'(n)]$ and $[\underline{W}(n)]$ are M x K for M regions or medium types, and each row of the matrices is a set of weights to be multiplied over the K-measured event discriminant \underline{X} . The detection measure \underline{D} of M components is obtained as:

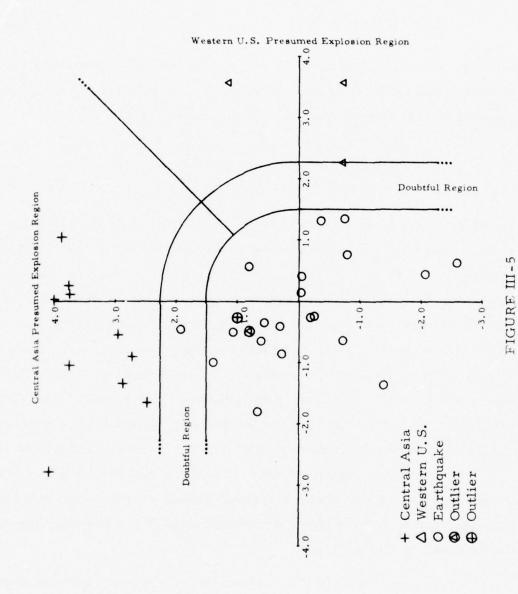
$$\underline{D} = [W'(n)] \underline{X}. \qquad (III-18)$$

The resultant set of discriminants \underline{D} can be interpreted as projections on unit vectors, each designating a signal type. For example, m=1 for central Asian events and m=2 for the western United States events:

$$A^{-1} = \begin{bmatrix} 1.1027 & - & -0.3364 \\ -0.3364 & & 1.1027 \end{bmatrix}.$$
 (III-19)

The resultant discriminants are plotted on Figure III-5. These are the orthogonal vector component projections of the event detectability vectors. These can be compared to $\underline{W}(n) \cdot \underline{X}$ plotted on Figure III-4. For these, the vectors $\underline{W}(n)$ are not orthogonal, but are least squares solutions normalized to an expected value of 1.0 for presumed explosions and 0.0 for earthquakes. In both cases, no weight was given to reduction of large negative deviations. The data for Figure III-4 are given under columns (5) and (6) of Table III-7. The data for Figure III-5 are given under columns (7) and (8) of Table III-7. The data under columns (1) and (2) are the discriminants using the average detectability of presumed explosions from region 1 (central Asia) and from region 2 (western United States). Under columns (3) and (4) are the orthogonalized projections. These perform less effectively than the least squares discriminants because of the highly correlated state of the spectrum levels and slopes shown on Table III-6.

Also on Table III-7 are shown hyper-space projections of the discriminants. Negative detectabilities are weighted by zero and others are weighted by one. The orthogonalized projections into M source regions are



MULTIVARIATE DISCRIMINANTS ORTHOGONALIZED

SUMMARY OF MULTIVARIATE SHORT-PERIOD SPECTRAL EVENT DISCRIMINANTS (PAGE 1 OF 2) TABLE III-7

(14)	0.00 0.00 0.27 1.00 0.00 0.00 0.00 0.00 0.00 0.00 0.0
(13)	1.00 0.00 0.00 0.00 0.00 0.00 1.00 1.00
(12)	0.16 0.00 0.00 0.00 0.00 0.00 0.00 0.00
(11)	0.0000000000000000000000000000000000000
(10)	1.00 0.00 0.00 0.00 0.00 0.00 0.00 1.00 0.00 0.00 0.00
(6)	1.46 0.029 0.098 0.098 0.00 0.00 0.0000 0.
(8)	-1.04 -0.43 -0.66 0.78 -0.73 -0.73 -0.64 0.13 -0.24 -0.85 -0.35 -0.35 -0.35 -0.47 -0.47 -1.80
(7)	1.46 0.29 0.62 0.81 -0.72 -0.72 -0.20 -1.39 0.28 1.08 0.28 1.08 0.54 0.54
(9)	-0.19 -0.15 -0.15 -0.15 -0.03 -0.05 -0.06 -0.06 -0.06 -0.06 -0.06 -0.06 -0.06 -0.06 -0.06
(5)	0.38 0.05 0.033 -0.32 -0.32 -0.09 -0.09 -0.00 0.01 0.01 0.01 0.01 0.03
(4)	-0.09 -0.08 -0.08 -0.09 -0.09 -0.05 -0.05 -0.05 -0.05 -0.05 -0.05
(3)	0.16 0.06 0.13 -0.02 0.10 -0.28 0.01 -0.03 0.03 0.08 0.06 0.06 0.06 0.06 0.06 0.06 0.07 0.08
(2)	-0.43 -0.33 -0.33 0.41 -0.30 -0.17 -0.01 -0.24 -0.24 -0.24 -0.26 -0.29 -0.26 -0.36
(1)	0.59 0.15 0.23 0.45 -0.38 -0.36 -0.37 -0.14 0.11 0.57 -0.01 0.57 -0.01
Event Number	01 02 04 06 14 17 22 22 22 22 33 33 34 44 44 48 67 69 90
	e9Asupd11sA

SUMMARY OF MULTIVARIATE SHORT-PERIOD SPECTRAL EVENT DISCRIMINANTS (PAGE 2 OF 2) TABLE III-7

(14)	0.00 0.18 0.00 0.00 0.00 0.00 0.00	0.86 1.00	0.00
(13) (1.00 0.82 0.00 0.00 0.00 0.00 0.00 0.00 0	0.14 0 0.00 1 0.00 1	0.96 0
(12)	0.35 0.23 0.27 0.19 0.26 0.26 0.38	0.32 0.18 0.23	0.06
(11)	0.00 0.00 0.00 0.00 0.00 0.00 0.00	0.91 1.00 1.00	0.00
(10)	1.00 1.00 1.00 1.00 1.00 0.88 1.00 1.00	0.09 0.00 0.00	1.00
(6)	3.75 2.88 2.43 2.70 3.75 3.02 3.75 3.75 2.99	3.84 2.24 3.56	1.12
(8)	0.23 -2.80 -1.35 -1.66 -0.92 -1.02 1.04 0.03	3.66 2.24 3.56	-0.29
(7)	3,74 4.04 2.88 2.43 2.70 3.75 2.84 2.99 3.71 2.95	1.17	1.12
(9)	0.444 -0.50 -0.15 -0.30 -0.03 0.61 0.30 0.40	1.28 0.65 1.07	0.02
(5)	1.28 1.07 0.82 0.64 0.81 1.15 1.06 1.25 0.92	0.76 -0.01 0.12	0.35
(4)	0.05 0.15 0.01 -0.04 -0.00 0.12 0.05 0.05	0.30 0.18 0.23	0.01
(3)	0.35 0.32 0.23 0.27 0.19 0.28 0.26 0.38	0.12	0.05
(2)	0.14 -0.68 -0.01 -0.23 -0.18 0.43 0.15	1. 24 0. 77 0. 99	0.04
(1)	1. 22 1. 16 0. 80 0. 98 0. 66 0. 99 0. 91 1. 13	0.36	0.19
Event	07 13 16 32 49 51 53 58	11 15 81	99
	Region 1	Region 2	Outliers

given as a length and the square of the direction cosines. For M=2 (central Asia and western United States) the least squares discriminant is shown by a length under column (9), squared direction cosine of the region 1 component (central Asia) under column (10), and squared direction cosine with region 2 under column (11).

The length and squared direction cosine components are shown for the discriminant derived from the mean detectabilities of region 1 and region 2 under columns (12), (13), and (14). For the earthquakes shown in Table III-7 (page 1), the length of the least squares projection was zero for 40 percent of the complex earthquakes and 20 percent of the simple earthquakes. For 40 percent of each type of earthquake the dominant projection was toward region 1. For 40 percent of the simple earthquakes and 20 percent of the complex earthquakes, the projection was toward region 2. The lengths of the earthquake projections were all less than the length of presumed explosions with the exception of the two outliers shown on page 2 of Table III-7.

SECTION IV SUMMARY, CONCLUSIONS, AND RECOMMENDATIONS

The need to perform interactive discrimination processing in the surveillance mode stems from the following problems:

- The methodology which optimizes discrimination processing is not yet known. Therefore, programmatic changes in discrimination processing procedures will need to be rapidly implemented on-line. An analyst can be computer-assisted and prompted under the constraint of a programmed set of standard operating procedures for performing the discrimination processing. Any such programmed changes in the analyst's procedures must be shown to significantly improve the analyst's discrimination performance using his old set of standards as a baseline.
- Certain tasks such as picking the start time of an event, detection and removal of echos, absorption correction, and other interpretive tasks may be performed better by an analyst than by any automatic procedure. But the introductions of analyst interpretation, even if constrained by standard operating procedures, trade off reproducibility of results. The projected gains of such processing must be verified and shown to be statistically significant.
- In some difficult tasks such as discrimination processing, interactive processing by an analyst is a necessary transition to more optimal and reproducible automatic processing. The exact definition of the task and the criteria for optimizing the task must be learned.

• As optimum automatic processing procedures evolve, the analyst will function primarily in response to emergency conditions. Some of these are: to detect and cope with overloading due to event swarms, etc.; to perform extended and more subjective analyses on events of doubtful origin.

The development and demonstration of the Short-Period Earth-quake/Explosion Discrimination Package (SPEED) partially fulfills the above needs for interactive discrimination processing. Our demonstrated capabilities have indicated that a substantial fraction of the required interactive processing capability has been developed. Also, the considerable amount of support data processing for editing events, selecting channels, and for time alignment of stations has been developed.

Some of the principal problems remaining to be solved are as follows:

- Automation of support data processing:
 - select out bad channels
 - time align channels
 - pick event start time
 - detect and correct station or component polarity reversals.
- Extend and provide needed improvements to the SPEED options:
 - correct time series for absorption with option of reprocessing data corrected for absorption
 - provide analyst capability to pick start times with automatic correction for initial offset
 - improve cepstrum analysis to more unambiguously determine echo delays; if possible, automatically determine echo delays and derive source parameter information from the cepstrum of the signal waveform

- provide an option to correct the event waveform for multiple scattered echos instead of just for single integer delay echos
- change the Variable Frequency Magnitude (VFM) program to measure magnitudes and rolloffs at an analyst-selected set of frequencies instead of for just a single high and low frequency magnitude measurement
- expand the list of short-period discriminant variate
 measurements and possibly also include long-period discriminant variate measurements which improve overall
 discrimination performance.
- Extend seismic command language capability:
 - compile event tables of discrimination variates derived from SPEED processing
 - compile event population plots of discrimination variates
 derived from SPEED processing
 - compile output tapes of standard format discriminant information for extended least squares multivariate discriminant analysis.

These recommended improvements may not all be achievable due to storage limitations of the PDP-15 computer. In some cases they may have to be performed as support processing on the IBM 360/44 rather than as SPEED options when such storage limitations are encountered.

In order to establish a performance baseline on utilizing SPEED as a routine event discrimination processor, a data base of representative earthquakes and explosions was processed. This baseline processing was specified as simply as possible and could be performed reproducibly in an automatic mode. The baseline performance data was obtained by fixed prescribed tapering, smoothing, and inverse tapering of the ground displacement

measurements. Several runs on some of the events indicated that the resultant measurements were reproducible. The measurements were magnitude changes at specified high and low frequencies from the average magnitude between 1.0 and 1.75 Hz. It turned out that the VFM method provides only marginal discrimination capability. It is estimated that about half the presumed explosions are detectable with a false alarm rate of about 2-1/2 percent. As would be expected, better performance could be obtained by utilizing all of the spectral values measured at four low frequencies and four high frequencies. Unexpectedly, it was found that a single set of weights for summing the discriminants could not detect presumed explosions analyzed from central Asia or from the western United States. Two nearly orthogonal sets of weights were required. This means that some finite set of vectors of an unknown dimension are necessarily required for a completely general multivariate spectral discrimination of presumed explosions. Even if such a complete basis for spectral discrimination is derived, there is no guarantee that spectral discrimination is sufficient to eliminate all false negatives associated with certain types of medium or geology.

There is also no guarantee that certain regions may not consistently produce false positive discrimination of earthquakes. The results obtained for multivariate discrimination indicate a standard deviation of 0.94 for the length of positive deviations. This is a conservative estimate obtained by neglecting the zero values of the discriminant; including them, the standard deviation is 0.86. The average presumed explosion discriminant length is 3.21. Assuming normal statistics, this would indicate a 2.5×10^{-4} probability of a false positive discrimination at the 50 percent level of detecting presumed explosions. The standard deviation of negative deviations in the presumed explosions population (possible false negatives) is 0.53. The 90 percent detection threshold for presumed explosions is approximately 2.5 (about 1.3 standard deviations below the mean of the presumed explosion population).

The probability of a false positive discrimination at the 90 percent detection level is estimated at 4.0×10^{-3} . In evaluating the baseline, the two outliers were obtained, both presumed to be peaceful nuclear explosions. From the above statistics, these are most likely not normal statistical variations but indicate incompleteness of the discrimination method in detecting every possible kind of explosion event. Either additional vectors are needed for more complete region or source medium type representation or more components are needed in the multivariate discriminant vector \underline{X} . It is probable that more discriminants other than the spectral discriminants analyzed are needed to discriminate all explosions. It is probable that direct detection of focal depth by methods more precise and reliable than those presently used will be needed to eliminate all systematic false negatives.

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APPENDIX A EVENT DATA

As part of the quality control in editing the NORSAR data used in this report, a matrix of plots of all of the event data was prepared for use by a data analyst. The plots included all sensors and subarray beams and also a window of noise preceding the event. The analyst by visual inspection of this data estimated the start time of the event, eliminated faulty channels, channels with polarity reversals, clipped channels, and those channels or subarrays showing no visual indication of event information on the channel or subarray beam. The remaining channels were then cepstrum beamformed and corrected for system response.

An additional quality control step was applied to the remaining operating good channels by comparing the spectrum of the element to a window of noise preceding the event. If at some frequency the spectrum of the noise exceeded the spectrum of the event, then that channel at that frequency was counted as containing no apparent event information. For each event, a summary table was prepared which at each frequency counted the number of channels with no apparent event information. These are presented in Tables A-1 through A-35 for all of the events processed. The tables are labelled by event number. Corresponding event description information is shown on Table III-1. Plots of the cepstrum beamform outputs are shown on Figure III-1. The column heading of frequency index numbers on Tables A-1 through A-35 indicate the number of the frequency estimate of the first row of that column. The index number column on the left side of the table indicates the frequency number increment starting from the top of each column. To

convert frequency index numbers to frequency in Hz, add the frequency index number on the left side of the table to the frequency index number listed across the top of the table, subtract 2, and multiply by 0.0098.

These tables give a powerful quantitative check on the amount of useful event information contained on all of the channels used in the cepstrum beamforming process. In case of alternative analyst picks of the channels containing weak signals and picks of the start time of weak signals, the tables containing lowest numbers and the broadest band of low numbers indicates the preferred analyst interpretation. A quick method of interpreting the tables is to take the largest of the first ten frequency numbers as the expected number of noise channels. A positive indication of seismic information is taken as a channel count of noise at a given frequency number equal to or less than one-tenth of the largest count between frequency number one and ten. The number of event indications by this criteria was observed in the following frequency number bands: 1-525, 526-750, and 751-1025. In the 1-525 band (frequencies less than approximately 5.0 Hz), all of the events indicate significant event information using this criteria. In the 526-750 (frequencies approximately 5.25 Hz to 7.5 Hz), only one out of 20 very large earthquakes (in particular, event number 22) indicated significant energy in this band possibly due to saturation and clipping. Ten out of eleven apparent explosions from eastern Kazakh indicated significant energy in this band. The one exception, event number 32, a possible peaceful explosion (PNE), was displaced several degrees from the other eastern Kazakh epicenters. In the 751-1025 band (frequencies greater than approximately 7.5 Hz), three out of 20 earthquakes were significant in this band; these included event number 22 again but also event numbers 4 and 87, both simple earthquakes. Six out of 11 of the eastern Kazakh events were significant in this band including event number 32, which was missed in the 5.25 Hz to 7.5 Hz band.

NOISE

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NUMBER

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TABLE A - 1 EVENT PAGE A - 3

401	451	501	551	601	651	701	751	801	851	901	951	1001
			551									
23	20	78877654447199755591458001	866945445454545457 7- 0865	35 36 36 38	35 32 34	38 37	38	354434	30	38	31	232233334421111890780899999999999999999999999999999
21	18	38	36	36	34	37	36	34	28	34	30	29
21	20	37	33	38	36	36	34	35	30	34	28	32
18	22	36	34	40	39	33	34	34	32	30	31	33
19	23	35	34	42	38	32	32	34	33	3.1	32	33
22	35	34	34	390 422 413 400 439 337 337 339 412 423	37	36	30	30	28	32	33	33
21	27	34	34	43	36	34	33	39	30	32	33	34
25	27	33	35	40	35	36	34	37	30	33	35	32
20	27	29	34	40	35	35	35	37	29	35	37	31
22	27	29	35	39	34	37	32	35	3.0	37	3.8	31
18	25	25	34	39	35	38	34	35	34	35	38	28
18	24	25	37	35	40	40	33	37	28	34	35	30
18	25	25	41	37	38	38	33	36	29	34	36	27
18	23	31	38	42	39	35	32	31	28	32	37	30
20	22	34	36	41	39	34	33	27	30	31	35	28
25	21	35	35	42	42	34	33	30	29	29	32	29
22	22	40	34 32 34	44	366 338 337 335 335 335 335 335 335 337 337 337	32	37	28	28	30	32	29
20	22	40	34	44 45 45	40	30	37	30	28	31	31	29
23	26	41	34	44	40	29	37	32	56	33	27	
23	29	39	34	44	38	28	35	33	28	34	28	
23	27	41	34	45	37	31	35	32	29	30	30	
24	27	39	37	44	37	31	35	33	33	31	33	
26	25	439908886766899	3467 367 400 41	42 40 39	30	31	33	34	32	31	31	
22	25	38	40	39	38	29	31	35	34	31	28	
22	27	38	41	41	37	29	34	32	34	3 1	29	
21	30	36	41	39	39	28	31	3.3	35	30	28	
19	31	37	39 39 40 39 40 36	39	39	28	32	33	35	30	28	
18	31	36	42	39	37	30	30	33	38	30	26	
18	31	38	39	37	36	32	32	33	36	28	25	
17	31	39	36	33	37	32	3.3	33	3.7	27	25	
18	33	38	32	38 37 38 41 39	36	33	37	446997975555769177708000m0484550mm8948888mm	34	31	20	
18	33	39	34 32 33 35	41	39 38 38 37 39 39 37 37 37 37 37	34	33	33	9.8000000000000000000000000000000000000	31	28	
16	36	39	33	39	37	35	35	31	31	34	29	
19	35	37	35	37	39	39	34	33	35	34	29	
231110890215502088886802222003333246322201908887788866911	0980123215778776545482212233698775457901121113346555	38 39 39 37 36 37	33 35 36 35	36	37 37 39 38 38	7647266465678868754444200981211099988072288072459990	\$\$\$\$454\\$\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	31 31 33 32 33	32 35 36 37	#CO+NANMMENTED144MN+900+mm460+121+00009870+1+454mN	1008112m5m578895687520216787031889898986555688999888	
21	33	37	3.3	39	38	40	33	33	31	32	28	

LE A-I VENT | € A-3

NUMBER OF	SEN	SORS	WITH	SIGNA	L LES	S THA	N NOI	SE AT	GIVE	N FRE	QUENC	Y IND	EX		
	1	51	101	151	201	251	301	351	401	451	501	551	601	651	701
2 3 4 5	61 62 62 62 58	44567	9 14 17 30 45	11 14 24 29 25 20	00000	1 1 2 2 2 1	9 10 10	0000	55566	8 8 11 9 5	13 11 17 19	15 18 18 19	17 17 16 18 18	27 26 28 28 26	32 31 29 29 25
6 7 8 9	59 59 58	88954	51 49 10 10 5	14 8 5 3	00000	210000	12 10 11 12 10	1 2 2 2 1 1	57 97 9	33221	21 22 21 18 16	21 22 22 24 27 26 27	17 17 17 18 21	25 24 25 22 25 26 54 25 26 25 24	25 25 23 23 23
11 12 13 14 15	60 59 60 59 61 59	32 1 1 1	2 1 1 1 1 0 1	100000		0000	10 7 8	3 3 1 1	12 12 19 20 19 20	1 1 2 3 5	15 12 11 11	24	21 22 21 21 20 20	25 24 22 21 23	2331122468444335498876543587898989100 22222222222222222222222222222222222
17 18 19	61 61 59 56 59	1 1 2 2 2 2	1 1 1 2	000	*	10000	8 6 7 5 5	1 1 0	26 28 28 30 26 28	4 6 7 8	11 11 15 17	24 20 20 20 20 20 19	21 22 22 22 22 22 22 20 19	22133224443533 222222233	28 24 24 24 23
20 21 22 23 24 25 26	59 58 57 55 51	10000	1 1 1 1 1 0	00000000	00000	0 0 1 2 3 3	545655	1 2 2 2 2 2 2	24 25 19 18	10 10 8 9 8	13 12 12 11 12	17 18 17 18 20 20	20	23 25 23 23 19	23 25 24 29 28
25 26 27 28 29 30 31	51 48 48 45 42	1	000000	0000000	000000	3 5 6	54421	2222222223	17 12 13 11	7 11 12 11 11	12 13 15 16 16 15	20 23 24	17 17 16 14 15	122222222222222222222222222222222222222	28 27 26 25 23
32 33 34 35 36 37	38 38 37 37	1 1 1	000000	000000	00000	58979	1 2 2 2 3	4 4 4	89998	10 12 10 10 11	16 15 16 15 15 20 17	24 23 22 21 21 21	15 20 20 21 21 21	25 26 26 26	25 28 27 28
38 39 40 41	35 30 27 25 23	1 0 1	00000	000	000000	8 7 9 9	3 2 0 1	444555	8 7 6 6	8 7 8 9 7	17 18 18 18 19	19 17 19 18	20 21 22 23 23	28 28 27 26	28 29 28 29
42 43 44 45	18 17 15	22335	000 1 1	000000	1	55554	2 2 1 0	333333333333333333333333333333333333333	6654355	88889	17 15 15 17 19	16 17 15 16	24	28	31
47 48 49 50	10 8 6 6	57777	1 1 2 7	0000	2 2 2 2 2 2 2	4565	0000	3 2 2 2	56 8 8	98 14 14	17 17 16 16	16 18 18 18 18	32 32 32 31 26	31 28 29 31	29 27 23 24 24

TABLE A-Z EVENT Z PAGE A-4

GIVE	N FRE	QUENC	Y IND	EX								
01	451	501	551	601	651	701	751	801	851	901	951	1001
55566579792290688068459872711198999888766654755688	8819554332211235466780089871211102001878978888899844 11111111111111111111111111111	11799121864521111115743221235665656565778889755797766	188991122247674400000978780003443211119798675668888 11111222222222222222111112222222222	17 16 18 18 17 17 18 12 22 11 22 22 22 22 22 22 22 22 22 22	268865944552654213322444435333900245556666888768888811891 22222222222222222222222222222	2219955333112246844433549887654358789898989100197344 33322222222222222222222222222222222	23090355320022257197765788697665312231367877986545 222122222222222222222222222222222222	65556788192190640087537825666555210108090121077897 22222222233232222211111222222222222222	1433443123322221112354323110009999009019011006988999	021345442013m66555542m4532987678888801458667432666554 222222222222222222222222221111111222222	533345976345689981122082884454675543421190211225676 222222222222223333323222222222222222	2246824565768544654422591332 22222222222222223333

A-2 NT 2

	NUMBER OF	SENS	SORS	WITH	SIGNA	L LES	S THA	N NOI	SE AT	GIVE	N FRE	QUENC	A IND	EX		
3		1	51	101	151	201	251	301	351	401	451	501	551	601	651	701
	1	54	15	0	0	1	1	5	11	7 5	2	8	18	24	12 12	22
	2	54	12	0	Ŭ.	1	1	5	12	2	4	8	18	24	11	21
	i i	55	6	1	×	5	1	4	13	6	5	7	19	28	12	23
	5	52	6	3	0	2	1	4	12	5	7	7	17	27	12	19
	6	50	5	3	0	2	2	3	13	6	6	7	18	26	14	18 18
	8	53	5	4	1	1	1	i i	16	6	5	7	20 21	24	15	17
	9	52	1	71	1	1	Ó	3	14	5	5	7	20	21	17	14
	10		0	3	0	1	0	3	13	5	6	7	16	21 20 21	18 18	14 15
	11 12	46	0	3		0	0	5	17	5	8	1	13	21	16	14
	13	44	0	2	Ŏ	0	0	2	21	4	8	5	11	22	16	17
	14	41	0	2	0	0	0	2		5	6	4	14	21	17	16
	15 16	37	0	3	Ö	1	1	7 2	19	4	6	67	15	19	18 18	17 19
	17	36	-	5		1	0	2	20	2	6	7	20	18	17	19
	18	36	0	1		0	0	2	20	1	7	7	20	11	18	19
	19	37	0	1	1	1	0	2	20	1	1	7	23	15	18	19
		36		1	-	1		4	21	4	6	7	23 23 25	17	15	19
	21 22 23	35	Ö	1		- 3	0	5	19	3	6	6	22	17	16	22
	23	36	0	9	0	2	0	5	18	5 5	4	9	25	17	18	22
	25	35	- X		-	5	1	3	19	5	7	8	22 25 26 27 29	16	24	51
	25 26	36	0	0		1	1	4	17	5	6	8	29	15	23	21 22
	27	34	0		0	Q.	1	5	14	4	5	10	27	15	25	21
	28 29	36	- 0		1	-	2	4		4	4 5	10	27	16 16	22	26
	30	37	· ŏ		ŏ	. 0	2	3	12	2	5	11	29	19	22	23
	31	35	0	0	0	- 0	1	3	12	3	6	12	28	19	20	22
	32	36	0		U		-4	3	11	7	5	12	28	18	21	18
	34	33	0				4	3	11	3	g	0	24	19	18	17
	35	33	0		0		4	4	12	3	8	11	25	18	17	20
	36 37	33	1	0	1	0	3	LL LL	10	3	8	13	26 26	22	17	18 18
	38	30	1	0	0	1	5	6	9	5	9	15	26	19	18	19
	39	31	1	0	0	2	5	4	9	5	9	14	25	17	22 23 24 23	19
	40	30	0	0	0	2	11	4	9	7 9	9	12	24	15	23	18 18
	42	29		- 0	1	1	3	3	6	7	q	15	25 26	14	23	18
	43	29	0	0	1	1	2	3	6	6	8	16	24	14	22	18
	44	28	0	0	1	1	2	4	6	5	8	17	24	14	23	17
	45	28	0	V.	1	-	3	6	8 7	5	11	11	23 22 22 23	12	21 22 21 23	15
	47	27	ŏ	ŏ	0	1	2	5	6	5	10	14	22	14	21	16
	48	22	0	0	0	0	1	8	6	4	8	14	23	11	23	14
	4 9 5 0	20	0	0	1	0	1	6	5	3	7	14	21	13	23	13
		10			1		,	8	/	- 2	5	13	26	12	23	12

TABLE A-3 EVENT 4 PAGE A-5

IVE	N FRE	QUENC	A IND	EX								
01	451	501	551	601	651	701	751	801	851	901	951	1001
7	2	8	18	24	12 12 11	22 21 23 21	11	11	10	9	tı.	q
5	4	8 7	18	24 24 27 28 27 26 21 21 22 21 22 21 22 21	11	53	10	13	11	1.0	4	10 12 11
6	5	7	20	28	12	21	10	15	10	10	14	11
5	7	7	17	27	12	19	11	16	12	10		11
6	6	7	18	26	14	18	11	18	12 12 12 12	10	6	10
7	5	5	20	24	16	18	11	19	12	10	6	11
6	5	7	20 21 20	21	15	17	10	19	12	10	6 6 7	11
5	5	7	16	21	17 18	14	12	20	13	12 12 13		9
5	6	5	13	51	18	15	14	20	12	13	5	10
5	8	Ū.	11	22	16	14	12	20	17	13	655	10
- 4	8	5	11	20	16	17	13	20	15	12	5	11
5	6	4	14	21	17	16	12	17	13	11	7	11
4	6	6	15	19	18	17	14	15	13	13	11	12
3	6	4	16	18	17	19	15	14	12	14	10	15
1	7	7	20 20	11	1.8	19	15 16	1/1	13	13	10	16 16
2 4	7	7	23	15	18 17	19		13	13	14	11	16
	6	7	23	15	17	2.0	15	15	12	14	13	14
435	6	7	25	17	15	19	14	15	13	16	11	16
3	6	60	22 25 26 27 29	17	16	22	11	12	14	14	9	19
5	4	8	52	16	21	22	11	13		13	q	19
- 5	5	7	27	16	- 24	21	10	11	12	14	- 9	20
5	6	8	29	15	21 24 23 25	22 21 22 21 24	1.0	11	14	13	9	
4		9	27	15	25	21	10	11	12	15	8 7 8 9	
4	5	10	27	16	24	24	13	11	13	15	8	
2233	5	10	20	16 19	22	26 23 22 18	11	10	13	16 15	q	
3	6	12	28	19	20	33	12	10	14	14	q	
3	6	12 12 10	28	18	21 21 18	18	12	10	13	13	7	
- 3	- 6	10	24	20 19	21	17	q	8	15	12	7 8	
3	9	0	2.5		18	17	9	9	12	10	8	
3,77	8	11	25	18	17	20	11	6	9	13	9	
3	o o	15	29 29 28 28 24 25 26 26 26	22	19	18	10	7	11	12	7	
6	9	15	26	19	1.8	19	10	7	g	12	77666789	
- 5	9	14	25	17	22 23 24 23	19	10	6	8	1.4	6	
7	9	12	24 25 26 24	15	23	18	12 13 12	6	8	16	6	
8	9	13	25	14	24	18	13	6	R	17	6	
7	9	15	26	14	23	18	14	3	9	16	0	
65	8	16	24	14	22	17	14	6	8	12	G	
- 5	9	11	24 23 22 22 23	12	21	15	13	7	8	13	10	
14	11	13	22	12 13	22	17	14	7	7	13	10	
. 5	10	14	22	14	21	16	16	8	8	10	10	
11	8	14	23	11	23	14	15	q	8		11	
3	7	14	21	13	21 22 21 23 23 23	13	13	10	7 8	7	10	
-	9	13	24	12	23	12	12	10	0	1	, ,	

LE A-3 VENT 4 6 A-5

NUMBER	OF	SENSORS	WITH	SIGNAL	LESS	THAN	NOISE	AT	GIVEN	FREQUENCY	INDEX
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1	51	101	151	201	251	301	351	401	451	501	551	601	651	701
1 12 2 11 3 11 4 11 5 12	19 19 19	55444	5566	14 14 15 14	88888	10 10 10	10 11 11 11	12 12 11 12	10 10 10 10	15 14 14 13	7 8 7 6	14 14 13	6566	8 8 7 7
6 12	17 16 15 15	2 2 2 1	6 6 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7	14 14 14 14	8 9 10 11 11	10 10 10 10 89 7	11 10 11 11	12 12 12 11 11	10 10 9	13 12 12 12 12 15 14 15	56699	11 10 10 10 10	5 6 6 7	8 8 8
8 12 9 12 10 12 11 13 12 13 13 13 14 14	14 11 100 100 100 100 100 100 100 100 10	2 1 1 3 3	7 10 10	14 15 15 15 13	11 14 14 14	7 6 7 7 7 7 7 7	10 10 10 10 8	10 10 10 10	66665	13 12 11	9 10 10 10	10 10 11 12 12 12 10	8 8 8 7	9 8 8 10
15 16 16 16 17 16 18 18 19 18	9	3 3 2 3	7 6 7 6 6	14 14 12 11 13	14 12 12 12 12 12 10	9 9 10 11	67 66 7	8 8 9	4 4	10 10 10 10 10 88 88 98 87 77	11 11 11 12 11	8 9	88568	10 12 13 13 13
20 18 21 17 22 18 23 18 24 18	10 9 8 8 8	33433	447333	13 12 10 11 11	9	12 13 13 12 12 11	8 10 12 10	10 10 9 8	4 5 5 6 7 7	8 8 9 8 8	12 11 11 11 11	8 9 9	6 7 7 7	14 13 13 13 13
21 17 22 18 23 18 24 18 25 18 26 18 27 18 27 18 29 16	8 8 8 10 10 8	3 3 3 3	1 1 1 1 3	8 9 9	9776555	11 99 100 100 100	11 12 13 13	7 9 10 10	8 8 8	7 7 7 10 10	10 10 10 8	11 12 13 14 14	10 10 10 10 10 10	11 11 11 11 10
31 17 32 18	8 8 8 7 6	23444	4 4 4 5 5 5	12 12 12 12 12 12	5 5 5	10	10 10 11 10 10	11 13 12 12 11	8 11 12 13	11 11 10	9 11 12 11	13 12 13 15	90000	10
36 15	66555	5 6 5 7	55555	13 15 15 14 13	57 66 6	10	10 10 11 13	13 12 13 13	13 12 10	10	13 12 12 12 11	14 13 12 12 11	10 10 10	100
40 15 41 15 42 15 43 14	4555	334443	6 7 9 10	13 13 14 14 13	66889	11 13 12 14	12 13 12 11 12	13 13 13 13 13	10 12 12 11 11 12	12 12 12 12 13 13 10 8	11 10 10	11 11 11	109987	8 10 10
45 17 46 16 47 16	6576655	344555	10 11 14 14 14	11 11 10 8 8	9 9 10 10	14 12 10 9 10	12 12 12 12 11 10	13 11 10 10	12 14 13 13 16 16	8 7 6 7 8	12 13 13 13 14	10	7777777	8 9 9
17 50 17	5	5	14	8	iŏ	10	11	9	16	8	14	8	8	10

TABLE A-4
EVENT 6
PAGE A-6

GIVE	N FRE	QUENC	Y IND	EΧ						
401	451	501	551	601	651	701	751	80.1	851	9.0
12 12 11 12 12 12 11 11 11 10 10 10 10	10010011100976666655	154 143 122 125 145 121 121 121 121 121 121	78765669999000111	14 14 13 13 11 10 10 10 10 10 11 12 12 12 10	65665566788887	8 9 8 8 9 9 8 8 9 9 1 1 2 3	100119999999999999999999999999999999999	12 10 99 10 10 10 11 11 10 11 11 10 11	7766777667788798	1
8	4	10	11	10	8 8	1.3	9	11	6	1
9 11	4	10	11 12 11	9 8 9	568	13 13 14	10 10 11	10 11 11	8	1

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EVEN

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951 1001

1	51	101	151	201	251	301	351	401	451	501	551	601	651	701
	0.5	_	ρ		,	2	,	7	,	7	- 6	3	15	10
63	26		10	4		5	1	7	4	6	6	11	16	14
	24			1	× ×	5	1	ú	4	6	6	5	20	13
64	22		13	1		5	5	4	5	5	7	5	17	16
65	19		13			- 4	- 5	- 5	5	5	- 1	h	16	17
65	18	0	14				3	6					17	10
6.5	19		14		0	2	3		6	7	7	6		16
62	17		16	0	0	1	2	6	3	1	9	6	17	
63	14		18	0		1	4	4	3	8	g	6	19	14
64	9	0	17	0	0	0	4	4	2	8	10	7	19	16
63	9	0	15	0		1	4	5	- 4	11	12	7	12	17
6.4	7	0	12	17	- 0	1	L	6	- 4	11	13	8	13	16
65	7	^	10	0		1	- 4		3	1.0	14	g.	15	15
65	7		- a	- 0		0	5	6	2	10	12	11	15	14
	7	2			0	0	5	6	3	g	11	10	14	15
64	4	2	7			1	11	5	3	10	11	11	Q	13
63						-	3	5	3	8	11	11	11	13
61	4	1	6				- 11	6	7	8	0	5	11	13
61	3	1	6		1			5	3					14
63	3	0	6			1	- 4		- 3	9	9	5	12	
63	3					1	- 4	5	3	8	9	5	11	15
55	3	0	9			2	3	5	3	- 6	10	6	12	17
62	3	0	11	-	1	2	14	- 4	3	11	9	6	12	16
61	2		q	1	1	3	4	4	2	5	7	7	10	16
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TABLE A-5
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TABLE A-5 EVENT 7 PAGE A-7

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TABLE A-6 EVENT II PAGE A-8

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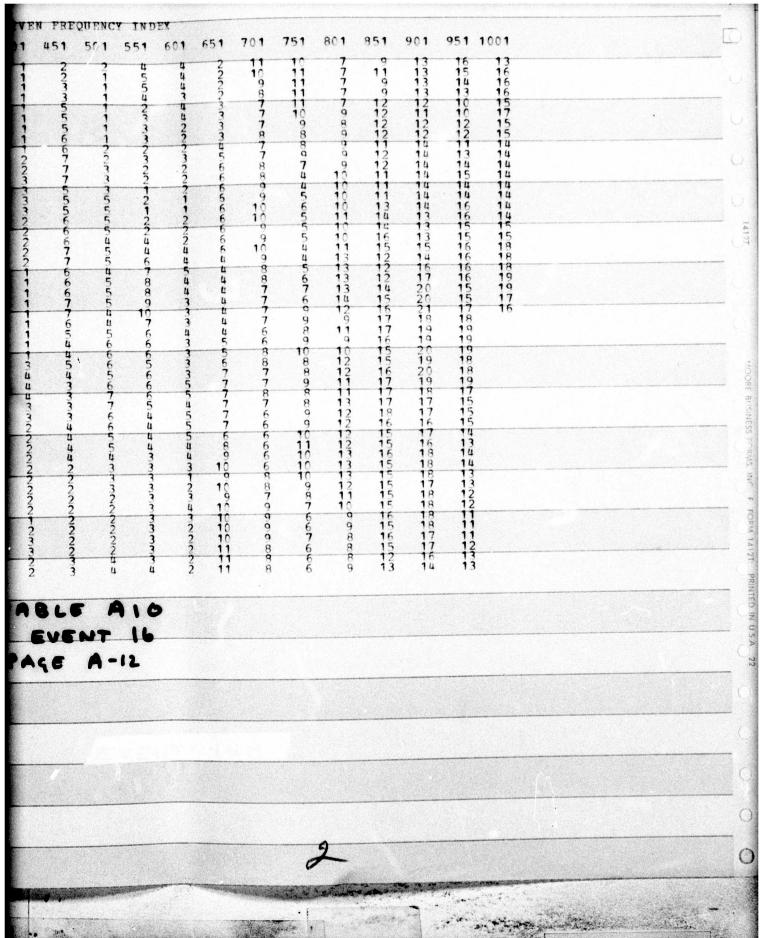
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NUMBER OF SENSORS WITH SIGNAL LESS THAN NOISE AT GIVEN FREQUENCY INDEX

	1	51	101	151	201	251	301	351	401	451	501	551	601	651	701
1 2	49	11	0	1 0	5	10	17 15 15	10	51 53 53 - 50	34 32	23 21 20	40	38 36	38 39	34 36
2 3 4 5 6 7	51	9985	Ô	0	3	10	15	11	53	31 29	20 19	42	38	41	35
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GIVE	FRE	QUENC	Y IND	EX								
401	451	501	551	601	651	701	751	801	851	901	951	1001
11330999757424750735768665792976400868019133777910133 55554444444333333333333333333222333277910133	42199934450097564334421009033139979900120110139965 3332223333333333333333333333333333333	310992689810245676660088776555434116899002111225117888	01285511831244009768765431132426034354576798663977	866801007777666874566587779823668106657201908777685779899 33344443333333333333333344445544444434333333	3391108875556667988866887899108670236444444433333333333333333333333333333	4651460199120877012342236366563195533333333333333444333344444444444444	321213445457689255644443070787668650975886691202021 33333333333333334444444443070787668650975886691202021	08789132111001767889097099222456522584198577786331	208877788678887671432577544807776355612566346633355 2111111111222222222222222222222222	211002235589845181110002000020234122910201144128788 222222222222222222222222222222222	002434123886555531101111900033986455534545668197665	15 14 13 13 14 18 19 16 16 16 16 16 19 19 19 12 22 27 27

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NUMBER	OF	SENS	ORS	WITH	SIGNA	L LES	S THA	N NOI	SE AT	GIVE	N FRE	QUENC	Y IND	EX			
		1	51	101	151	201	251	301	351	401	451	501	551	601	651	701	
123456789012345678901234567890123456789		1 4444444444444444444444444444444444444					251 00000010000000000000100111000120000000								651 18771802254321288864646487511266679991424342222224	70 1 43 43 43 143 143 143 143 143 143 143	
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	1001	132 154 155 144 155 166 168 177 178 199 199 199 199 199
	951	1232112108876887889099011212323444354444432344457734571665
	901	133313213444444111343323647675857320987767901900022 111111111111111111111111111111
	851	1222233665467653321111100255344354225546787777532322
	801	1332334453109900111211345224308765791111112149922243
	751	197577888875457899000877776678866688887545785531111000223
	701	1434348990109022220111433301122088687956656656898898 111111112221222222222222222222221111111
	651	18 177 180 122 122 188 164 164 164 175 112 166 179 199 114 117 119 119 119 119 119 119 119 119 119
EX	601	765688801111133311001134444552221123441311221145677658888011111133311001134444552221123441311221145677658
Y IND	551	33347777564445544533366521909899020209099967776709997
QUENC	501	219.87611543413315336354556433124555554310902222334342
N FRE	451	111221111111122232344767777700911121589124767555591
GIVE	401	111212221111211222212322212123212311234333223322

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UMBER	OF	SENS	ORS	WITH	SIGNA	L LES	S THAN	4 NOI	SE AT	GIVE	N FRE	<i>Gaenc</i>	A IND	EX		
		1	51	101	151	201	251	301	351	401	451	501	551	601	651	701
1 2 3 4		34 34 34	0000	4 3 3 4	4 6 8	12 4 2	21 23 14	1000	17 16 13	12 10 11 12	16 18 19 21	12 11 12 16	32 33 32 30	26 26 26	21 20 20 21	24 22 21 23 22 20 21 20 21 16
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GIVE	N FRE	QUENC	Y IND	EX								
401	451	501	551	601	651	701	751	801	851	901	951	1001
12 11 12 11 12 11 10 98 88 81 13 13 13 14 14 13 11 12 12 12 13 13 13 13 13 13 13 13 13 13 13 13 13	1899101288888777778999999999999999999999999999	2126791019242E578778875555466644853C33B3B3B3B3B3B3B3B3B3B3B3B3B3B3B3B3B3B	23207008889866997099870222112321210198754124246767 33332322222222222222222222222222222	22222222222222222222222222222222222222	222222222222222222222222222222222222222	2221324200186698811223244232813333110019888991876 1111122222222222222222222222222222222	1699103322224589807876524314322015655554446897888753	1456656877777897555981099618889910100133222200321002 11111111111111221112118889910133222200321002	2322111775474344444775521892345300890889980134642212 11111111111111111111111111111111	1345443323223222222222222222222222222222	20999779886576 19779886576 11111111111111111111111111111111111	16 17 18 19 19 19 18 18 17 19 19 19 18 18 17 19 19 19 19 19 19 19 19 19 19 19 19 19

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NUMBER	OF	SEN:	SORS	WITH	SIGNA	L LES	5 THA	N NOI	SE AT	GIVE	N PRE	DUENC	Y INL	EX		
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GIVE	N FRE	QUENC	Y IND	EX								
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NUMBER	OF	SENSORS	WITH	SIGNAL	LESS	THAN	NOISE	AT	GIVEN	FREQUENCY	INDEX
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TABLE A-25 EVENT 53 PAGE A-26

CIVE	N FRF	OHENC	Y IND	EA										
401	451	501	551	601	651	701	751	801	851	901	951	1001		
444	3333	4 3 3	1 1 1	0001	4 4 3	1 1 1	1 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	4 4 4	3 2 2 2 1		2 2 2 2	1		
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ABLE A-25 EVENT 53 PAGE A-26 A= 0.0 ON CHANNEL 130

A= 3.14 ON CHANNEL 132

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7	10	49	8	4	1	5	18	7	22	20	28	31	4.1	55	
8	10	48	8	4	1	5	19	9	2.2	21	3.0	30	38	57	
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TABLE A-25 EVENT 55 PAGE A-27

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21	17	24	39	50	51	43	53	47	49	49	39	42	
20 21 25 24 26 27 28 28 27 30	20	29	41	46	49	44	57	48	52	48	38	42	
24	22	28	41	48	48	45	56	49	52	51	37	40	
20	20	30	40	49	43	45	55	50	52	49	36	41	
28	22	29	40	48	45	42	55	50	48	49	37	41	
28	21		48	47	45 45 45	41	53 53 54	48	46	48	37	40	
27	23	31	49	49	45	42	53	48	46	45	35	42	
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33	26	11.5	41	42	53	55	39	40	52	37	36		
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26 25 20 21 21 20	20	36	49 51	43	54	56	43	46	51	38	40		
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TABLE A-27 EVENT 57 PAGE A-29

GIVE	N FRE	QUENC	Y IND	ΕX								
401	451	501	551	601	651	701	751	801	851	901	951	1001
142 133 135 166 176 168 169 169 169 169 169 169 169 169 169 169	2111978802210987775466669800091222456662334431298000013332 1122222111111111112212222222222	435544578097678898688786700209887766666666888891101 2222222222222222222222222222222222	2m1980981110m2290090112444688899900011008655444mm10	291001118789986688764554765667991801096665766888909999988	2889910112222099902211199887787677767676799967876344443	233112012199910122223454545455663322319023222221190009976	14456555345578998887899887897987953344 11565553455789988789987953344	222222222222222222222222222222222222222	122211888988877778656697654454421223447888899908881	02222218998980322454445544198001098076547024687776 222222118998980322222222221122111112222222222222	222222222222111222111122211112221111221111	1933221000190222771788165188112225

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NUMBER OF	SENSORS	WITH SI	GNAL LESS	THAN NOISE	AT GIVEN	FREQUENCY	TNDEX
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	1	51	10.1	151	201	251	301	351	401	451	501	551	601	651	701
1	64	48	1	14	9	19	42	28	44	71	70	57	67	51	60
2	64	43	1	16	0	18	42	27	39	71	73	58	70	51	61
3	63	42	1	19	8 7	20	43	26	40	71	71	61	72	51	61 59
4 5	61	41	5	24	6	21	30	25 25	38	68	72	62	71	51	59
6	50	30	3	54	6	19	42	27	38	67	73	61	70	47	60
7	62	38	5	25	6	10	42 42 42 43	29	35	63	70	64	73	46	59
8	61	36	5	27	6	19	42	28	37	63	70	64	73	45	50
9	63	32	2	30	7	17	42	26	38	67	70	67	73	47	59
10	63	33	1	31	7	19	43	29	37	65	73	67	74	52	59
11	64	34	0 -	33	5	17	41	28	37	65	72	66	73		61
12	65	36	3	31	- 6	17	40	30	38	67	70	63	69	57	63
13	67	38	3	28 27	6	14	27	32	37	66	69	64	68	58	65
14	66	39	3	54	6	14 15	37	33	40	64	69	67	66	59	65
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17	65	45	3	22	6	13	34	30	44	64	64	70	61	49	64
18	64	47	3	19	6	13	33	29	44	65	64	69	61	49	61
19	65	48	3	19	6	12	32	28	45	62	64	69	62	46	62
20	63	51	4	19	6	12	31	28 28	42	62	62	70	62	43	62 62 59
20 21 22 23	62 60	55	4	18	6	11	27	29		62 62 65	64	68	64	45	59
22	6.2	58	14	16	5	11	28	29	48	6.7	62 59	69	62	51	57
23	60	60	4	15	5	11	26	29	48	66	59	6.7	65	52	56
24	60	65	3	14	5	10	27	28	52	59	59	68	66	53	52
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55	56 56	63	4	11	4	8	30	38	61	36	56	70	62	56	49
20	58	62	5	8	3	10	30	42		54	50	74	63	56	49
27 28 29	5.8	51	5	9	3	10	31	44	62	57	50	71	64	56	48
30	58	53	5	8	3	13	31	46	58	60	61	71	6.6	53	53
31	56	46	5	8	3	15	35	47	59	63	64	70	65	53	53
32	54	39	6	9	- 4	18	35	47	60	6.3	62	7.0	63	55	51
33	56	36	5	7	4	20 21 21 20	33	48	61	67	63	70	6.5	57	54
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41	54	7	3	4	6	30	35	48	61	73	56	58	52	50	64
42	56	4	3	4	7	37	35	50	63	75	57	58	49	54	65
43	60	4	3	5	7	36	36	50	6.7	73	58	63	49	52	64
44	58	4	- 5	7	10	38	35	50	6.9	70	55	63	52	51	61
45	58 57	4	4	8 8	11	41	33	50	70	70	55	62	56	54	60
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48	55	2	7	9	12	43	20	49	71	73	55	64	57	55	56
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TABLE A-29 EVENT 59 PAGE A-31

OULICE STECCHOOMICS INC

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	1	51	101	151	201	251	301	351	401	451	501	551	601	651	
1	40	12	0	0	0	0	12	0	11	2	3	5	12	10	
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TABLE A-30 EVENT 60 PAGE A-32

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	222221111111211111111111111111111111111	335534444465677910111311551666665544332222445556	5556544455453337466654444432433445666576777787889990110		10 10 10 10 10 10 10 10 10 10 10 10 10 1	12 11 13 12 12 11 10 10 10 10 10 10 10 10 10 10 10 10	785433355656666677666664232255555666754322223346777	78987777648383554445566777899990098099098765564	222333334445444466777787887766466666555533344412344	4455455456666556787778888886677778987885459755654456	6766879988676555443212455444657777666565555555666666	5 6 6 4 3 3 3 3 3 3 6 7 10 11 11 13 16 18 18 19		
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5	45	40	38	28	5	0	0	4	2	2	11	3	8	8	20
7	45	43	40	26	3	ŏ	Ö	4	2	3 3	10	3	8	8	20
Q	45	46	42	26	3	Ö	0	6	2	3	8	4	8	7	21
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10	45	43	39	26	4	0	1	5	2	3	9	5 7			19
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14 15 16	42	36	33	25	4	0	2	6	1	3	10	9	5	8	16
17	43	34	33	20	3	0	1	6	1	3	9 10 10 9 9	7	6	10	18
17 18 19	43 45 46	33	30	24	3	1	1	4	1	3	9	6	6	11	18
19	46	33	32	24	4	1	1	4	3	4	11	67	6	11	17
20	45	34	32 32 33	24	333433221	1	1	3	34455555	5 6 7	11 12 13 13	8 8 8	4	11	16
22	46	35	33	23	2	1	1	3	5	6	13	8	5	12 10 10	20
23	46	36	32 36	22	2	1	1	14	5	7	13	10	6	10	20
24	46	34	36	22 22 20	1	1	2	4	5	8	11	9	6	11	21
20 21 22 23 24 25 26 27 28 29 30	44	35	36 35 35	18	0000022	1	2	4555557	7	8	11	9 8 9	666645566657	14	20
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30	45	39	33	15	2	1	2	6	2	11	9	9 8	8	14	24
32	45	37	37	11	1	1	3	6 5 6	3	14	9	8	á	12	21
32	45	37	34	11	2	2	2222222367	6	1	13	8	8 8 8 7	87	13 12 11 10 10	21
34	47	38	36	9	2	2	7	4	2	10	9	8	7	10	20
35	46	41	34	8	2	2	7	4	4	10	10	1	8	10	20
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42	44	42	29	6	1	0	10	4	3	10	7	10	á	13	21
42	44	37	31		1	0	8	6	3	8	8	10	9	12	18
44	45	35	33	6	1	0	7	6	3	8	5	10	7	13	19
44 45 46	45	34	35	6.	1	0000000	8 7 7 7 7	6	3 2 2 2 2	9	989 1099999 1077 785 665	11	11 12 11	14	21 18 19 20 22 23 22 21 22
45	43	34	34	6	1	0	7	2	5	10 10 10 10 9	5	10 10 10 8 7	12	17	23
48	41	35	37	6	1	ŏ	7	î	1	10	4	10	11	20	22
49 50	40	38	37	6	0	0	5 4	1	1	10	5 5	8	11	20 18 19	21
50	40	39	38	6	0	0	4	1	1	9	5	7	12	19	22

TABLE A-31 EVENT 77 PAGE A-33

	1	55533334457767977678880988998888877778889000110087	699088887765555666664556666578887987889877779979121	998989877778788880911111201111432231447720819	198019901109986511111111111111111111111111111111111	22222222222222222222222222222222222222	8699755655467668888014455562354208875322092232222222222222222222222222222222	11311289134579108696799977890770214464554998009448 2222221122222233322222222222233223333333	123332232325109332355555698558999999988688800119097 22222222222222222222222222222222222	75699000965322234455785332469999667890123090878000 22222333222222222222222222222222222	30 30 30 30 30 30 30 30 30 30 30 30 30 3
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14347822101978910220034412429964323122566753325552987	49880269022011030299889994299985545 555566666666665555555555444444 5555545555544455555	55554545555555555555555555566666666666	22254666541885442219090001109144578908455666788576 6666666666555555555555555555	518 479 519 519 519 519 519 519 519 519 519 51	96444670118934220132344229124372347821066556655854422 4444455554455555555555555555555	0769042112134556453991735321898089121373444322979755	44444444444444444444444444444444444444	420100113515668175434232358654655197900854554222245	3566655112222247777679889977877566653833487886796614444444444444444444444444444444444	42421778023107928645466666655667020089215664678541 4444333433333333333333333333334444334444	1176#54#66966#767####1146662@220904###T386######202##5	36 37 36 35 36 37 36 37 36 37 36 37 36 37 37 37 37 37 44 44 44 44 44 44	
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2	58	1	0	11	5		13	6	13	26	48	27	39	22	20
3	58 58	1	0	2	7	0	14	6	14	25	.47	28	33	26	19
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6	59	1	0	0	. 4	2	16	6	11	23	44	25	33	25	18
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8	62	1	0	1	4	2	16	6	10	26	37	28	3.0	25	19
9	64	1	0	1	4	11	11	5	13	26 28 29 28 30	39	31	39	22	17
10	65	2	0	1	1	5	11	7	12	28	37	3.4	38	22	15
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12	63	1	0	2	1	4	9	6	12	28	34	34	40	20	15
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19	61	0	0	2	2	1	12 12 10 10	2	12	37	28	37	33	18	13
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23	60	ň		0	5	4	q	5	15	41	7.8	30	3.3	17	15
24	61	0	0	- 7	5	5	9	5	17	3.0	30	39	32	19	14
24	61	- 0	0	0	1	5	9	5	17	41	32	41	35	19	15
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2	29	2	0	6	4	3	11	6	28	32	33	36	35	16	14
3	33	- 2	- 6		5	- 0	8	7	26	31	33	37	36	14	14
34	17	3	ŏ	00	5	3	6	Ó	25	32	32	39	36	14	14
35	22 17 15	2	0	Č	5	2	9	0	27	32	31	41	35	14	15
36	12	2	1	0	5	1	10	12	26 25 27 28	20	29	30	34	15	15
7	12	5	1	-0-	3	1	13	14	28	29 29 32	20	38	35	17	17
19	9	1	1	0	3		13	15	28 30	33	28	30	35	18	17
39		5	1		2 2	2	13	14	33	34	30	37	34	18	15
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15	1	1	15	1	- 1	5	11	15	30	30	30	40	22	18	18
15	1	1	19	2		2	13	14	38	40	30		22 24 27	18	17
16	1		22	3	1	1	13			40	29	41	27	18	
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19]	0	22 23 22 15 16	ш		10	9	15	35	45	31	46	25 27 25	21	15
50	1	0	16	3		10	8	13	31	44	29	46	25	20	15

TABLE A-33 EVENT 87 PAGE A-35

E A-33 NT 87 A-35

	NUMBER	OF SEN:	SURS	WIIH	STUNE	h 1.55	STHA	NINGI	DE AI	OT A	THI K	AND PINE	A TMI	12.8		
		1	51	101	151	201	251	3.0.1	351	401	451	501	551	601	651	701
ü	1	29	30	4	23	11	21	17	33	3.5	27	31	36	29	32	23
-	2	29	27	14	23	12	21	15	33	35	28	31	36	20	32	21
	3	29 29	28	4	21		19	18	34	35	29	32	38			23 21 23
	4	30	3.0	3	21 20 22	11	20	19	34	35	29	31	3.9	31	33	26
	5	30	25	3	22	13	20	18	35	36		31	39	29	34	27
	5	30	25 22 20 20 19	1	22	12 12 12 12	20 20 23 23 21	19	35	37	32	26	39	30	33	26 27 26 26 26
	8	31	30		53	15	53	ŽČ	37	36	33	54	36	29	28	37
	q	30	10	100	22	15	53	25	36	35	33	27	35	29	27	29
	10	29	10	5	21	11	21	20	36	36	30	31	35	29	28	27 29 29 32 30
	11	29	18	14	18	11	24 26	29	32	36	30	30	33	29	28 27	32
	12 13	29	19	3	21	11	26	32	31	35	31	30	33		27	30
	13	27	20	3	2.2	11	31	34	30	33	32	29	33	29	26	30
	14	27	19	3	22	11	31	32	31	30	31	30	35	29	25	28
	16	27	18	4	19	11		33	31	32	35	28	35	30	25	20
	17	27 28	18	ü	22	11	31	29	32	33	32	31	35	30	57	28 28 29 26
-	18	29	18	5	18	0	20	26	33	32	31	3.3	33	31	27 28 29 30	29 29 29 20 30
	19	29 28	18	5	20	9	28	26	32	32	33	32	33	31	29	29
	20	29 29	18	7	19		31	23	33	33	32	30	35	33	3.0	29
	21	29	17	8	19	8	33	2.3	32	32	31	29	32	33	29	3.0
	22	30	17	8 7	19	11	30	22	29	33	31	30	32 32	30	29 32 30	31
	24	29	14	7	19	16	28 26	54	58	30	35	27	32	31	36	30
	25	31	14	7	22	16	26	23	27	30	34	27	29	30	31	32
	26		16	6	23	19	26	22	28	31	36	25	57	31		26
	27 28	32	19	7	23 22 22	21	26	21	29	29	35	26	27 26	31	30	26 27
	28	33	20	9	22		24	23	32	30	35	25	28	33	30	27
	29	34	25	11	24	27	24	24	29	32	34	25	29	33	.28	27
	30 31	32	28 31	14	23	27	23	26	33	31	35	26	29	33	28	26 26
	31	27	32	19	55	21	55	26	33	38	32		28	32		20
	32	27	34	21	55	10	26	54	34	30	34	32	29	37	29	23 21 18
	34	28 28	33	22	23	17	20	25	33	31	35	35	28	77	32	18
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	36	26 27	36	26	26	16		22	30	30	32	34	26	35	31	19
	37	27	37	28	29	14	28	20	29	30		34	25	3.3	31	17
	38	23	38	27 32 35	31	14	28	21	33	30	34	33	27	33	30	17
	40	30	35	35	30	13	27 26	24	31	30	37	37	20	37	31	17
	41	30	27	35	38	13	30	27	29	28	34	36	28 28	30	31	19
	42	77	50	34	36	13	29	- 55	20	23	3.1	17	27	3.0	30	10
	43	32	14	35	3.2	14	28	25	29	25	31	34	26	3.8	30	22
	44	32	11	34	26	17	30	23	29	27	31	35	25	35	31	23
	45	35	9	33		16	30	2.3	32	25	32	36	24	33	30	22 23 26 28 29
	46	35	8 5	32	20	18 19	27	24	34	26	31	36	27	32	29	28
	48	34	2	27 28 28	17	22	25	24	37	25	32	38	27	33	24	29
	49	33	3	28	15	54	25	59	30	26 27 28	31	37	59	31	24	30
	50	31	3	26	13	21	20	32	30	58	30	37	30	32	23	31
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TABLE A-34 EVENT 89 PAGE A-36

GIVE	N FRE	OUENC	A IND	EX									
401	451	501	551	601	651	701	751	801	851	901	951	1001	
35	27	31	36	29	32 32 33	23	31 228 27 222 222 222 222 222 222 222 222	3.3	2.8	27	24	28	
35	27 28 29 29 29	31	36	29	32	21	20	31	28 29	27	25	27	
35	29	32	3.8	29	33	23	20	3.1	30	20	27	26	
35	29	31	39	31	34	26	57	35	28	29	28	26	
37	- 22	36	30	30	33	26	26	28	29	31	27	26	
36	32	27	36	29	31	26	25	29	29	29	28 27	26	
36	32 32 33 33	26 27 27 29	36 35	27	28	27	25	30	31	26	27	22	
35	33	31	35	29	27 27 27 27 26	26 26 27 29 29 32 30	26	29	3	29 26 23 23 24 24	55	26 22 21 22 23 24	
36	30	30	33	50	57	32	25	23	31	23	27 23 23 22	23	
35	31	30	33	29 30	27	30	27	29	. 30	24	23	24	
33	32	29	33	29	26	30	28	23	3.0		22	24	
30	31	30	35	29	25 24 25 27 28 29 29	28 29 29 26	20	27	32	26	24 26 25 26	24	
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33	32	31	35	30	57	26	28	27	30	23	26	23	
37	31	33	33	30	28	29 29	30	27	29	22	27	25	
32	33	32	33	31	29	29	3.1	28 27 27 25 24	3.0	2.2	26	26	
3.3	32	30	35	33	30	29	33	24	31	23	27 26 26 27	24 23 23 25 26 26 28	
32	31	29	32	33	29	21	33	23	33	- 52	20	28	
30	31 33 35	29	32 32 32 29	31	29 32 30	31 30 32 29	33 32 31 31	23 22 22 20	34	20	28 26 27 23	28 29 30	
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30	34	27	29	30	31	29	31	20	3.1	20	23	3.0	
31	36	25	27 26	31	30 30	26 27 27	37	21 23 24	33	20 19	33		
29	35	26	20	31	30	57	28	51	35	13	55		
32	34	25 25	28	23	28	27	31 28 28 27	24	33	20	23 22 22 26		
31	35	26 31	29	33	28 28	26	27 28 26 28 28 28	25	33	21	20		
31	33	3.1	28	3.4	28	26	28	29	31	2.3	27		
28 30	32	32 32 35	29	32 37	29 30	23 21 18	20	28	31	24	27		
- 31	35	35	28	34	35	18	28	3.1	38	53	50		
31	34	33	28 27	38	32	19	28	30	28	23 23 24	27 29 28		
30	32 33	34	26 25	35	31	19	27 29	30 30 30	26 24	22	29		
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30	34	33	27	33	30	17	30	30	25 26 28	22	27 28		
31	37	37	28	37	31	19	28	30	28	25	57		
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23	31	37	28 28 27 26	3.0	30	19	30	37	27	25	28 28 31		
25	31	34	26	38	30	22 23 26 28 29	31	28	27	24	28		
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25	31	36	57		29	28	30	31	31	24	25		
26 25	32	38	27 27	32	24	29	31	30	31	29	28		
26	33	36	28	34	24	30	34	3.1	30	28	28		
26 27 28	31	37	28 29 30	31	24	31	33	30	30	28	29		
28	30	37	30	32	23	3.1	32	29	20	26	31		

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1	50		0	1	4	/1	7	16	35	3.8	52	37	22	30	
	50			7	5	4	7	18	33	3.6	50	37	35	33	
3	50		0	1	5	5	4	19	33	40	52	30		31	
4	50		0	1	4	5	6	20	32	39	55	43	35	31	•
5	50	0	ă.	2	5	5	6	50	34	41	55	43	29	34	
6	67		0	- 5	5	7	5	22	77	40	54	u i	29	30	
7	60		0	3	4	5	7	21	32	42	51	45	21	28	
8	6.5)	Ď.	3	5	Ĭ.	g	24	33	43	51	44	31	27	
9	60	0	n	1	5	14	8	30	32	42	53	44	33	27	
10	60		0	1	5	1	q	37	311	41	ца	43	22	28	
11	60	0	0	1	5	3	12	33	3.4	40	46	42	34	29	
12	50		0	1	5	4	11	32	3.8	3.8	46	40	23	29	
13	60	0	0	0	5	3	11	31	36	36	47	41	33	30	
14	50		0	1	5	3	11	31	34	30	46	44	31	30	
15	58			1	5	3	10	30	36	32	47	45	29	30	
16	58			1	3	3	11	28	33	27	49	44	23	34	
17	56		0	2	3	3	12	30	34	27	46	43	28	33	
18	54		0	3	3	3	11	28	38	27	45	40	28 28	31	
19	53			4	3	2	10	30	3.7	26	46	3.9	28	32.	
20	51		0	4	2	2	10	30	37	24	46	38	27	33	
21	4.8			14	1	3	8	30	38	25	4.8	37	27	32	
22	42			5	1	3	8	32	37	27	47	40	30	30	
2.3	3.8			5	1	5	10	3.3	36	28	48	41	33	29	
24	32		0	5	1	4	9	33	34	30	49	42	30	31	
25	29			5	1	3	11	32	33	31	49	39	28	28	
26	30			5	2	2	12	33	32	35	46	33	30	26	
27	24		0	4	2	2	11	34	33	36	50	38	32 32 32	25 26	
28	18			LL.	0		10	3.9	31	36	52	40	3.2	26	
30	12	2	0	4	0	2	8	41	32	40	54	41	32	27	
31					Ų.	3	6	40	32	41	54	41	31	25 22 21	
	7		0	5	1	3	6	39	36	44	55	40	32	22	
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34	- 1			5		2	6	42	33	45	53	40	27	22	
35	2		1	3	1	6	11	40	35	44	51	30	26	18	
36			0	3		5		36	34			39	29	19	
37	2		0	3	1	5	12	36	36	49	54	40	30	18	
18			0	3		- 5	10	36	35	46	53	42	32	16	
39	5		1	3		2	13	36	33	47	51	39	30	14	
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41	2		1	3	- 1	4	16	41	35	51	53	38	58	14	
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43	É	2	5	2	ň	3	17	44	36	55	52	35	59	19	
44		5	5	2	1	14	14	45	37	57	49	35	28		
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46	0	,	1	2	7	TI.	14	41	36	57	41	34	32		
47	0		1	1	3	5	15	45	38	57	39		33	22	
48			1		- G	6	15	37	35	54	40	32 32	32	56	
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IVE	N FRE	QUENC	Y IND	EX .									
01	451	501	551	601	651	701	751	801	851	901	951	1001	
35	38	52	37	33	3.0	27	17	15	19	14	13	8	
32 33 34	33	50	38	35	33	27	18	17 19 18	21	14	12 13	10	
33	40	52	30	35	31	27	18	10	22	13	13	10	
34	41	55	43	33	311	59	20	19	22	14	12	10	
33	40	54	42	- 59	30	27 28 27 29 29	20 20 19	17	17	16	10	13	
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33	43	51	44	31	27 30	30	18	14	16	16	12 12	15	
32	42	53	44	3.3	30	29 31	18	13	12 12 14	16	13	13	
34	41	46	42 42 40	33	29	29	21	12	1/1	14	11	12 13 12 14	
38	38	46	42	34	29	28	21 21 20	17	16	15	11	13	
36	36	47	41	33	29	28 27	20	18	17	13	12	14	
34	30	46	44	37	30	26 24 25	17	16	17	12	11	13	
36.	32	47	45	29		24	14	17	17	11	12	16	
33	32 27 27	49	44	29	34	25	17	18	18	12	14	16	
34	21	46	43	28 28 28	33	25 24 24	17	17	18	14	15	16	
38	56	46	39	28	32	54	15	16	17	16	14	20	
37	27 26 24	46	38	27	33	23	16	76.	16	16	13	20	
38	25	48	37	27 27	32	23	15	14	18	16	12	17 20 20 21	
37	25 27 28 30 31	47	40	30	30	20	16	14	19	15	11	22 21 22 22 22	
36	28	48	41	33	29 31	18	18	15	19	12	12	21	
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32	31	46	33	50	26	15	20	15	20	13	15	22	
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31	36	50	38	32 32 32	26	17	17	16 15	19	10	14		
32	40	54	41	32	27	18	17	17	20	10	13		
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36	44	55	40	32	22	16	20	10	24	11	10		
33	45	53	40 40 40	27	22	14	20 20 20 20 20	17	20	14	12		
35	44	51	30	27 26	18	13	20	19	25	15	17		
34	49	53	39	29	19	12	20	19	23	14	13		
36	49	54	40	30	18	1 (4	18	20	24	13	12		
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34	47	54	40 39	30	14	18	17	27	20	14	14		
33	52	50	38	29	14	16	17	20	19	14	10		
34	51	52	3.8	58	14	17	17	19	21	13	16		
31	53	5.0	37 35	27	15	16 16	12	1 R	18	15	14 16 17		
36	55	52	35	29	19	16	18	17	16		15		
37	57	49	35	28	19	15	18	19	16	15	18		
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35	57	39	3.3	37	55	14	20	20 20 20	18	17	14		
35	54	40	32 32 34	32	56	16	17	50	16	16	13		
30	51	38		34	22 23 26 27	18	17	19	15	16	13		
40	52	40	3.0	3.11	28	18	19	18	16	13	12		

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